

# Efficient Solvers Based on Manycore computers and adaptive techniques for Cardiac Modeling

FISIOCOMP - Laboratory of Computational Physiology

Graduate Program in Computational Modeling Universidade Federal de Juiz de Fora (UFJF) Juiz de Fora - MG - Brazil

Prof. Dr. Rodrigo Weber dos Santos



# Efficient Solvers Based on Manycore computers and adaptive techniques for Cardiac Modeling

#### Part I

Who, When, Where and Motivation



#### PTB-Berlin (2002-2004) Group (2005 - )

Prof. Rodrigo Weber dos Santos, Dr. Math.

Prof. Marcelo Lobosco, Dr. Comp. Sci.

Prof. Ciro Barros Barbosa, Dr. Comp. Sci.

Prof. Luis Paulo Barra, Dr. Eng.

Prof. Elson Toledo, Dr. Eng.

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Ricardo Campos (Cardiac Modeling)

Bernardo Rocha (Cardiac Modeling)

Barbara Quintela (Models of Immune System)

Alexandre Pigozzo (Models of Immune System)

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**Daniel Mendes Caldas** 

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Bernardo Lino Oliveira (PhD in Simula Lab)

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Fernando Otaviano Campos (PhD in Graz)

**Daves Martins** 

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Programa de Pós-Graduação em

#### Modelagem Computacional

Mestrado / Doutorado (Conceito 4 CAPES)

Buscar

SIGA

Biblioteca

Calendário

English Version

|                         | Imprimir   🗷 Fonte:   |
|-------------------------|---|
| Página Inicial          | Corpo Docente   |
| Curso                   | Co.po Doconto   |
| Disciplinas             | O Corpo Docente que atua no Programa de Mestrado em Modelagem Computacional é composto pelos  |
| Grade Curricular        | seguintes Professores:  |
| Normas e Regulamentos   | Permanentes:  |
| Corpo Docente           | Afonso Celso de Castro Lemonge, Departamento de Mecânica Aplicada e Computacional 🕰 Lattes    |
| Corpo Discente          | Carlos Cristiano Hasenclever Borges, Departamento de Ciência da Computação 🕰 Lattes           |
| Produção Científica     | Elson Magalhães Toledo, Departamento de Mecânica Aplicada e Computacional 🕰 Laltes            |
| Dissertações Defendidas | Flávio de Souza Barbosa, Departamento de Mecânica Aplicada e Computacional 🕰 Lattes 🍪 www     |
| Processo Seletivo       | <u>Hélio José Corrêa Barbosa,</u> Departamento de Ciência da Computação 🕰 Lattes 🏈 <u>www</u> |
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| Palestras               | Marcelo Lobosco, Departamento de Ciência da Computação 🕰 Laltes                               |
| Eventos                 | Michèle Cristina Resende Farage, Departamento de Mecânica Aplicada e Computacional 🖳 Lattes   |
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| Localização             | Ana Paula Couto da Silva, Departamento de Ciência da Computação 🙆 Lattes                      |
| Galeria de Fotos        | Ciro de Barros Barbosa, Departamento de Ciência da Computação 🖳 Laltes 🍪 www                  |
| Links                   | Raul Fonseca Neto, Departamento de Ciência da Computação 🖳 Laltes                             |
|                         |   |

Sócrates Dantas de Oliveira, Departamento de Física 🙆 Lattes

Wilhelm Passarella Freire, Departamento de Matemática 🕰 Lattes

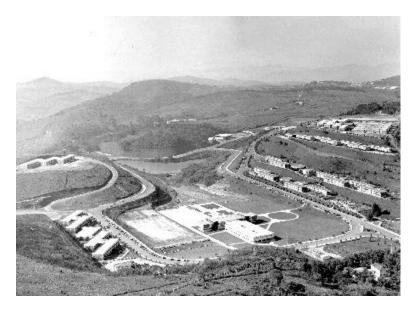


Graduate Program in Computational Modeling – 2006 Building - 2008



Graduate Program in Computational Modeling – 2009

#### UFJF Campus started to be constructed in 1969







Today it offers aver 100 of undergraduate and graduate courses

700 Professors2000 Staff20000 Students





#### Models of Cardiac Electro-Mechanics

 Cardiac disease is the #1 cause of death around the world

 Today, computational models of the heart provide a better understanding of the complex phenomenon and support the development of new drugs, therapies, biomedical equipments and clinical diagnostic methods



- Heart stops Defibrillator
- Complications during labor Demand cesarean
- Migraine Drugs



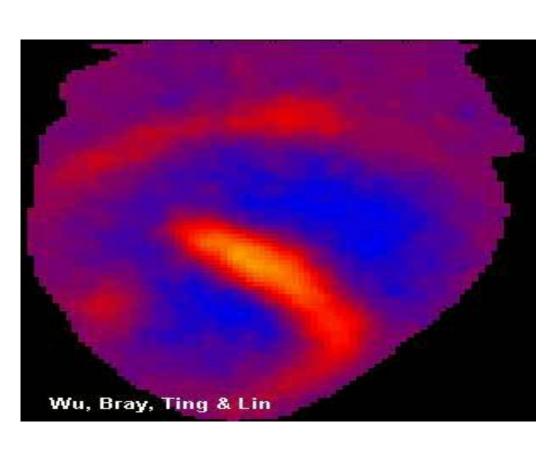
- Heart stops Defibrillator
- Complications during labor Demand cesarean
- Migraine Drugs

- Acute Conditions
- Different procedures
- Short-term



- Heart stops Defibrillator
- Complications during labor Demand cesarean
- Migraine Drugs

- Acute Conditions
- Same Phenomena
- Nonlinear Waves
- Excitable Media
- Spiral Waves





- Heart stops Defibrillator
- Complications during labor Demand cesarean
- Migraine Drugs

- Acute Conditions
- Same Phenomena
- Nonlinear Waves
- Excitable Media
- Long Term







# Efficient Solvers Based on Manycore computers and adaptive techniques for Cardiac Modeling

#### PART II

Crash introduction to the challenges of cardiac modeling?



# ratório de fisiologia computacion Vathematical and Computational Physiology

Integrative Computational Physiology:

using models to bridge the gap between genes and function or malfunction( clinical pathology)



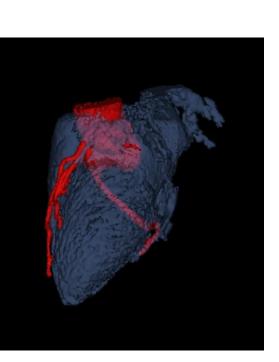
# Mathematical and Computation Mathematical and Physiology

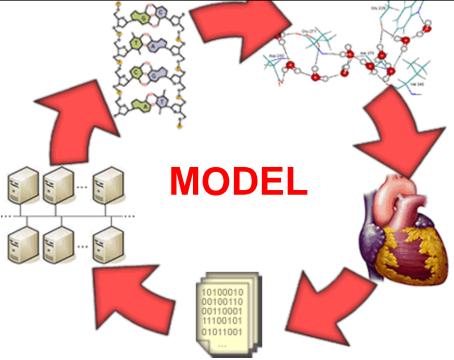
The bad news:

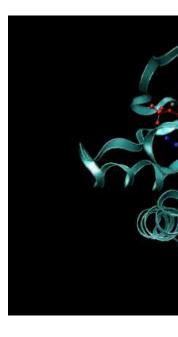
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It is a wide gap connecting multiple scales, genes, proteins, cells, tissues, organs...; multiple physics: quantum, molecular dynamics, chemistry, electro-mechanics...;
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# Models of cardiac physiology

The models represent, are based and depend on multiple and diverse data





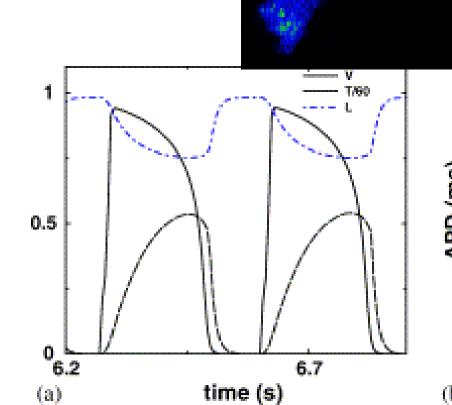




## Cardiac Cell

#### • Cellular contraction:

An electric potential difference develops across the cell membrane and triggers a chain of electrochemical reactions that results in cellular contraction (intracellular Calcium spike, ATP, etc)

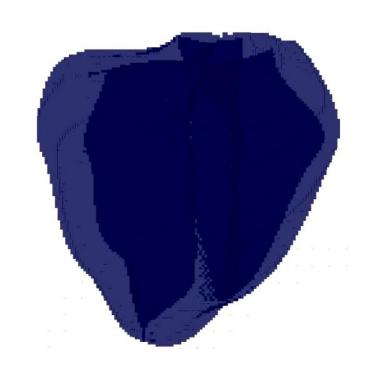




## The heart

 How do cardiac cells synchronize and contract at the same time?

The interior of the cells are connected by special proteins that allow the electric potential to propagate. A fast electric wave propagates and triggers heart contraction.

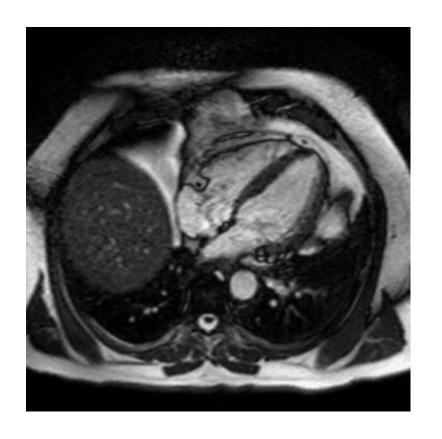




### The heart

The blood pump

Cells contract changing the organ geometry and the blood is expelled

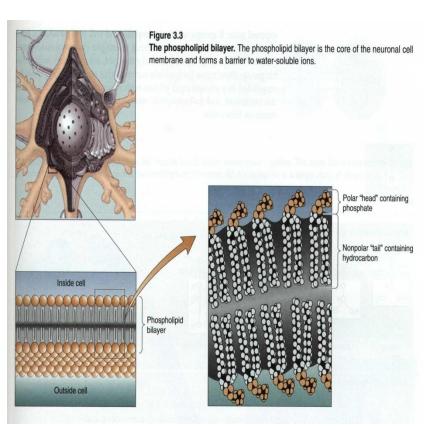




#### Models of Cardiac Electro-Mechanics

Bottom-up design

#### Sub-cellular and cellular mathematical models



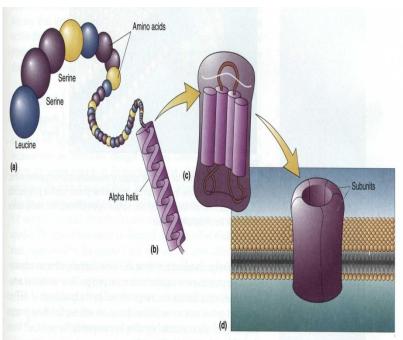


Figure 3.6

**Protein structure.** (a) Primary structure: the sequence of amino acids in the polypeptide. (b) Secondary structure: coiling of a polypeptide into an alpha helix. (c) Tertiary structure: three-dimensional folding of a polypeptide. (d) Quaternary structure: different polypeptides bonded together to form a larger protein.

### Cell model

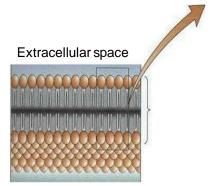
• Bi-lipid layer:

$$C_m = \frac{q}{\phi}$$

$$C_m \phi = q$$

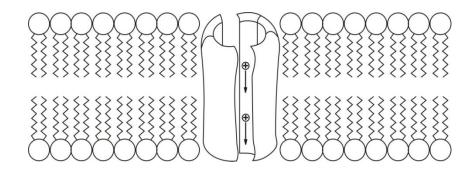
$$C_m \frac{d\phi}{dt} = \frac{dq}{dt} = I_c$$

Ionic channels: Special arrangement of proteins cut thru the membrane and allow the flow of specific ions, such as Sodium, Potassium and Calcium. Ionic currents I<sub>ion</sub>



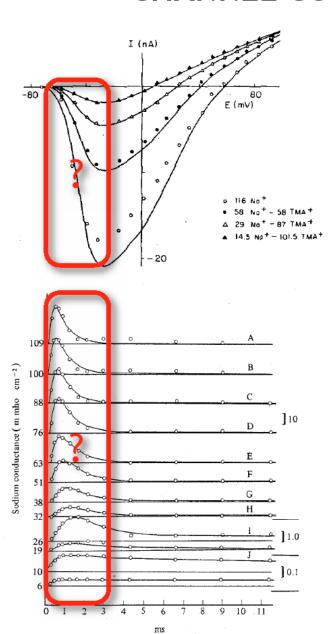


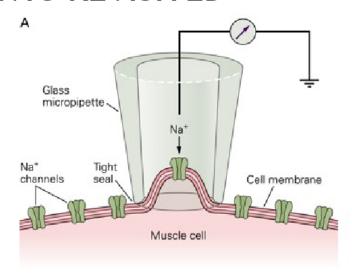


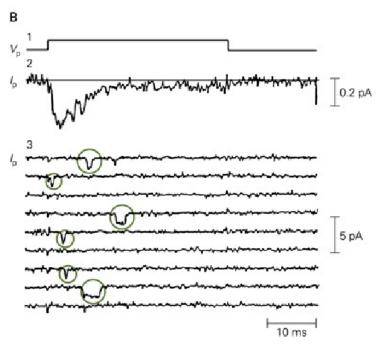


Ionic channel

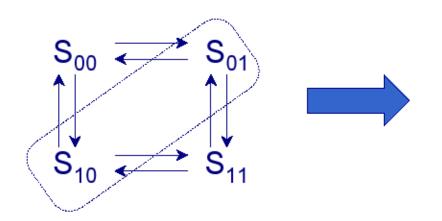
#### **CHANNEL CURRENTS REVISITED**







# K<sup>+</sup> channel gating

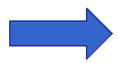


$$S_0 \xrightarrow{\frac{2\alpha}{\beta}} S_1 \xrightarrow{\frac{\alpha}{2\beta}} S_2$$

$$\frac{dx_0}{dt} = \beta x_1 - 2\alpha x_0$$

$$\frac{dx_2}{dt} = \alpha x_1 - 2\beta x_2$$

$$x_0 + x_1 + x_2 = 1$$



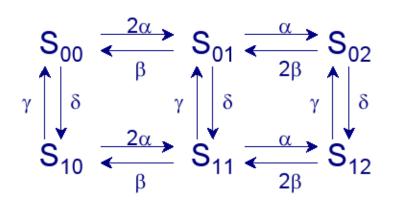
$$x_0 = (1 - n)^2$$

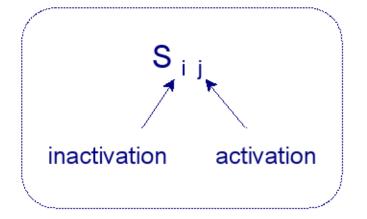
$$x_1 = 2n(1 - n)$$

$$x_2 = n^2$$

$$\frac{dn}{dt} = \alpha(1 - n) - \beta n$$

## Na<sup>+</sup> channel gating







$$x_{21} = m^2 h$$

$$dm$$

$$\frac{\alpha m}{dt} = \alpha(1-m) - \beta m$$

$$\frac{dm}{dt} = \alpha(1-m) - \beta m$$

$$\frac{dh}{dt} = \gamma(1-h) - \delta h$$

activation

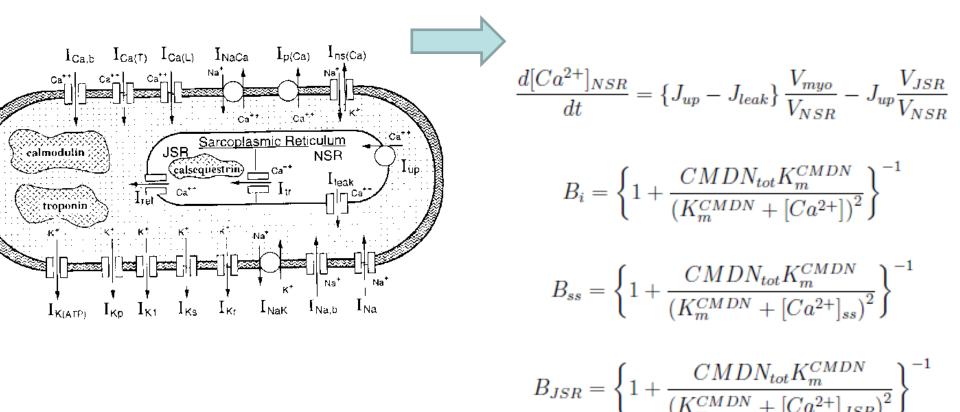
inactivation

# Models of Cardiac Electrophysiology

Bottom-up design

# Sub-cellular and cellular mathematical models

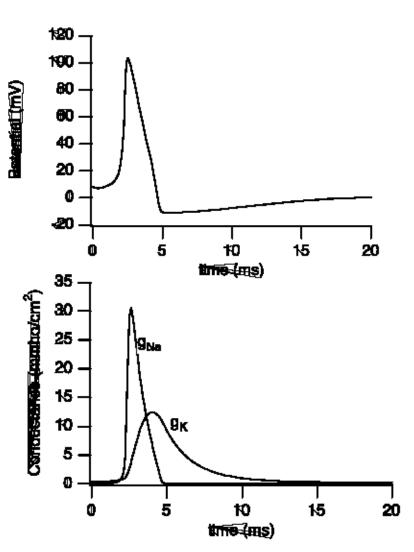
Nonlinear System of ODEs



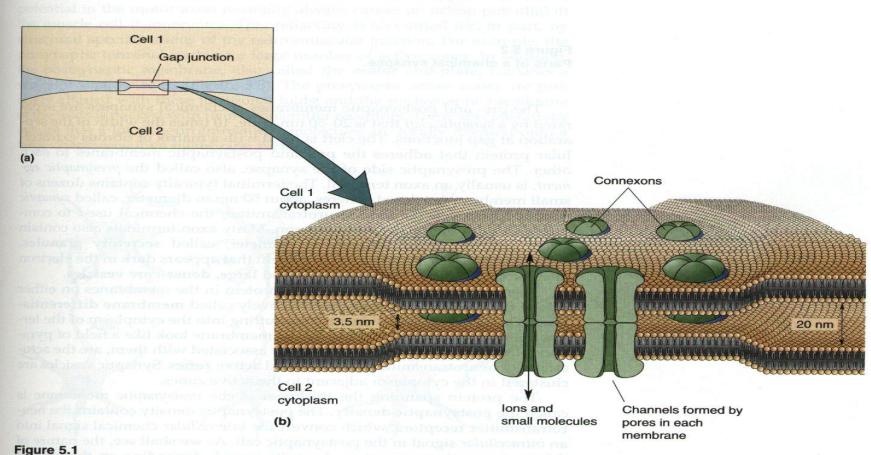
. . .

## An action potential

- $g_{\rm Na}$  increases quickly, but then inactivation kicks in and it decreases again.
- $g_{\mathbb{K}}$  increases more slowly, and only decreases once the voltage has decreased.
- The Na<sup>+</sup> current is autocatalytic. An increase in V increases m, which increases the Na<sup>+</sup> current, which increases V, etc.
- Hence, the threshold for action potential initiation is where the inward Na<sup>+</sup> current exactly balances the outward K<sup>+</sup> current.

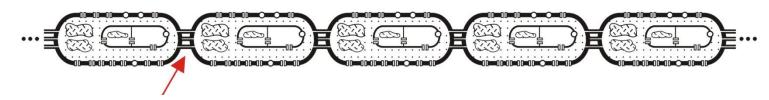


# Intra-cellular Connection Electrical Synapses

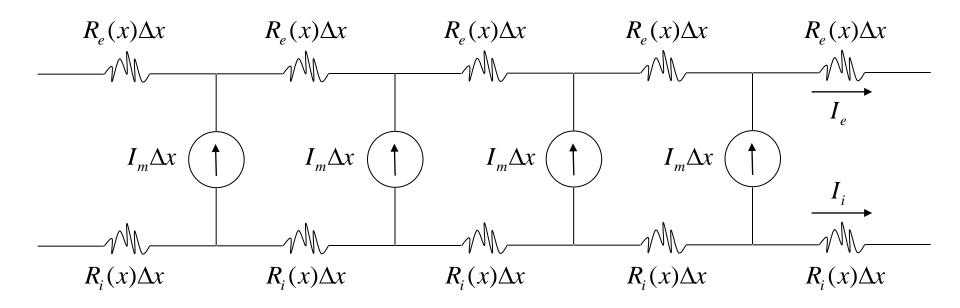


A gap junction. (a) Neurites of two cells connected by a gap junction. (b) An enlargement showing connexons, the channel proteins that bridge the cytoplasm of the two cells. Ions and small molecules can pass in both directions through these channels.

## Bidomain model



Gap junction





#### Cardiac Bidomain Model

$$\nabla \cdot (\boldsymbol{\sigma_i} \nabla \phi_i) = \chi \left( C_m \frac{\partial \phi}{\partial t} + \frac{1}{R_m} f(\phi, \vec{n}) \right),$$

$$-\nabla \cdot (\boldsymbol{\sigma_e} \nabla \phi_e) = \chi \left( C_m \frac{\partial \phi}{\partial t} + \frac{1}{R_m} f(\phi, \vec{n}) \right),$$

$$\frac{\partial \vec{n}}{\partial t} = g(\phi, \vec{n}),$$

$$\phi = \phi_i - \phi_e, \ \mathbf{x} \in \Omega \ e \ t \in [0, \ t_f].$$

- $\sigma_{i,e}$  are the conductivity tensors
- Tissue anisotropy (fibers orientation) or orthotropy (fiber-laminar).
- $\sigma_i(x,y)$  and  $\sigma_e(x,y)$ : spatial variation of fibers/sheets orientation, different extracellular and intracellular (gap junctions) conductivity values.



### Cardiac Bidomain Model

- Tissue Model for cardiac electrophysiology
- Intracellurar and extracellular spaces (domains) modeled from an electrostatic point of view
- The coupling of the two domains is via non-linear cell modeling. Total cell membrane current spreads to both intracellurar and extracellular spaces

# Action Potential Propagation Reaction-Diffusion

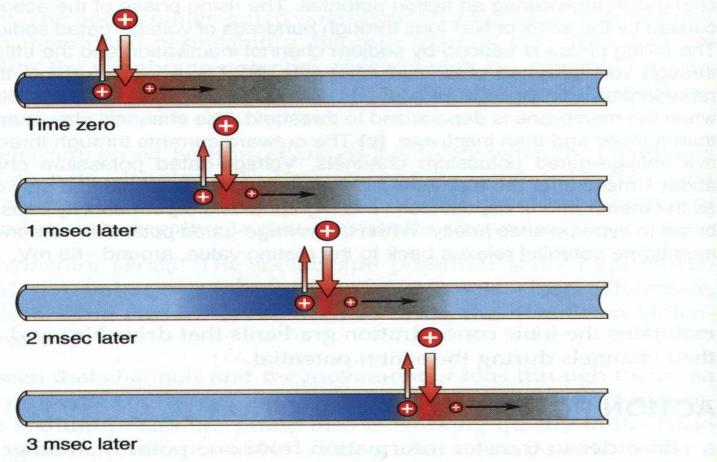


Figure 4.10

Action potential conduction. The entry of positive charge during the action potential causes the membrane just ahead to depolarize to threshold.

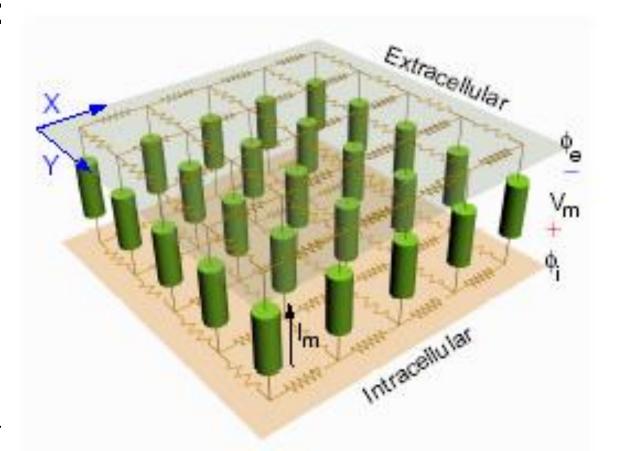


#### Models of Cardiac Electro-Mechanics

Bottom-up design

Tissue mathematical and computational

moc

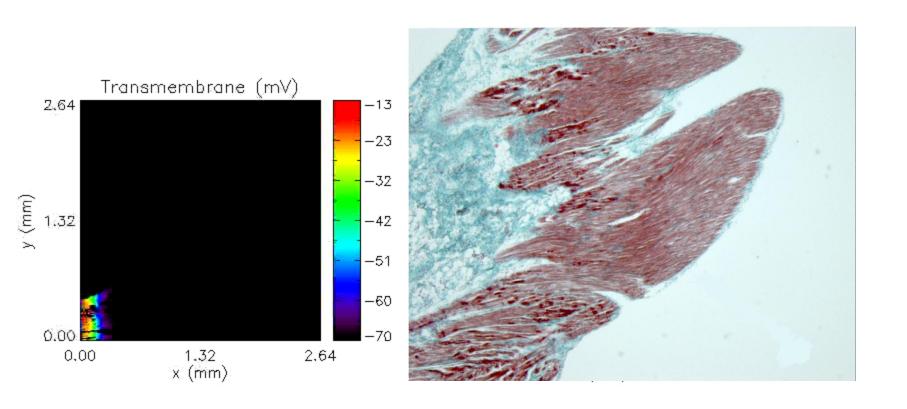




#### Models of Cardiac Electro-Mechanics

Bottom-up design

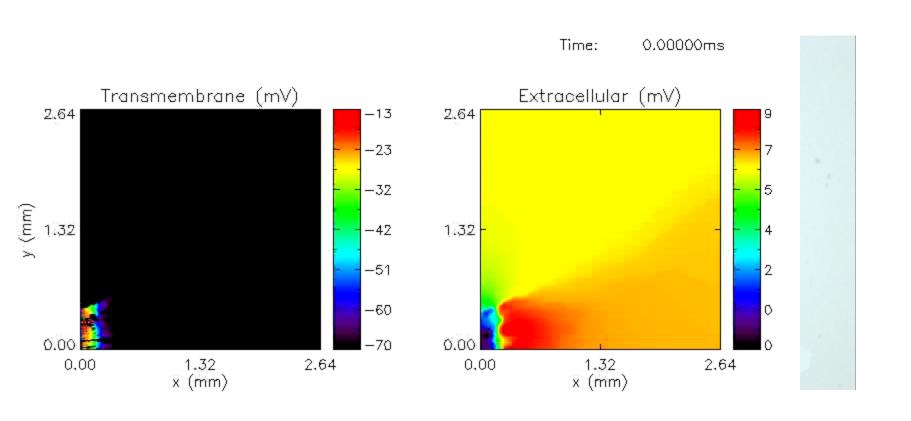
Tissue mathematical models: electric activity





Bottom-up design

Tissue mathematical models: electric activity



Bottom-up design

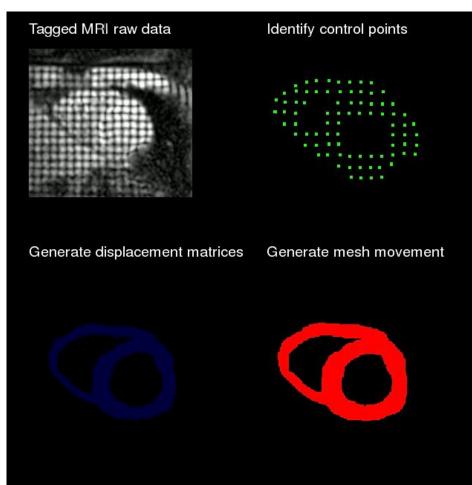
#### Tissue mathematical models: mechanical

coupling

$$\delta W = \int_{V_0} \mathbf{S} : \delta \stackrel{\bullet}{\mathbf{E}} dV_0 - \int_{V_0} \mathbf{f_0} \cdot \delta \mathbf{v} dV_0 - \int_{\partial V_0} \mathbf{t_0} \cdot \delta \mathbf{v} dA_0 = 0$$

$$S_{ij} = \frac{1}{2} \left( \frac{\partial W}{\partial E_{ij}} + \frac{\partial W}{\partial E_{ji}} \right) + S_{a}$$

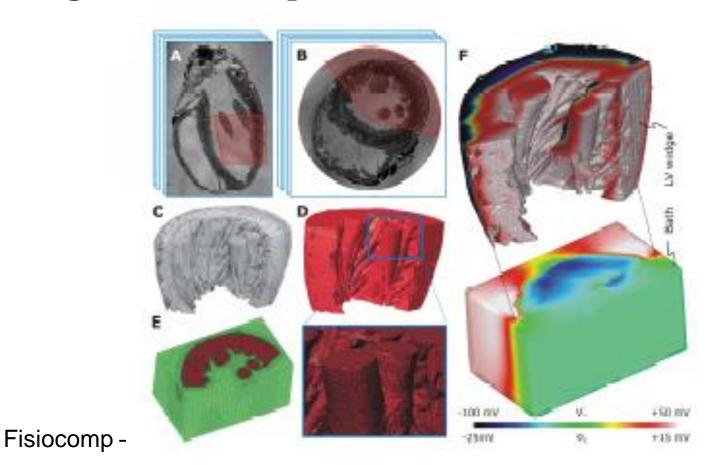
Theory of Large Deformations
Nonlinear Hyper-elastic Materials





Bottom-up design

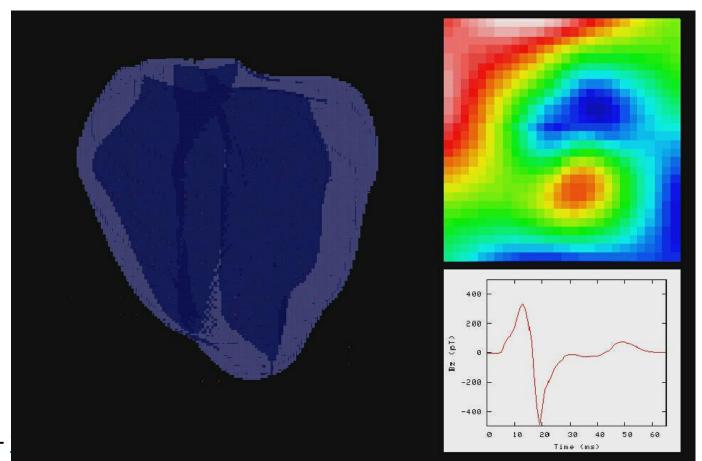
### **Organ Modeling**





Bottom-up design

### **Organ Modeling**



Fisiocomp –



## Complex Models

Modeling Challenges: Multi-scale and Multiphysics

 Computational Challenges: Simulations are computationally expensive (one heart beat = a couple of days in a parallel machine)

 Computer Challenges: Involves the coupling of several components (submodels) and data (geometry, biophysical parameters)

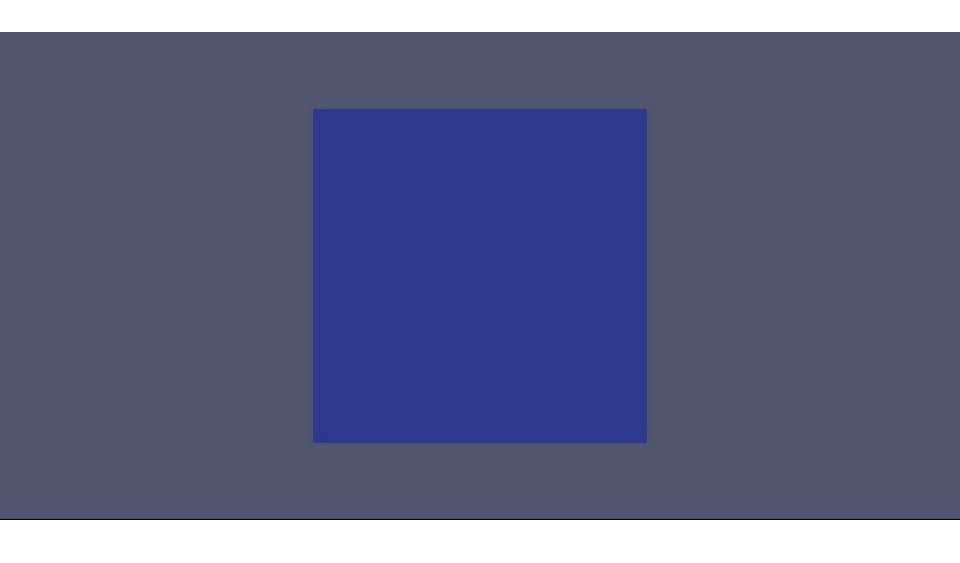


# Heterogeneous models for electrical propagation and mechanical contraction in the heart

PART III

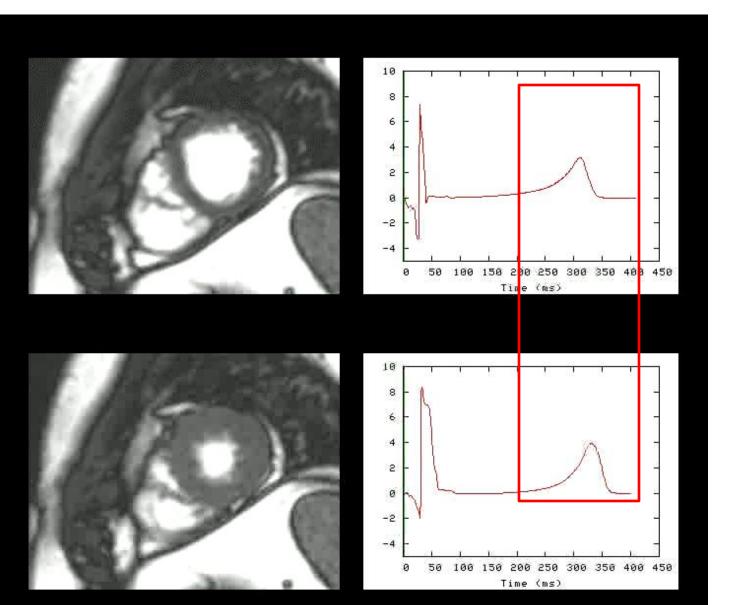
Some **2D** Applications

Velocity of the wave front = Depolarization + tissue properties Simulation of fibrosis and of low gap junctional couping



Dispersion of refractory period = Repolarization (APD) + tissue properties + Mechanical function

# ECG – T-Wave = Repolarization. Waveform?

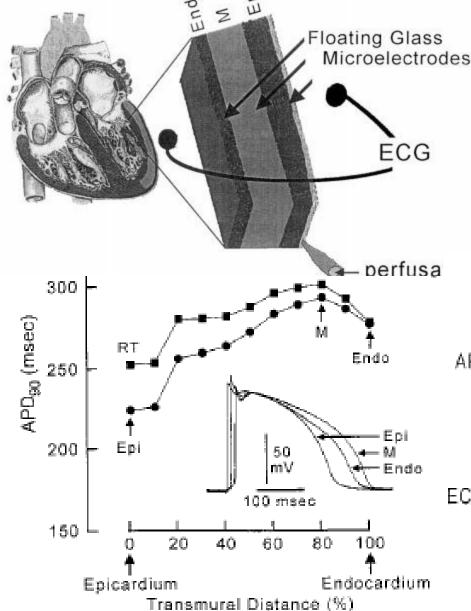


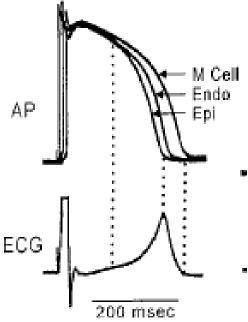


### LV Wedge

- -Transmural Gradients
- -M cells

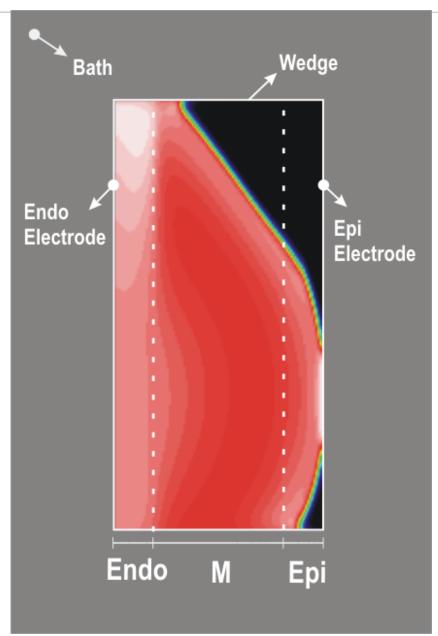
-Key ingredients to understand Repolarization (T-Wave) and Arrhythmia (Tend-Tpeak index for transmural dispersion)

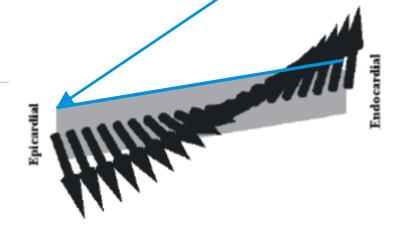




from Yan et al. Circ. 98





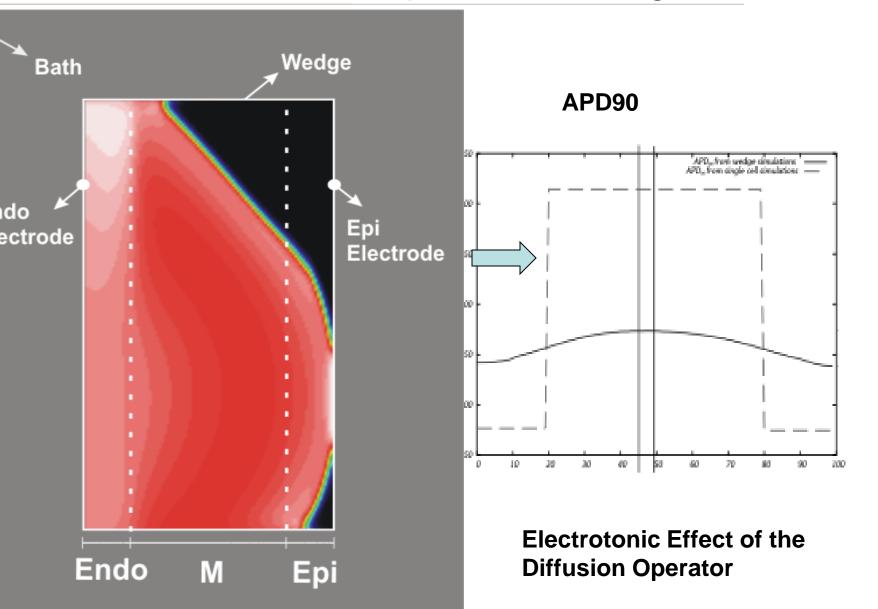


Anisotropic Tissue –
Transverse Anisotropy
Fiber Transmural Rotation

T-waves are near flat

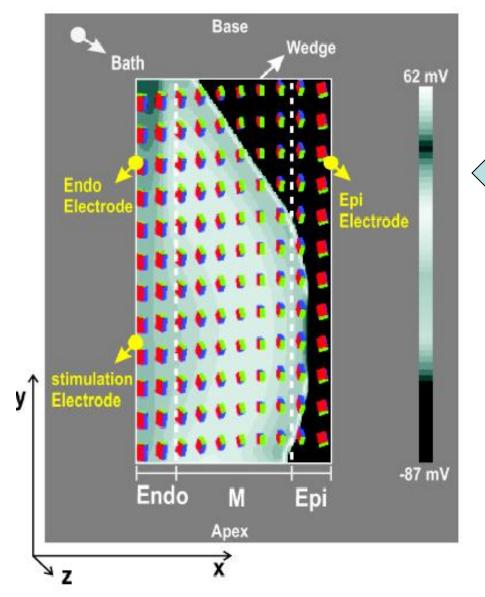


### LABORATÓRIO DE FISIOLOGIA COMPUTACIONAL COMPUTATIONAL Wedge for human LV

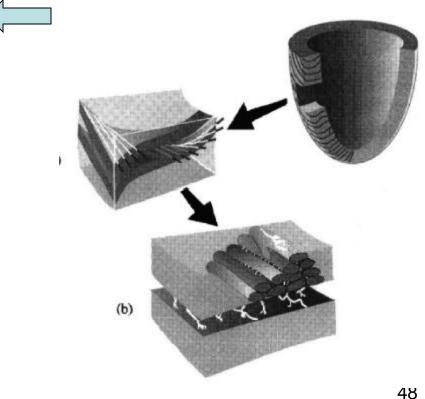




# Low Conduction of Epicardial Region Laminar-fiber structure

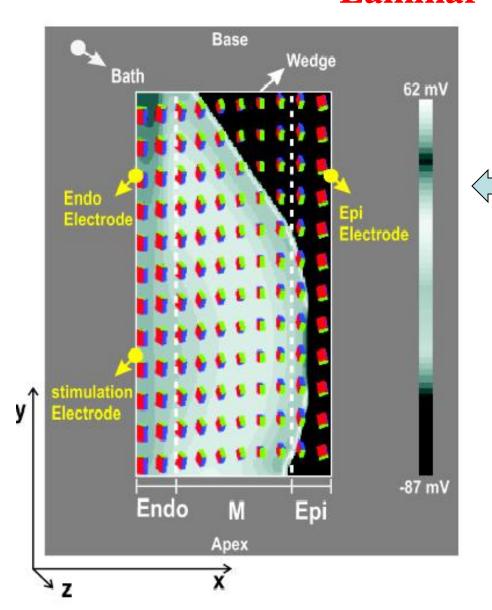


Costa et al. AmJ Physiol Heart Circ Physiol 1999;.

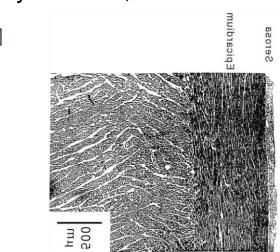




# Low Conduction of Epicardial Region Laminar-fiber structure

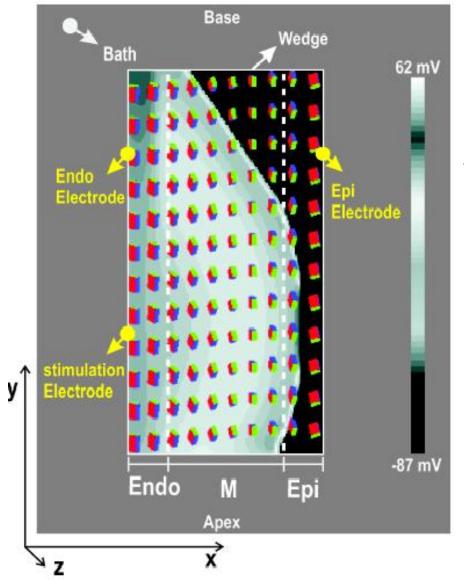


Costa et al. AmJ Physiol Heart Circ Physiol 1999;.



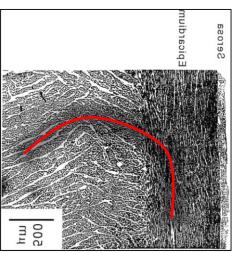


# Low Conduction of Epicardial Region Laminar-fiber structure



Costa et al. AmJ Physiol Heart Circ Physiol 1999;.

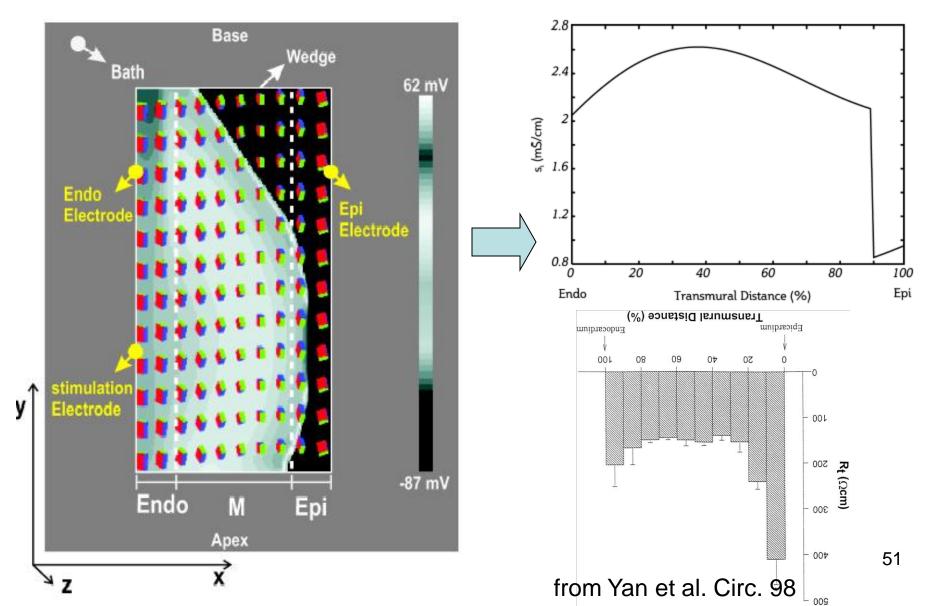






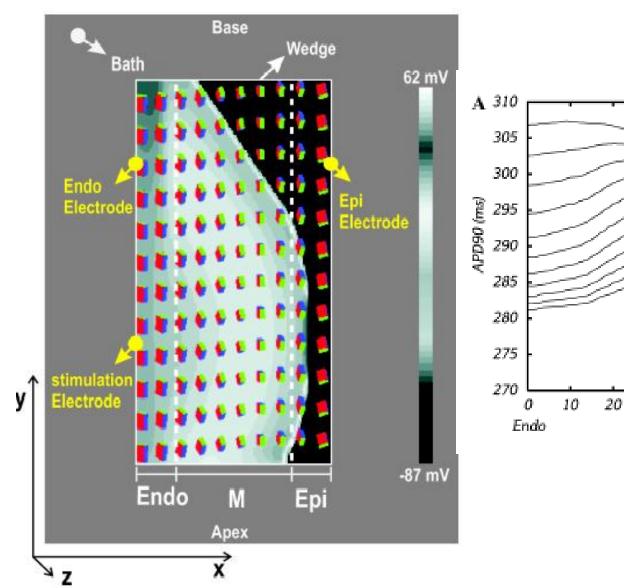
### Epicardial Region Low Conduction:

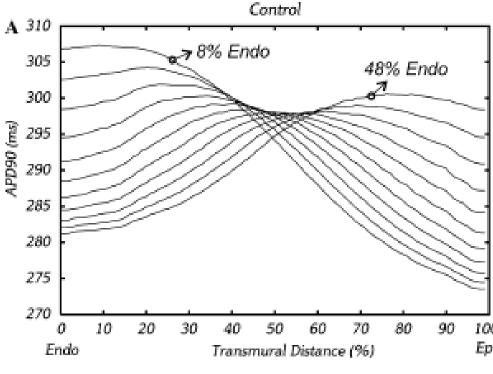
#### Laminar-fiber Architecture





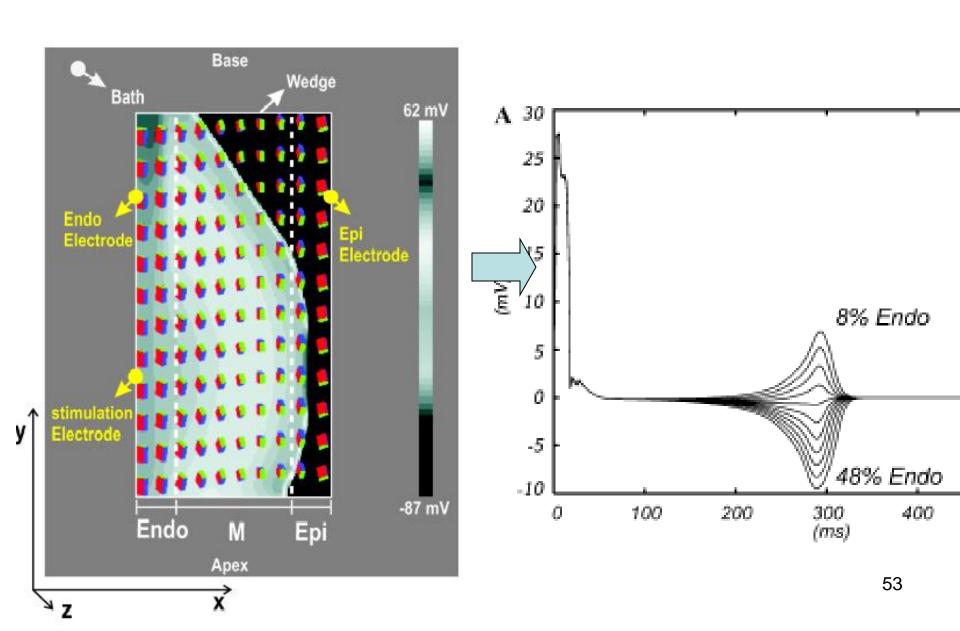
#### M-cells = 44%







#### M-cells = 44%





# A Computational Wedge model for the human LV

•T-wave format results from the Interplay of functional (APD, epi, endo M) and anatomical heterogeneities (fiber-sheet transmural rotation).

dos Santos, Rodrigo Weber; OTAVIANO CAMPOS, FERNANDO; NEUMANN CIUFFO, LEANDRO; NYGREN, Anders; GILES, Wayne; KOCH, Hans. ATX-II Effects on the Apparent Location of M Cells in a Computational Model of a Human Left Ventricular Wedge. **Journal of Cardiovascular Electrophysiology**, New York, v. 17, n. Suppl 1, p. S86-S95, **2006**.



# A Computational Wedge model for the human LV

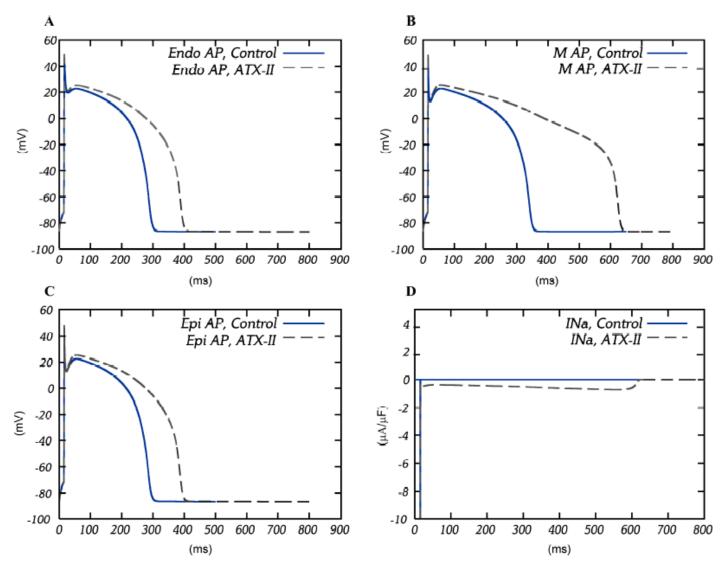
- •Administration of anemone toxin II (ATX-II) alters the dynamics of late Na+ currents, INa in ventricular cells.
- •Experiments using isolated canine ventricular wedge preparations can mimic LQT3 (Genetic disease Deathly arrhythmia).

### LABORATÓRIO DE FISIOLOGIA COMPUTACIO SIMUlation of ATX-II for the ten-Tusscher

The effects of ATX-II on INa were simulated by altering the inactivation parameter: h (fast gate) and j (slow gate).

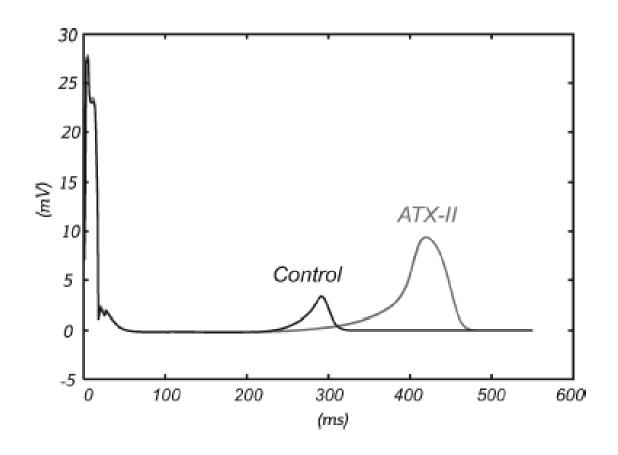
Crossing scales from protein (ion channels) to electrograms

### cell models



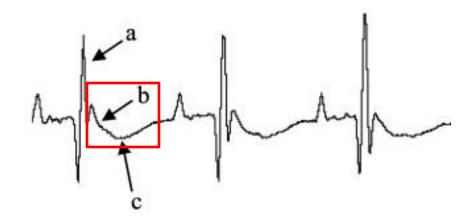


# GIA COMPUTACIONAL Transmural Electrograms from the computational wedge: Control and ATX-II



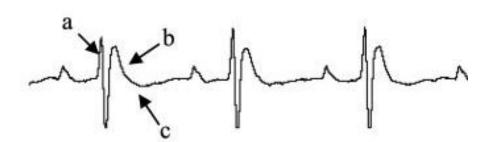


# Computational wedge model for the rat LV



Danik et al. AmJ Physiol Heart Circ Physiol 2002;

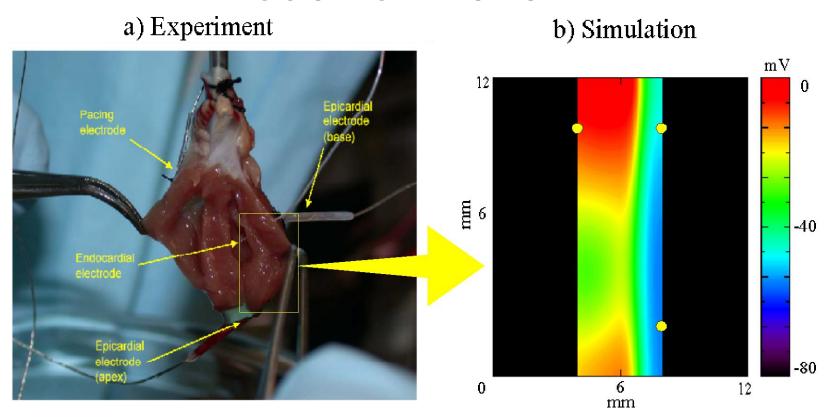
Biphasic T-wave





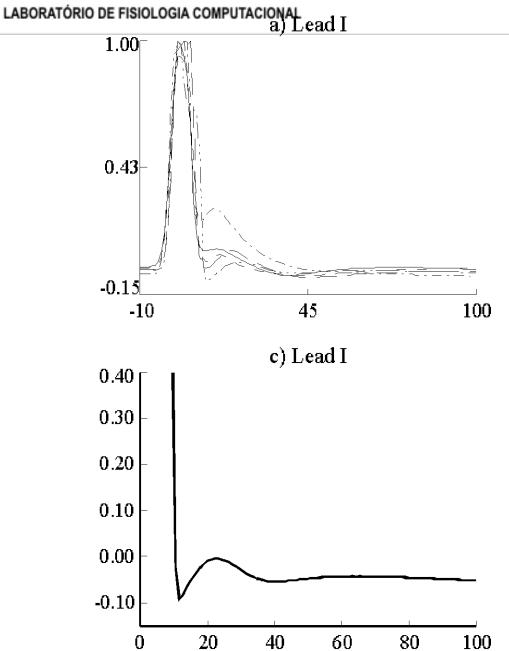
### Computational wedge

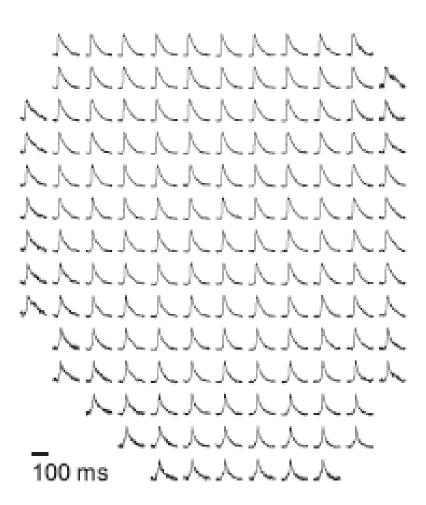
### model for the rat LV



a) Setup of the Rat experiment. b) Simulation setup. The perfusing bath is shown in black. A transmembrane potential (mV) distribution taken during the repolarization phase is presented on the tissue. The simulated electrodes are shown as yellow circles.

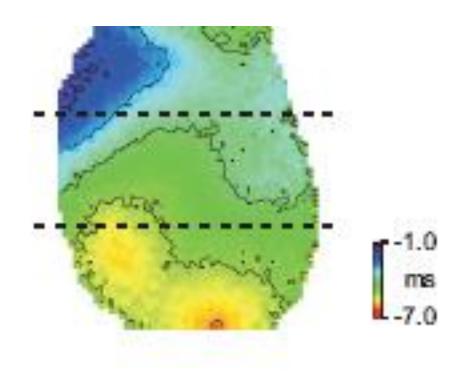




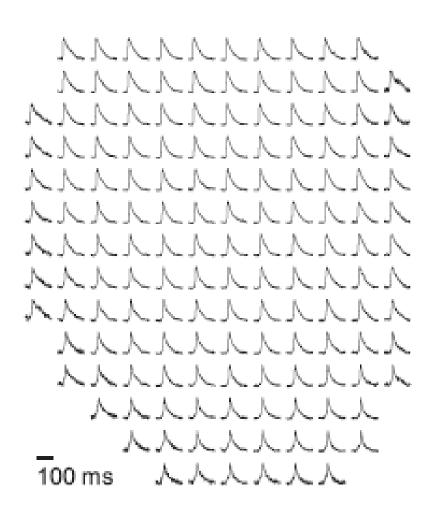


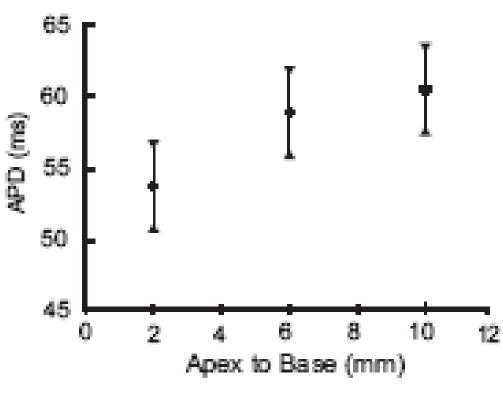
### **Optical Maps**

AAAAAAAAAススススススススススス  $\lambda\lambda\lambda\lambda\lambda\lambda\lambda\lambda\lambda\lambda\lambda$ ハハハハハハハハハハハ *スススススススススス* **スノノノノノノノノノノ スススススススス メスススススス** 100 ms 人人人人人人

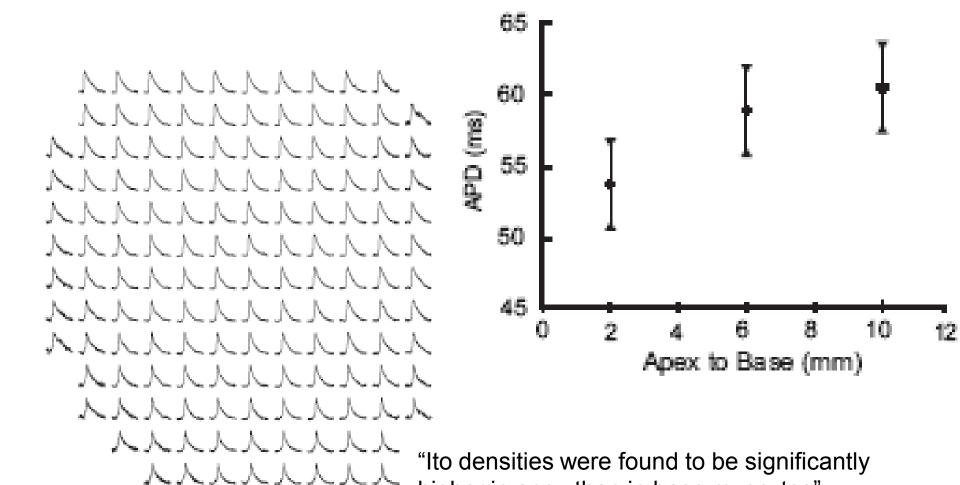


#### **APD Distribution**





#### **APD Distribution**

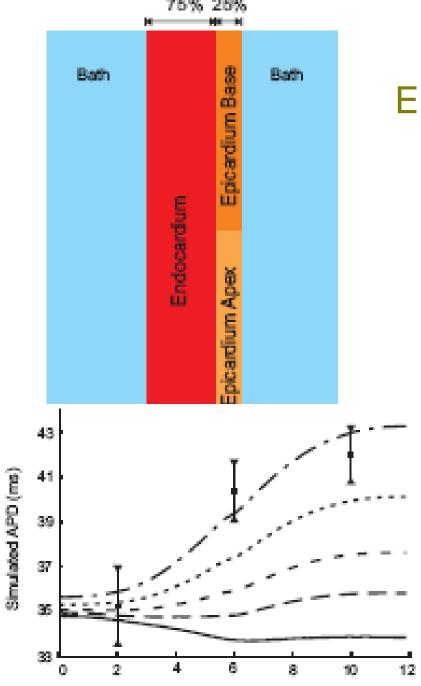


**人人人人人人** 

100 ms

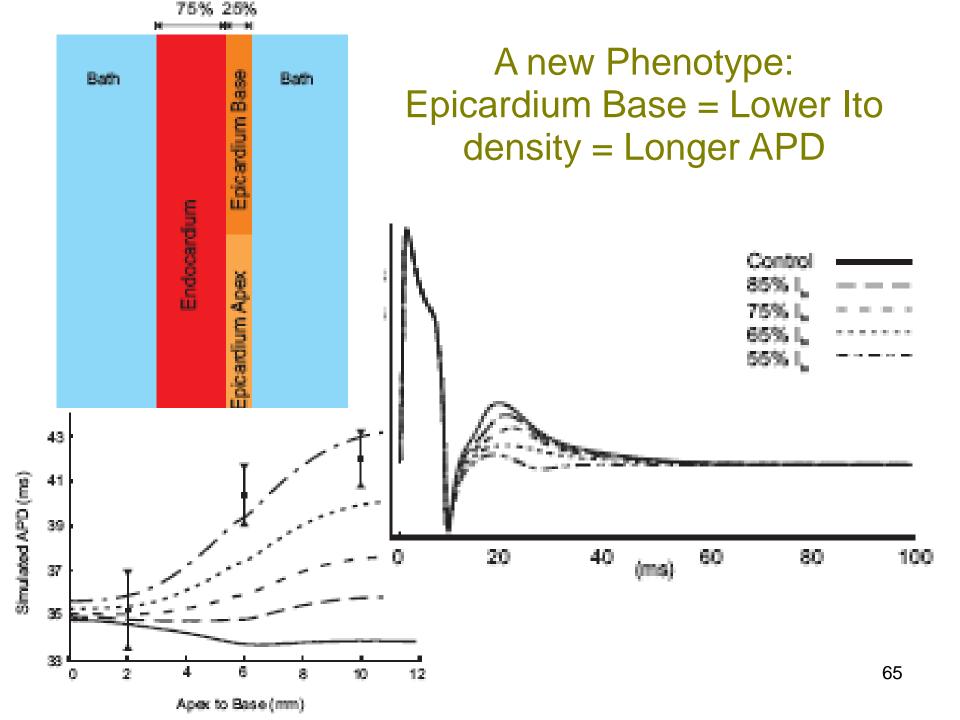
Brunet et al. J Physiol 559: 103-120, 2004.

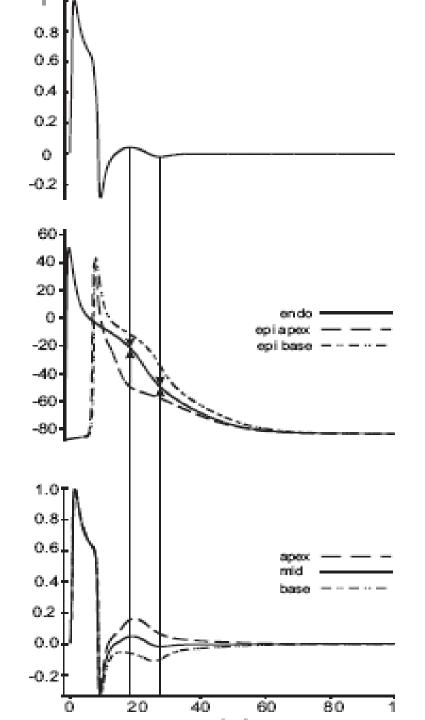
higher in apex than in base myocytes"



Apex to Base (mm)

### A new Phenotype: Epicardium Base = Lower Ito density = Longer APD

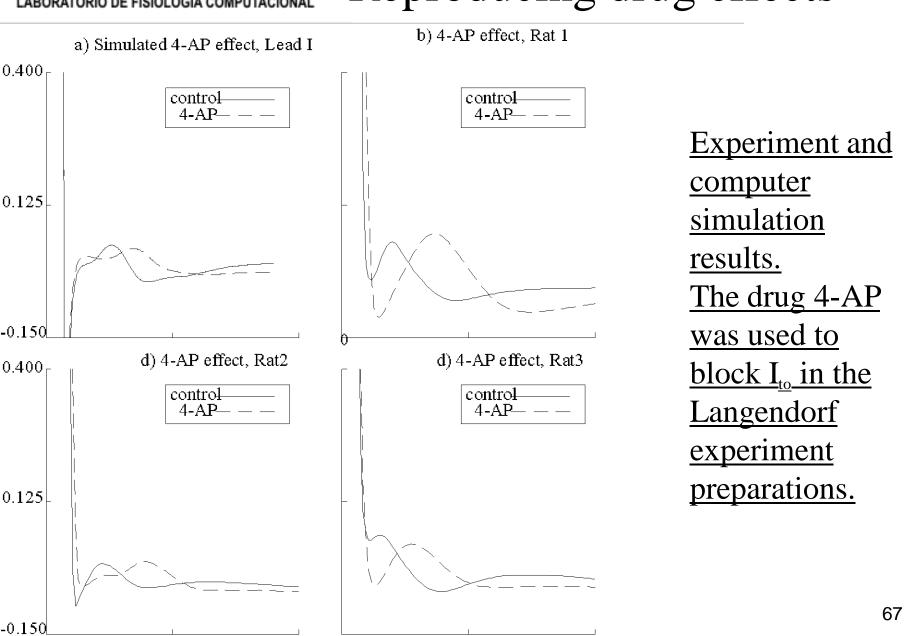




Weber dos Santos, R.; Nygren, A.; Otaviano Campos, F.; Koch, H.; Giles, W. R.. Experimental and theoretical ventricular electrograms and their relation to electrophysiological gradients in the adult rat heart. American Journal of Physiology. Heart and Circulatory Physiology, v. 297, p. H1521-H1534, 2009.

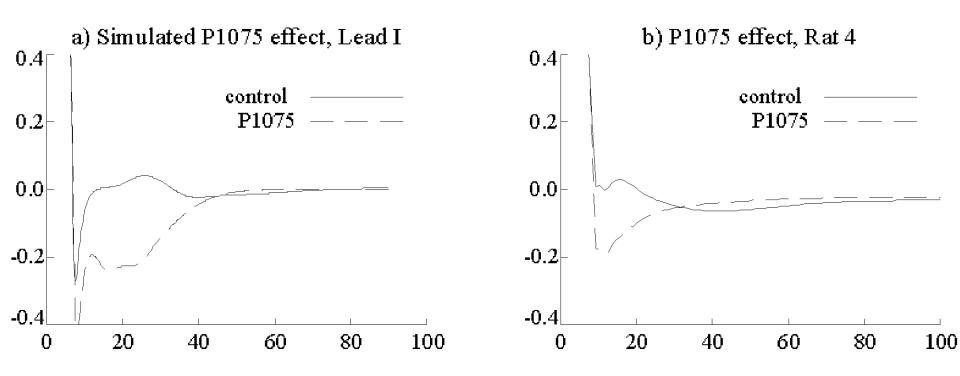


### Reproducing drug effects





### Reproducing drug effects



Experiment and computer simulation results.

The drug P1075 was used to open I\_K\_ATP in the Langendorf experiment preparations.

### Cardiac Mechanics

## Effects of Mechanical Deformation on Simulated Electrograms of a Human Left Ventricular Wedge

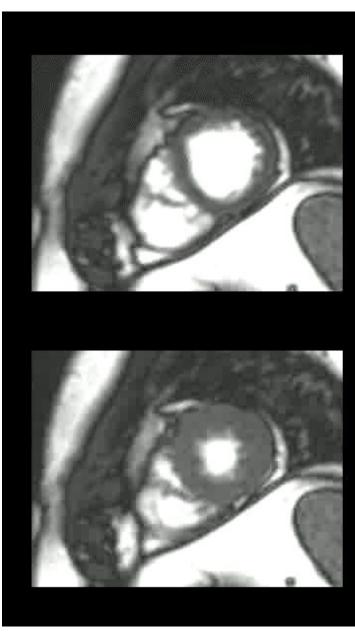
B. L. de Oliveira, B. M. Rocha, L. P. S. Barra, E. M. Toledo, J. Sundnes and R. Weber dos Santos

Abstract—Mechanical deformation affects the electrical acty of the heart through multiple feedback loops. The pure of this study is to quantify the effect of deformation on ulated electrograms from an in silico human ventricular edge". To achieve this purpose we developed a strongly pled electromechanical cell model by coupling a human left tricle electrophysiology model and an active contraction model arametrized for human cells. This model was then embedded tissue simulations based on bidomain equations and non-par solid mechanics. The effects of mechanical deformation on ulated electrograms were then evaluated. Our results indicate the feature of the electrogram that is most influenced by formation is the T-wave. Our findings are that there is an rease on the amplitude of the T-wave on simulations that ount for the effects of cardiac deformation.

Index Terms—human electromechanical model, bidomain, d mechanics, mechanoelectrical feedback, T-wave the ventricles have contracted and are in the relaxation ph The morphology of the T-wave has an important clin significance as changes to it can be associated with sev diseases and clinical conditions.

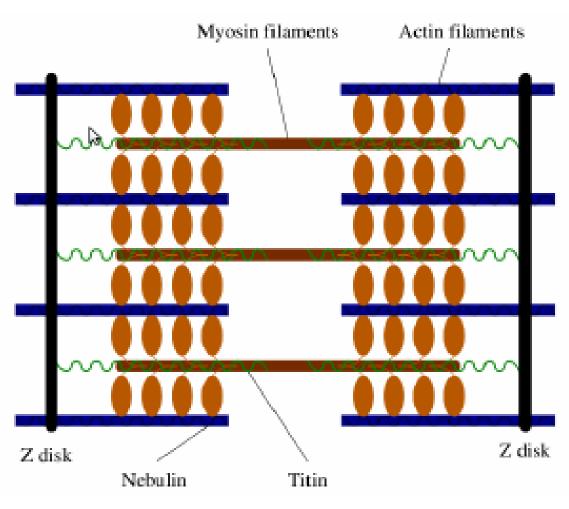
A 2D mechano-electric model was developed by Smith al. to evaluate how deformation affects the T-wave [4]. conclusion was that heart deformation slightly decreases wave amplitude. However, this study did not consider any to faction Potential (AP) heterogeneity which is well known to play an important role on T-wave morphology [6], [7].

Another study with the same purpose was developed Keller et. al. [5]. In this study different phenotypes expression of cardiac myocytes with heterogeneous action potentials we considered and a detailed 3D anatomical model of the toward developed. This study also concluded that the inclusion



#### Cardiac Mechanic

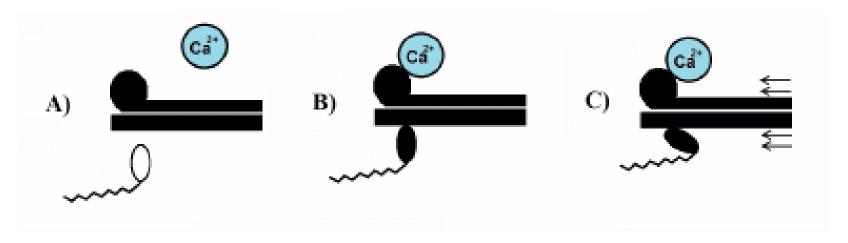
Force Generation



(Sachse 2004)

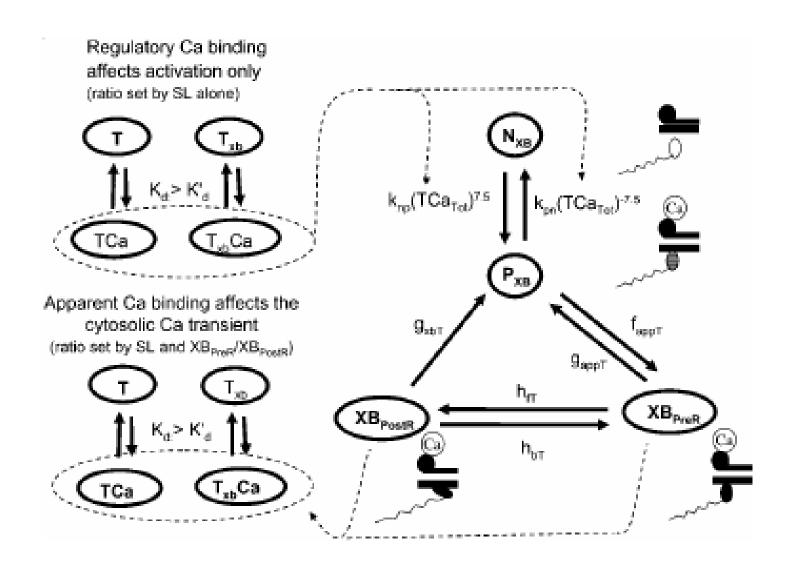
#### Cardiac Mechanic Cross Bridge

- Force is developed by a process known as cross-bridge cycling
- The rotation of myosin head generates force.
- The myofilaments slide and overlap.



#### Cardiac Mechanic

Rice model



#### Coupling Method

#### Coupled System

$$\frac{1}{\sqrt{C}} \frac{\partial}{\partial X^{M}} \left( \sqrt{C} D_{iN}^{M} C^{NL} \frac{\partial V_{m}}{\partial X^{L}} \right) = -\frac{1}{\sqrt{C}} \frac{\partial}{\partial X^{M}} \left( \sqrt{C} D_{iN}^{M} C^{NL} \frac{\partial V_{e}}{\partial X^{L}} \right) + \beta I_{m}(V_{m}, s)$$

$$\frac{1}{\sqrt{C}} \frac{\partial}{\partial X^{M}} \left( \sqrt{C} (D_{iN}^{M} + D_{eN}^{M}) C^{NL} \frac{\partial V_{e}}{\partial X^{L}} \right) = -\frac{1}{\sqrt{C}} \frac{\partial}{\partial X^{M}} \left( \sqrt{C} D_{iN}^{M} C^{NL} \frac{\partial V_{m}}{\partial X^{L}} \right)$$

$$\frac{ds}{dt} = f(V_m, s)$$

$$div \, \sigma + f = 0$$

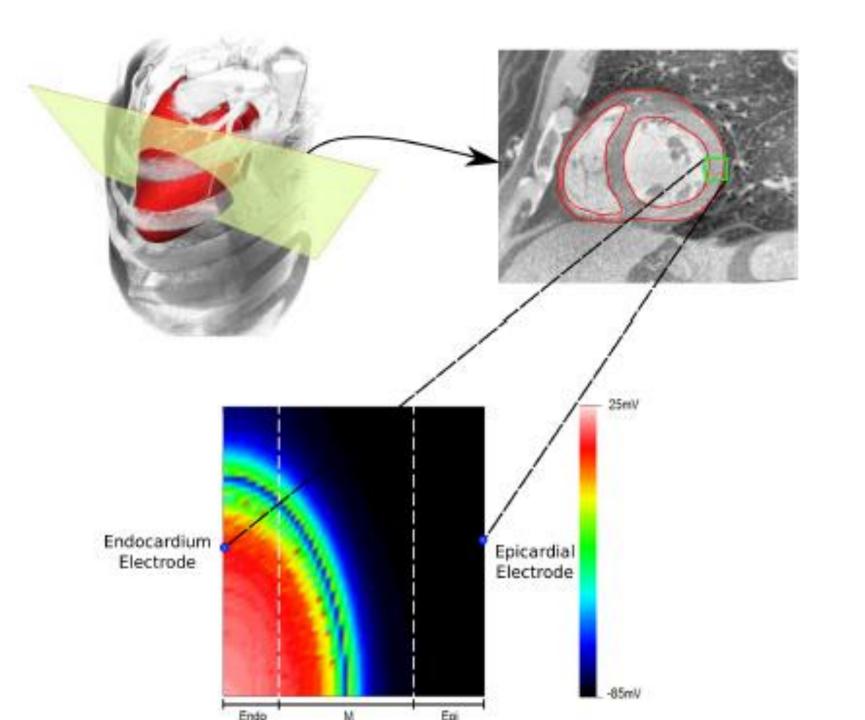
$$\sigma = \sigma_p + \sigma_a$$

$$\sigma_a = R^T \sigma_{al}(s) R$$

$$\sigma_p = J^{-1} F S F^T$$

$$S = \frac{\partial W}{\partial C}$$

$$W(I_1) = c_1(I_1 - 3)$$



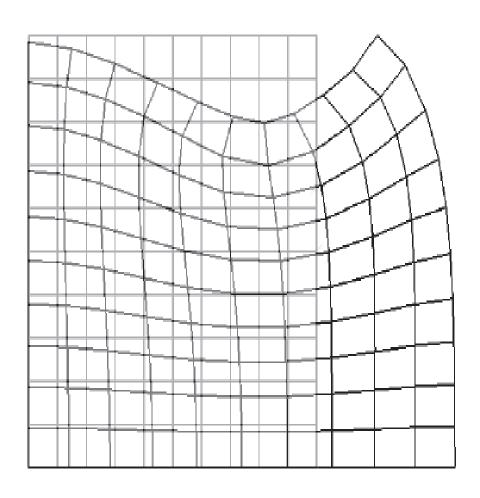
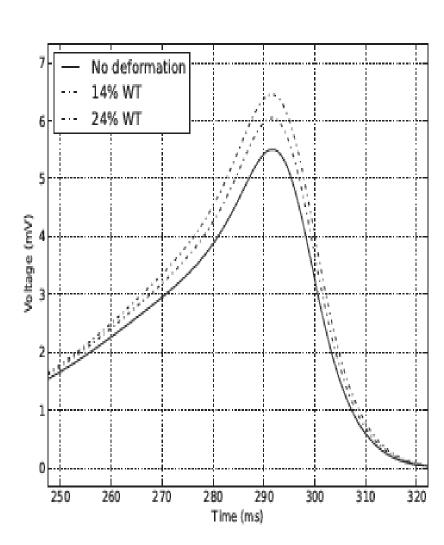
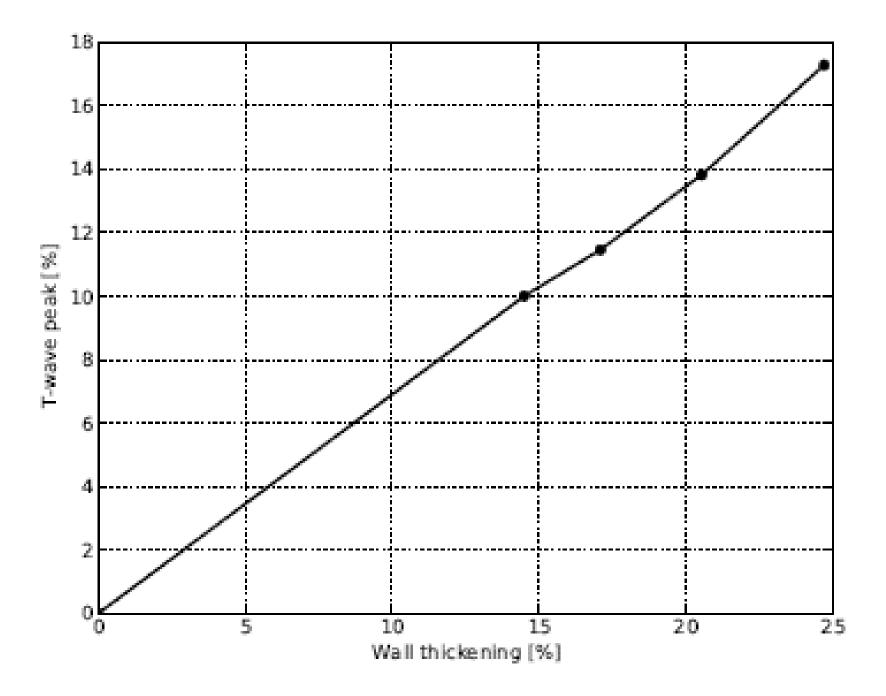


Fig. 3. Initial and deformed geometry of the human left ventricle wedge. This deformation was obtained at 110 ms of simulation, where we obtained the maximum WT.





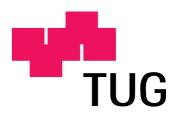
#### Repolarization summary

- T-wave format is influenced by different functional and anatomical heterogeneities of cardiac tissue as well as by the mechanical contraction of the heart.
- The computational models offer important insights that contribute to the better understanding of cardiac physiology and to the better interpretation of electrophysiological signals such as ECG, both for the case of normal and pathological conditions

# Wave Speed, slow conduction, fractionation, Saltatory effetcs







# Electro-anatomical Characterization of Microfibrosis in a Histologically Detailed Computer Model

#### Fernando Campos

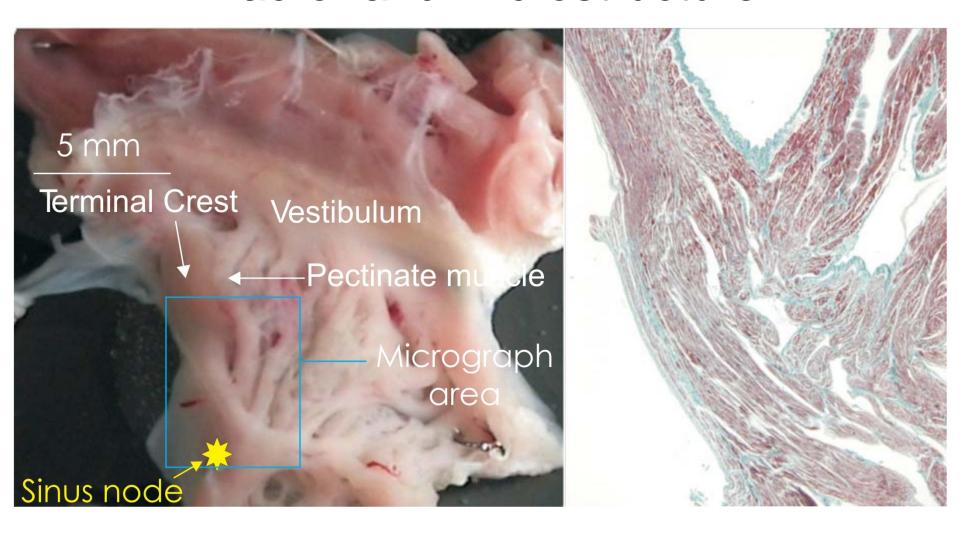
Supervisor:

Univ.-Prof. Dipl.-Ing. Dr. techn. Paul Wach

Co-supervisors:

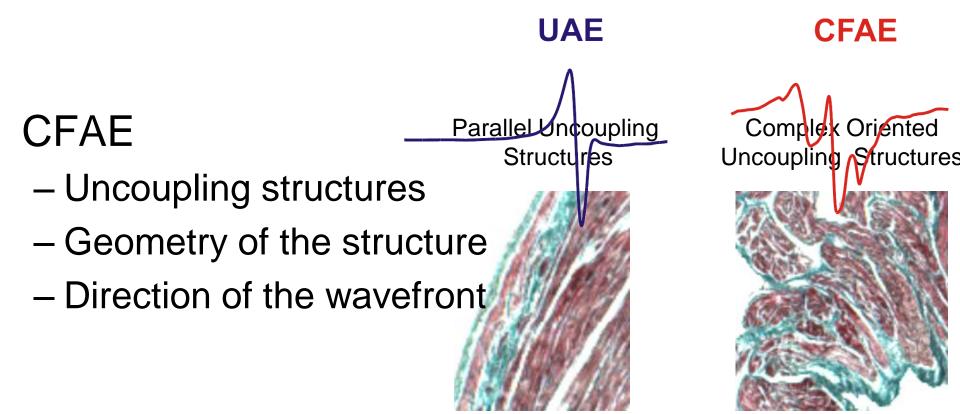
ao. Univ.-Prof. Dipl.-Ing. Dr. techn. Ernst Hofer assoz. Prof. Priv.-Doz. Dipl.-Ing. Dr. techn. Gernot Plank

## The Lower Right Atrial Isthmus Macro- and Microstructure

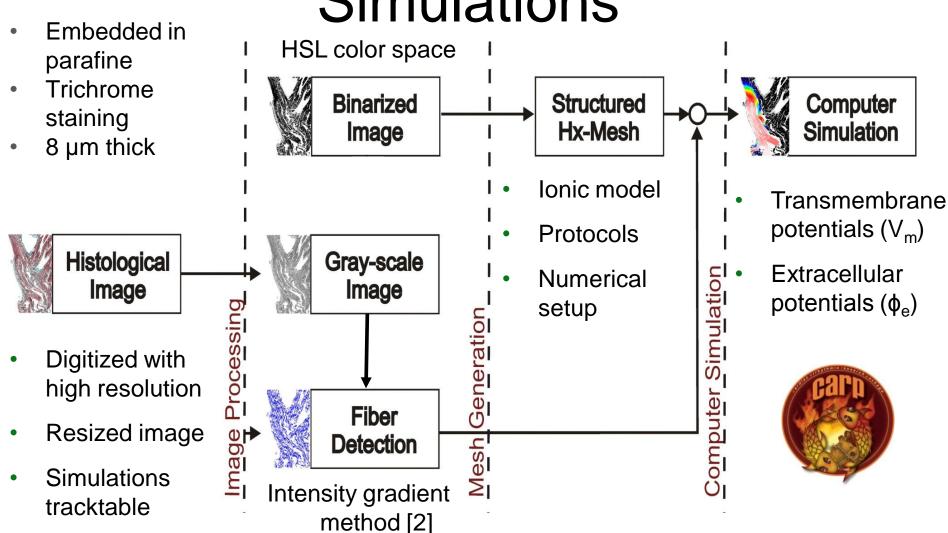


# Aging → Fibrosis → Atrial fibrillation (AF) Fibrosis may change conduction

 Uniform Atrial electrograms (UAE) → complex fractionated atrial electrograms (CFAE)



From Histographs to Computer Simulations





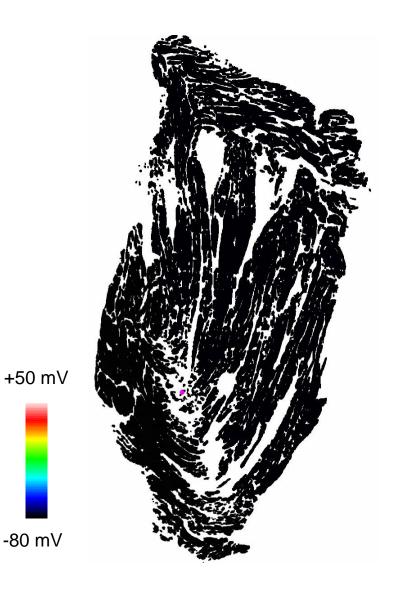
$$\nabla \cdot \left( \overline{\sigma} \nabla V_m \right) = \beta I_m,$$

$$I_m = C_m \frac{\partial V_m}{\partial t} + I_{ion}(V_m, s_i) - I_{stim},$$

$$\frac{ds_i}{dt} = f(V_m, s_i)$$



STIM (1:12)



#### Summary

- Investigate the relation between discontinuities in microstructure and CFAEs
- Support the development of a catheter tip for Multisite pacing to measure the degree of fibrosis





# Limitations of the homogenized cardiac Monodomain model for the case of low gap junctional coupling

Caroline Mendonça Costa and Rodrigo Weber dos Santos





#### Our goal

- Revisit the classical homogenized monodomain formulation
  - Evaluate its ability to reproduce the situation of low gap junctional coupling
    - Implementation and comparison of the results of two models based on the monodomain formulation

#### Motivation

- Pathological conditions
- Decrease of gap junctional coupling
  - Dilated cardiomyopathy
  - Ischemic cardiomyopathy
  - Myocarditis
  - Myocardial infarcts (< 5%)</p>

- Gap junctional remodeling
  - Affected cells are "isolated"

#### Microscopic Monodomain model

$$\nabla \cdot (\sigma(x)\nabla V_m) = \beta I_m(x)$$

with

$$I_m(x, V_m, \eta_i) = C_m \frac{\partial V_m}{\partial t} + I_{ion}(x, V_m, \eta_i) - I_{stim}$$

where

$$\frac{d\eta_i}{dt} = f(t, \eta_i)$$

$$I_{ion} = I_{Na}(x) + I_{Si} + I_K + I_{K1} + I_{Kp} + I_b$$

$$\sigma(x) = \begin{cases} \sigma_c; & i < x \le il - l_g \\ \sigma_g; & il - l_g < x, \le il \end{cases}$$

#### Homogenization

- Simplified model
- Large and complex simulations
  - No space variation
  - Effective values

 Macroscopic model that still captures the microscopic scale influence

#### Homogenization process

$$\bar{\sigma} = \frac{L}{\int_0^L \frac{1}{\sigma(x)} dx}$$

Intracellular conductivity

# Macroscopic Monodomain model

$$\nabla \cdot (\bar{\boldsymbol{\sigma}} \nabla V_m) = \beta I_m$$

with

$$I_m(V_m, \eta_i) = C_m \frac{\partial V_m}{\partial t} + I_{ion}(V_m, \eta_i) - I_{stim}$$

where

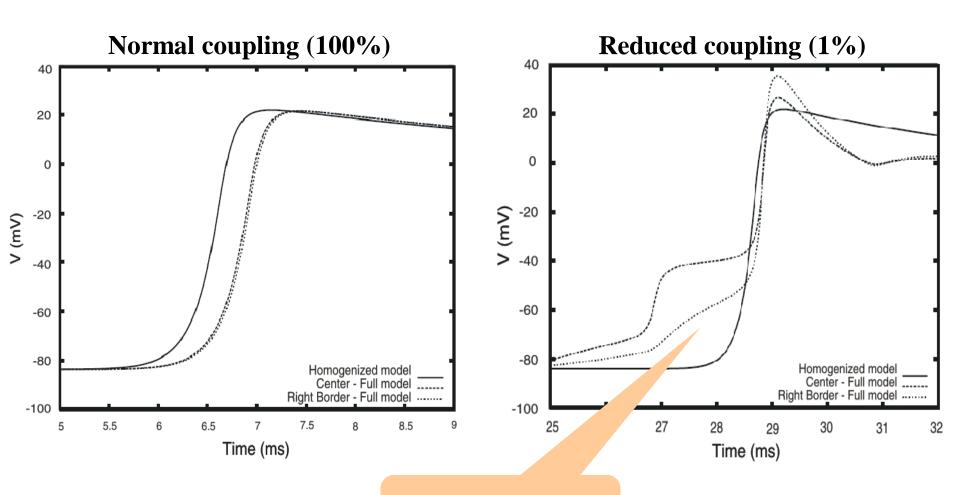
$$\frac{d\eta_i}{dt} = f(t, \eta_i)$$

$$I_{ion} = I_{Na} + I_{Si} + I_K + I_{K1} + I_{Kp} + I_b$$

#### What we did

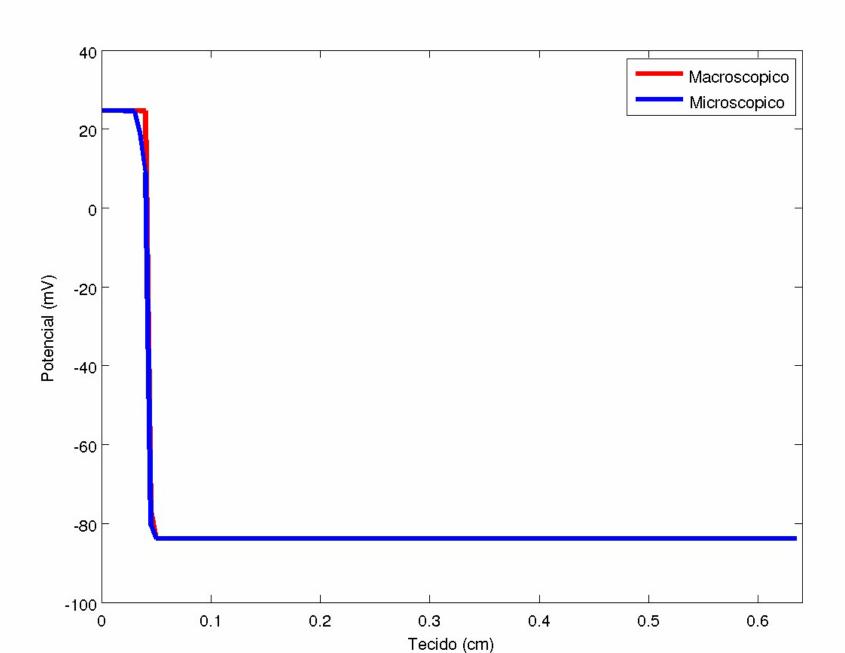
- We compared the simulation results of the two models for the case of low gap junctional coupling
  - This situations arises in many pathological conditions
  - Accurate models of these conditions are of extreme importance

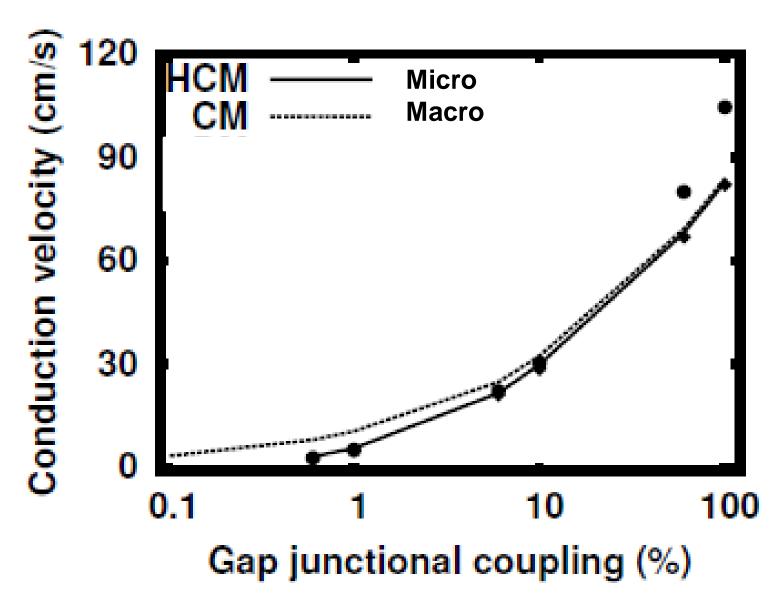
#### **Action Potential**

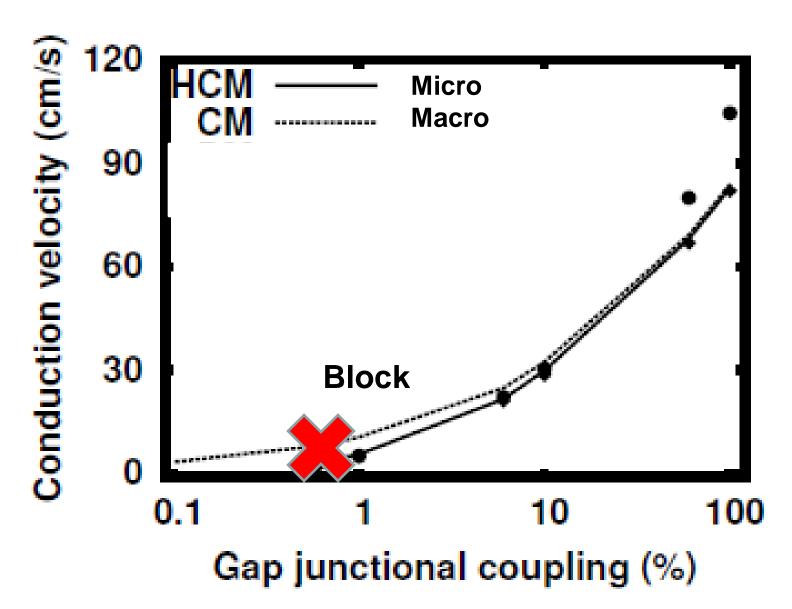


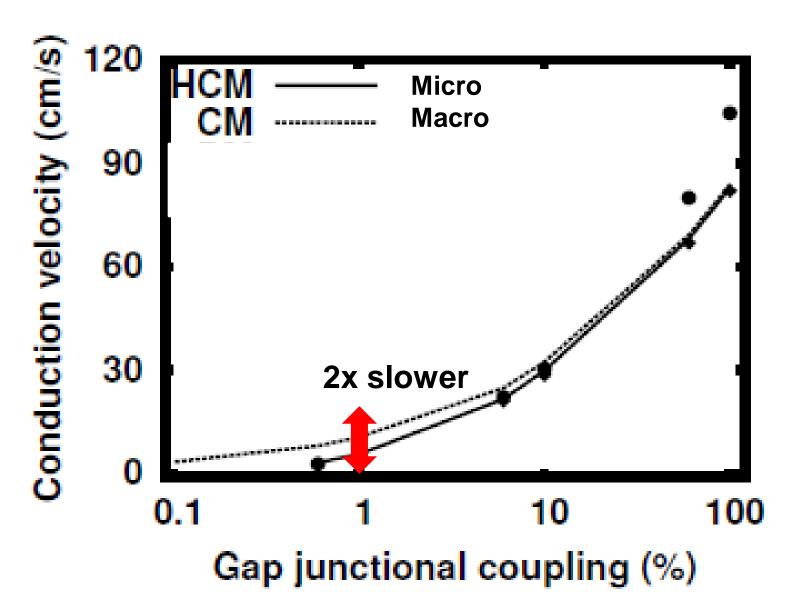
**Different shapes** 

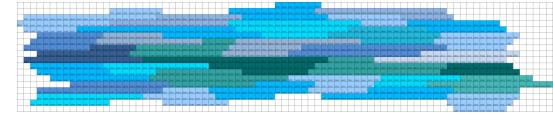
### Saltatory Conduction in 1D



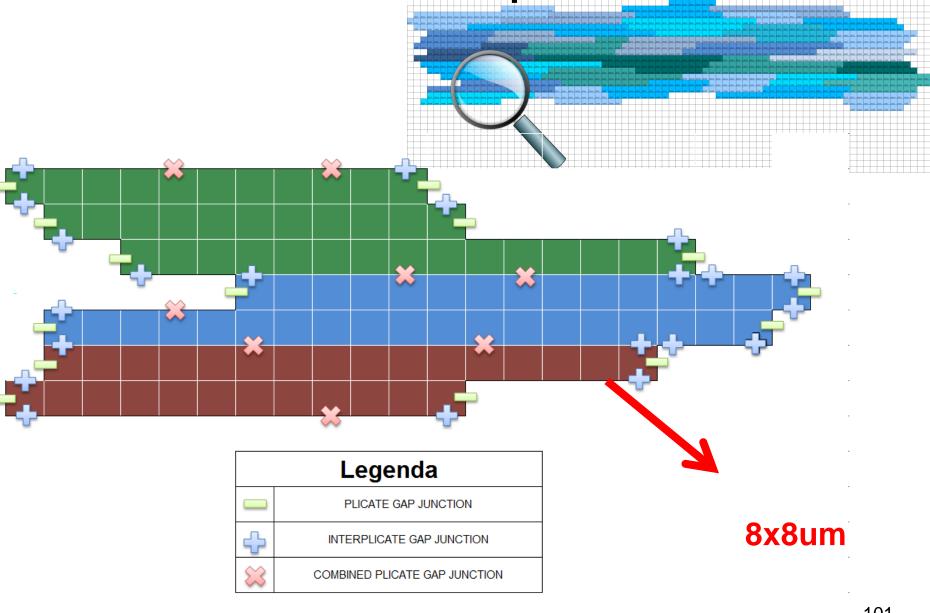


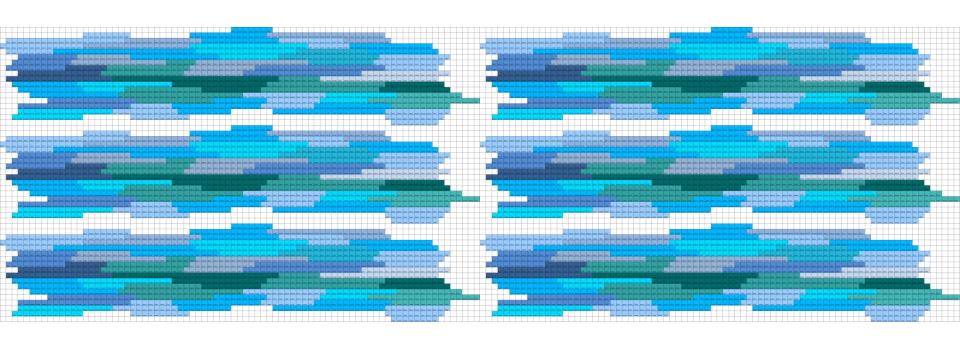


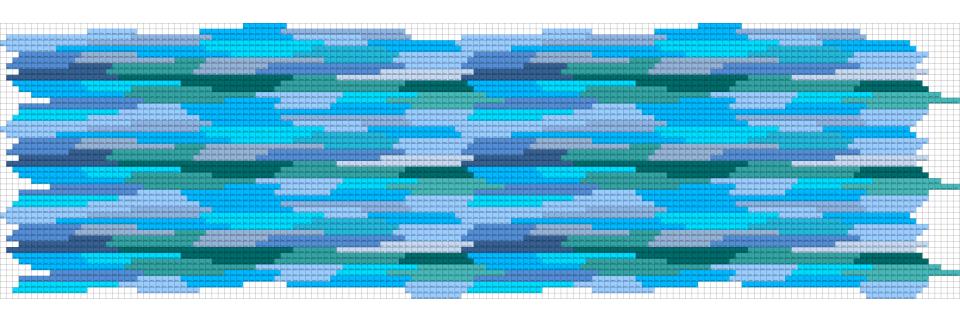


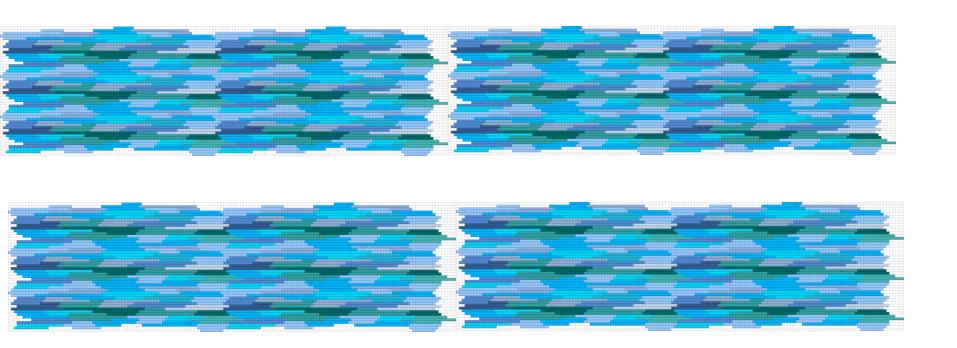


Madison S. Spach, J. Francis Heidlage The Stochastic Nature of Cardiac Propagation at a Microscopic Level Electrical Description of Myocardial Architecture and Its Application to Conduction, Circulation Research 76:366-380 (1995)



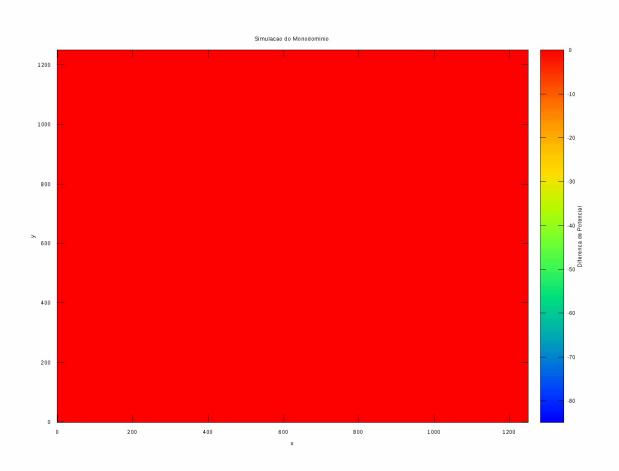






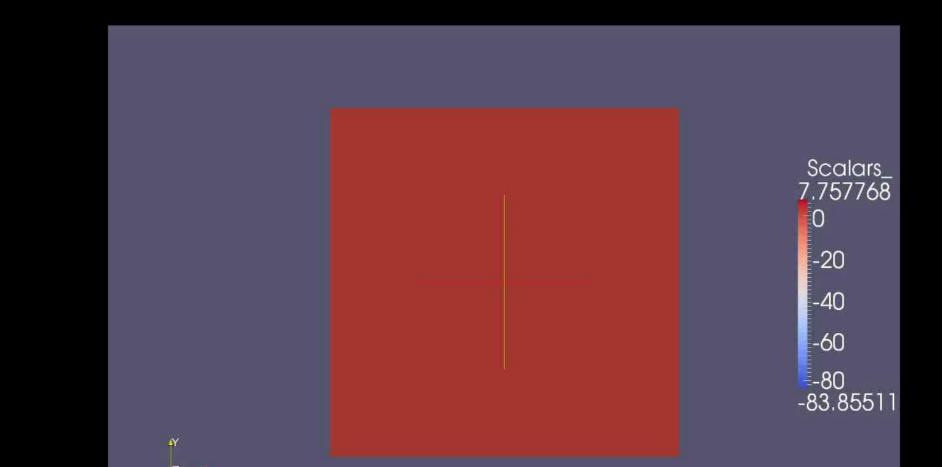
# 2D Microscopic Model 1x1cm tissue with 8x8um discretization

No. Unknowns = 1250x1250x41 = 64Millions



# 2D Microscopic Model 1x1cm tissue with 8x8um discretization

No. Unknowns = 1250x1250x41 = 64Millions Zoom in: 2mmx2mm





## Efficient Solvers Based on Manycore computers and adaptive techniques for Cardiac Modeling

PART IV



### Complex Models

Modeling Challenges: Multi-scale and Multiphysics

 Computational Challenges: Simulations are computationally expensive (one heart beat = a couple of days in a parallel machine)

 Computer Challenges: Involves the coupling of several components (submodels) and data (geometry, biophysical parameters)



# Efficient Solvers Based on Manycore computers and adaptive techniques for Cardiac Modeling

#### GPU and MultiGPU for Monodomain equation:

$$\beta C_m \frac{\partial V_m}{\partial t} + \beta I_{ion}(V_m, \eta) = \nabla \cdot (\sigma_m \nabla V_m) + I_{stim}$$
$$\frac{\partial \eta}{\partial t} = \mathbf{f}(V_m, \eta)$$

#### Methods

- Cell Model: LR1
- Tissue: 0.5cmx0.5cm
- Non-linear system of PDE: Operator Splitting
- ODE System: Solved with explicit Euler
- PDE: Discretized with Finite Elements, Implicit Euler for time
- Discretization: dx = 50m, t = 0.01 ms
- Linear System: CG
- Parallelization: OPEMP, CUDA, OPENCL, OPENGL

#### Numerical experiments - Environment

- Intel Core i7 860 2.80GHz, 8GB of memory
- GPUs:
  - NVIDIA GeForce GTX 470, 448 CUDA cores, 1 GB GDDR5 memory and 133.9 GB/s of memory bandwidth
  - AMD Radeon 6850, 960 Stream processors, 1 GB GDDR5 memory and 128 GB/s of memory bandwidth



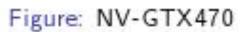




Figure: AMD-R6850

#### Results - Comments on ODE problem

- Embarrassingly parallel problem. High ratio of Comp/Mem
- Good performance of the GPU solvers.
- OpenGL was faster in all tests using NVIDIA GTX 470.
- Mathematical optimization flags really improves the performance of the ODE solver (GTX 470).
- We observed a good performance of the OpenCL implementation.

| Speedup            |     |  |  |  |
|--------------------|-----|--|--|--|
| NV-GTX470 - OpenGL | 449 |  |  |  |
| NV-GTX470 - CUDA   | 286 |  |  |  |
| NV-GTX470 - OpenCL | 277 |  |  |  |
| AMD-R6850 - OpenCL | 109 |  |  |  |

Compared to OPENMP with 4 cores

#### Results - Comments on PDE problem

- Non-embarrassingly parallel
- Building blocks: SpMV, DotProduct, Conjugate Gradient.
- Poor performance when using the "traditional" CSR format.
- Significant improvements using formats that exploits the structure of the matrix, i.e., DIA format (or even ELLPACK)
- CUDA outperforms the other implementations using NV-GTX470

| Speedup                  |     |
|--------------------------|-----|
| NV-GTX470 - CUDA - DIA   | 8.6 |
| NV-GTX470 - CUDA - CSR   | 1.5 |
| NV-GTX470 - OpenCL - DIA | 4.8 |
| NV-GTX470 - OpenCL - CSR | 1.3 |
| NV-GTX470 - OpenGL - DIA | 4.1 |
| AMD-R6850 - OpenCL       | 2.1 |

# Compared to OPENMP with 4 cores

- OpenCL was slower than CUDA:
  - CSR ~14%
  - DIA ~76%

OPENMP was 2.5 faster than seq. code

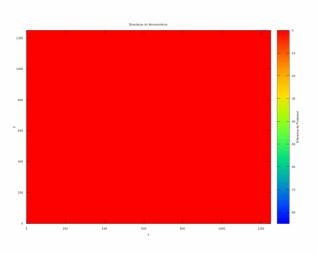
# GPGPU implementation using CUDA with **1 GPU** offered a total speedup of **35** (ODE + PDE) when compared to OPENMP running with **4 cores**

<sup>--</sup> Rocha, B. M.; Campos, F. O.; AMORIM, R. M.; PLANK, G.; Santos, R. W. dos; Liebmann, M.; Haase, G.. Accelerating cardiac excitation spread simulations using graphics processing units. **Concurrency and Computation**, v. 23, p. 708-720, 2011.

# 2D Microscopic Model 1x1cm tissue with 8x8um discretization

(No. Unknowns = 1250x1250x41 = 64Millions) on MultiGPU platform





#### Methods

- Cell Model: Bondarenko et al.
- Simulation time: 10ms
- Non-linear system of PDE: Operator Splitting
- ODE System: Solved with explicit Euler
- PDE: Discretized with Finite Elements, Implicit Euler for time
- Linear System: CG
- Parallelization:

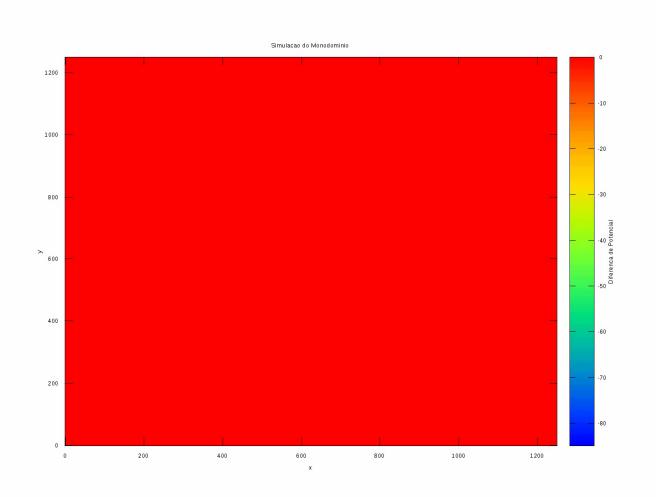
#### PETSc(MPI) for PDE + CUDA for ODEs

 Small Cluster: 8 machines (2 quad-core Intel Xeon CPU E5420 2.50GHz 8 GB RAM + 1 Tesla C1060 GPU) = 64 cores + 8 GPUs

| cores             | Exec Time           | Speedup             |
|-------------------|---------------------|---------------------|
| 0.5cmx0.5cm -> #  | 25*41 = 16 millions |                     |
| 1                 | 1.6day              | 1                   |
| 8                 | 5.1h                | 7.5                 |
| 16                | 2.6h                | 14                  |
| 32                | 1.2h                | 31                  |
| 64                | 38min               | 60                  |
| 64 cores + 8 GPUs | 6.7min              | 343                 |
| 1cmx1cm -> # unl  | xowns = 1250x125    | 0x41 = 64  millions |
| 1                 | 6.3days             | 1                   |
| 64                | 2.4h                | 61                  |
| 64 cores + 8 GPUs | 21.7min             | 420                 |

# 2D Microscopic Model 1x1cm tissue with 8x8um discretization

No. Unknowns = 1250x1250x41 = 64Millions





# Efficient Solvers Based on Manycore computers and adaptive techniques for Cardiac Modeling

#### GPU and MultiGPU for Monodomain equation:

$$\beta C_m \frac{\partial V_m}{\partial t} + \beta I_{ion}(V_m, \eta) = \nabla \cdot (\sigma_m \nabla V_m) + I_{stim}$$
$$\frac{\partial \eta}{\partial t} = \mathbf{f}(V_m, \eta)$$

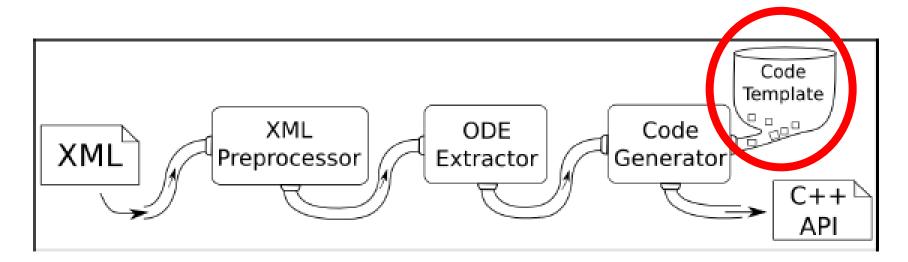
## AGOS – Automatic CellML To Numerical Sover (C, C++, CUDA, OpenMP))

- -- Garny, Alan; Nickerson, David P.; Cooper, Jonathan; SANTOS, Rodrigo Weber dos; Miller, Andrew K.; McKeever, Steve; Nielsen, Poul M.F.; Hunter, Peter J.. CellML and associated tools and techniques. **Philosophical Transactions. Royal Society. Mathematical, Physical and Engineering Sciences**, v. 366, p. 3017-3043, 2008.
- -- Campos, Ricardo Silva; Amorim, Ronan Mendonca; Costa, Caroline Mendonça; Lino de Oliveira, Bernardo; BARBOSA, Ciro de Barros; Sundnes, Joakim; Weber dos Santos, Rodrigo. Approaching cardiac modeling challenges to computer science with CellML-based web tools. **Future Generation Computer Systems**, v. 26, p. 462-470, 2010

#### (Ricardo Campos Master Thesis)

#### **CELL-Level Simulations**

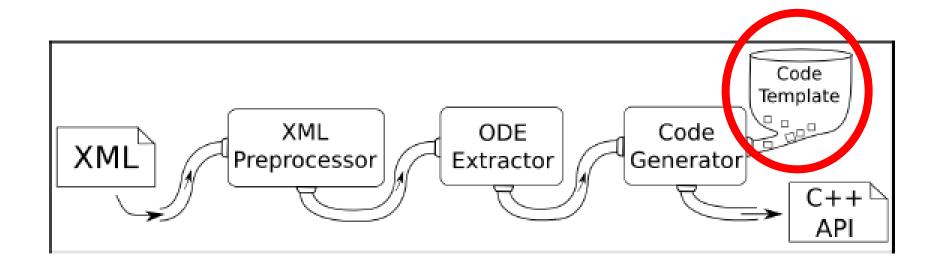
- Implement and merge different optimizations proposed before for the EULER method within the AGOS framework:
- Adaptive Time Step
- LUT + fine PE (PYCML)
- OPEMP
- Result: Light-weight explicit method more efficient than BDF (SUNDIALS) for cardiac modeling



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#### **CELL-Level Simulations**

- Implement and merge different optimizations proposed before for the EULER method within the AGOS framework:
- Euler with Adaptive Time Step
- Result: Light-weight explicit method more efficient than BDF (SUNDIALS) for cardiac modeling



#### Methods

 Four models were tested, h chosen so that errors (relative L2) compared to a simulation using very fine h were < 1%</li>

Computer: Intel Core i7 860 2.80GHz and 8GB

| Model                     | Frequency(Hz) | Simulation(s | Fixed h(s) |
|---------------------------|---------------|--------------|------------|
| Noble et al               | 1             | 100          | 1,0e-5     |
| TenTusscher e<br>Panfilov | 2             | 100          | 1,0e-6     |
| Garny et al               | -             | 100          | 5,0e-6     |
| Bondarenko et al          | 14            | 10           | 2,0e-7     |

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## Stiff ODEs

- Cardiac models are based on Stiff ODEs
- Cell-level simulations normally use BDF method from SUNDIALS with adaptivity for both time step and method order
- However, these methods are usually not used in tissue simulations due to huge memory consumption (Jacobian, Newton, etc).
- EULER or similar light-weight explicit methods (R-L): preferred methods for Ttssue simulations due to simplicity and low memory consumption

DRAWBACK: Demands small h -> many iterarions

### Methods

#### Time Step adaptive method:

- Increase/decrease h based on comparison:
- Euler x Heun 2<sup>nd</sup> order.

$$\widetilde{y}_{i+1}^{j} = y_{i}^{j} + h_{i}f^{j}(t_{i}, \overrightarrow{y_{i}})$$

$$y_{i+1}^{j} = y_{i}^{j} + \frac{h_{i}}{2}(f(t_{i}, \overrightarrow{y_{i}}) + f(t_{i+1}, \overrightarrow{\widetilde{y_{i+1}}}))$$

$$error_{i} = ||\overrightarrow{y_{i+1}} - \overrightarrow{\widetilde{y_{i+1}}}||_{\infty}$$

$$h_{i+1} = get\_new\_h(erro_{i}, tol, h_{i})$$

Get a new h using the difference between Heun and Euler solution, a user-defined tolerance (tol) and the current time step h.

$$h_{i+1} = h_i \sqrt{\frac{tol}{erro_i}}$$

If error i > tol:

Throw the iteratrion results away and compute them again with a new h

#### Else:

Accept results and go on to the next iteration with the new h.

## Adaptive Time Step Results

| BD | F | X | E | uler | X | AM |  |
|----|---|---|---|------|---|----|--|
|----|---|---|---|------|---|----|--|

BDF from 4.5 to 23.7 times faster than Euler

In average, BDF consumes 80% more memory;

AM: from 5.6 to 31.6 times faster than Euler

|     | Model       | Euler | ATSH | BDF  |
|-----|-------------|-------|------|------|
|     | Run-time(s) | 28.0  | 5.0  | 6.2  |
| NBL | Memory(kB)  | 180   | 180  | 316  |
|     | Error(%)    | 0.07  | 0.17 | 0.9  |
|     | Run-time(s) | 317.0 | 48.7 | 40.8 |
| TTP | Memory(kB)  | 180   | 180  | 312  |
|     | Error(%)    | 0.02  | 0.5  | 0.8  |
|     | Run-time(s) | 47.4  | 1.5  | 2.0  |
| GRN | Memory(kB)  | 152   | 152  | 288  |
|     | Error(%)    | 0.9   | 0.9  | 0.2  |
|     | Run-time(s) | 165.4 | 10.0 | 11.5 |
| BDK | Memory(kB)  | 196   | 146  | 356  |
|     | Error(%)    | 0.003 | 0.6  | 0.6  |

#### Results

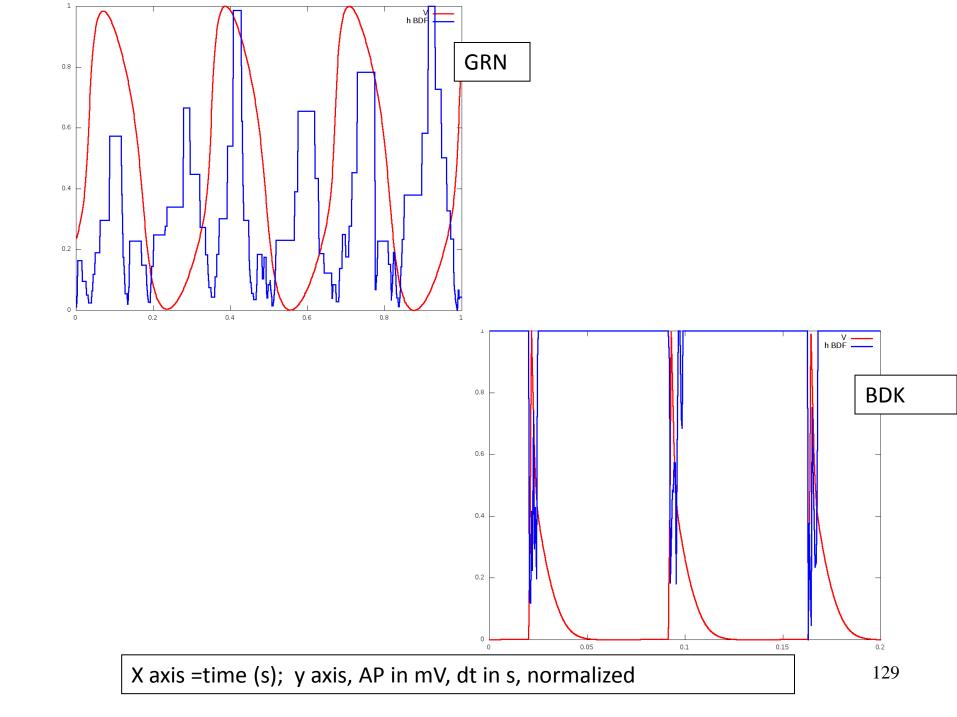
|  | BDF | Χ | Eu | ler | X | A۱ | / |
|--|-----|---|----|-----|---|----|---|
|--|-----|---|----|-----|---|----|---|

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# Summary

 AM x Euler: from 6 to 32 times faster than Euler, with same memory consumption

#### (Rafael Sachetto PhD thesis)

# Tissue Model: Adaptive mesh + time step + OPENMP

- Electrical wave propagation: only a fraction of the excitable medium is occupied by wavefronts.
- Wavefront demands fine mesh.
- It is possible to take into account the scale differences in the phenomena via reliable and efficient solutions.
- Adaptive mesh procedure:
  - Autonomous Leaves Graph (ALG).

- Computer: 2 quad-core Intel(R) Xeon(R) CPU E5420 2.50GHz 8 GB RAM
- Cell Model: Bondarenko et al. (40ms simulation)
- Non-linear system of PDE: Operator Splitting
- ODE System: Solved with the Adaptive Time Step method described before
- PDE: Discretized with Finite Volume Method, Implicit Euler
- Adaptive Mesh generation: based on ALG data structure (Graphs) and Peano-Hilbert Space Filling Curve – Generates non-conformal meshes – used both for strucutures and nonstructrured meshes
- Linear System: CG
- Parallelization: OPEMP
- L2 relative error computed from a very fine spatial and time discretization (25x25um)

### **ALG**

- Graph-based Data structure that can be integrated to the linear system solver to properly represent different geometries.
- Generic data structure, which does not rely on any type of numerical method, on the geometry of the problem nor on the problem's nature.

## **ALG**

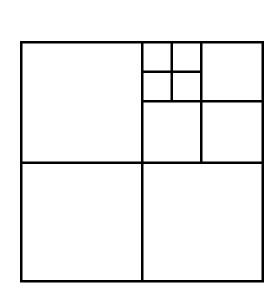
| _  | $\overset{\circ}{\Omega}_{6}$ $\overset{\circ}{\Omega}_{5}$ $\overset{\circ}{\Omega}_{3}$ $\overset{\circ}{\Omega}_{4}$ | $\mathring{\tilde{\Omega}}_{\circ}$              |
|--|---|--|
| $\overset{\circ}{\Omega}_{\scriptscriptstyle 7}$     | $\overset{\circ}{\boldsymbol{\Omega}}_{\scriptscriptstyle 2}$   | $\overset{\circ}{\Omega}_{\scriptscriptstyle 1}$ |
| •  |   |  |
| $\overset{\circ}{\Omega}_{\scriptscriptstyle{ m B}}$ | 2   | <b>)</b>   |

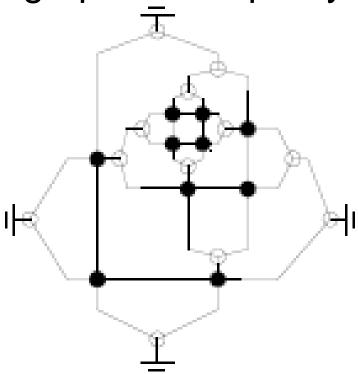
$$\alpha V_{i,j}^* - \sum_{k=1}^{m_1} \sigma_{x_{r',k}} (V_{r,k} - V_{i,j}) + \sum_{k=1}^{m_2} \sigma_{x_{l',k}} (V_{i,j} - V_{l,k})$$
$$- \sum_{k=1}^{m_3} \sigma_{y_{t',k}} (V_{t,k} - V_{i,j}) + \sum_{k=1}^{m_4} \sigma_{y_{b',k}} (V_{i,j} - V_{b,k}) = V_{i,j}^n \sigma_{y_{b',k}}$$

where  $\alpha = (\beta C_m h_{i,j}^2)/\Delta t$ .

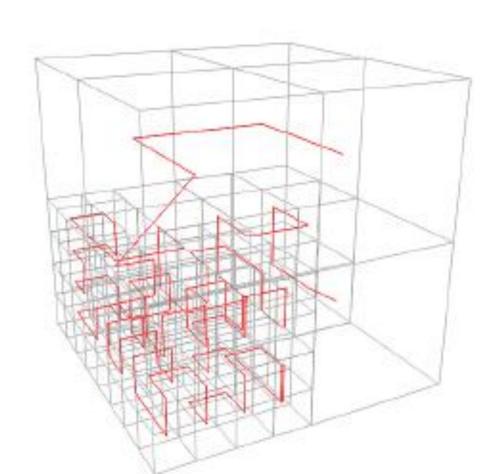
### **ALG Data-Structure**

- Black dot- Volume/Element node
- White dot Interface node
- Ground Domain Boundary
- Directions are omitted on graph for simplicity



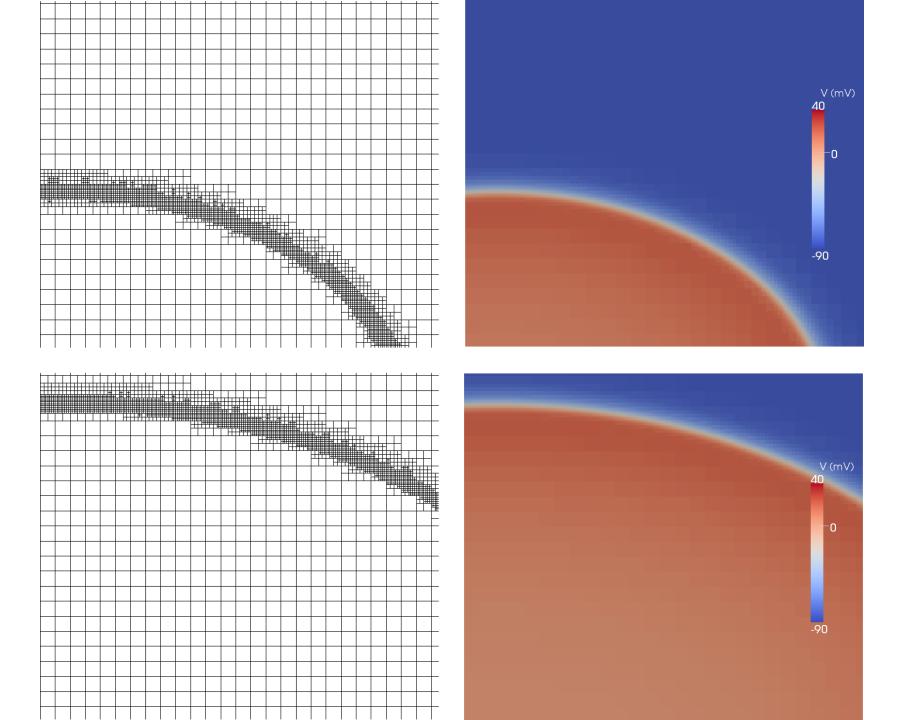


# Sorting the mesh/data-structure via Hilbert Curve



# ALG and the monodomain problem

```
begin
  set cell model initial conditions;
  set monodomain initial conditions;
  assemble the monodomain matrix (Linear system form
  PDE);
  while (t < t_ final)
      update_cell_model_state_vector;
      solve_cell_model;
      solev Linear System (PDE) via conjugate_gradient
      refine-unrefine
      reassemble the monodomain matrix if needed;
      t = t + dt
  end while
```



| Size (cm) | DX min/max(um)    | dt EDP(us) | dt EDO min/max(us) | Exec Time     | Speedup | Error (%) |  |  |
|-----------|-------------------|------------|--------------------|---------------|---------|-----------|--|--|
|           | Fixed mesh and dt |            |                    |               |         |           |  |  |
| 0.64x0.64 | 50/50             | 0.1        | 0.1/0.1            | 8. <b>6</b> h | 1.0     | 1.1       |  |  |
|           | Fixed m           | esh and    | two fixed dts      | \             | E)      |           |  |  |
| 0.64x0.64 | 50/50             | 10         | 0.1/0.1            | 6.8h          | 1.26    | 2.5       |  |  |
|           |                   | Fixed m    | nesh and ada       | pt dt         |         |           |  |  |
| 0.64x0.64 | 50/50             | 10         | 0.01/0.1           | 1.1h          | 8.15    | 2.6       |  |  |
|           |                   | Ada        | pt mesh and        | dt            |         |           |  |  |
| 0.64x0.64 | 50/50             | 10         | 0.01/10            | 10min         | 48.2    | 2.4       |  |  |
|           | Adapt             | mesh an    | id dt + OPEN       | MP(8 cores    | 3)      |           |  |  |
| 0.64x0.64 | 50/200            | 10         | 0.01/10            | 1.4min        | 368.6   | 2.4       |  |  |
|           |                   |            |                    |               |         |           |  |  |
| 1.28x1.28 | 50/200            | 10         | 0.01/10            | 5.8min        |         |           |  |  |
| 2.56x2.56 | 50/200            | 10         | 0.01/10            | 20min         |         |           |  |  |
| 5.12x5.12 | 50/200            | 10         | 0.01/10            | 51min         |         |           |  |  |
|           |                   |            | -                  |               | •       | -         |  |  |
|           |                   |            |                    |               |         |           |  |  |
|           |                   |            |                    |               |         |           |  |  |

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| 2.56x2.56                                      | 50/200            | 10         | 0.01/10            | 20min         |         |           |
| 5.12x5.12                                      | 50/200            | 10         | 0.01/10            | 51min         |         |           |
| X  | l <u>o</u> . Unkn | owns       | $= 1024 \times 10$ | 24x41 =       | 43Mill  | ons       |
| Less than a hour on a single and old (8-cores) |                   |            |                    |               |         |           |
|  |                   |            | compute            |               | •       | ,         |

### Results

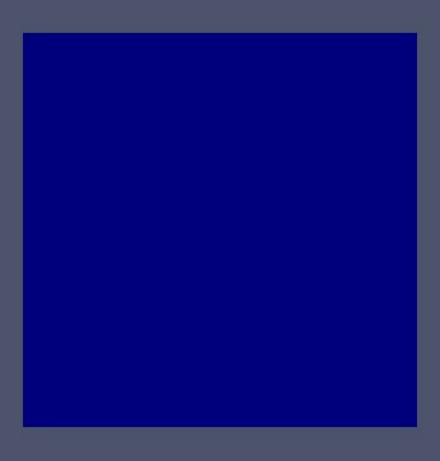
| 0.64x0.64cm Size: Adapt time space + OPENMP |         |                        |     |  |  |  |  |  |
|---|---------|------------------------|-----|--|--|--|--|--|
|   | Time(s) | Time(s) % time Speedup |     |  |  |  |  |  |
| Total                                       | 88      | 100,0                  | 7,2 |  |  |  |  |  |
| CG  | 1,3     | 1,5                    | 4,5 |  |  |  |  |  |
| ODE   | 78      | 88,2                   | 8,0 |  |  |  |  |  |
| Matrix                                      | 0,9     | 1,0                    | 1,9 |  |  |  |  |  |
| Ref/Unref                                   | 7,1     | 8,0                    | -   |  |  |  |  |  |

| 2.56x2.56cm Size: Adapt time space + OPENMP |         |        |         |
|---|---------|--------|---------|
|   | Time(s) | % time | Speedup |
| Total                                       | 1203    | 100,00 | 6,00    |
| CG  | 99      | 8,24   | 8,50    |
| ODE   | 733     | 60,90  | 7,90    |
| Matrix                                      | 27      | 2,26   | 6,10    |
| Ref/Unref                                   | 369     | 30,65  | -       |

### Conclusions

- Accelerating Monodomain in:
- ☐ 1 computer with 1 GPU = up to 35x faster than 4 CPU cores
- ☐ 1 cluster with 64 cores + 8 GPUs = up to 420x faster than 1 core

- □ 1 computer with Adaptive time step and mesh algorithms + OPenMP (8-cores) = up to 370x faster than 1 core without adaptive methods
  - □ps.: Espiral simulation was more than 100x faster



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# Ongoing work: 3D + Adaptivity + MultiGPU

