

Multimodal image registration by optimal control methods

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Problem statement. We present an optimal control approach to the registration of greyscale images $I_0(s)$, $I_1(s): \Omega \rightarrow [0, 1]$, $\Omega \subset \mathbb{R}^2$, with different modalities. Following [4] and [5], we determine an elastic deformation $x: \Omega \rightarrow \mathbb{R}^2$ as a solution of the following Dieudonné-Rashevsky type control problem:

$$(P): \quad F(x) = \int_{\Omega} \left(k_1(s - x(s)) - k_0(s) \right)^2 ds \\ + \mu \cdot \int_{\Omega} r(Jx(s)) ds \longrightarrow \inf!; \quad x \in W_0^{1,\infty}(\Omega, \mathbb{R}^2); \quad Jx(s) \in K \subset \mathbb{R}^{2 \times 2} \quad (\forall) s \in \Omega.$$

The registration is based on edge sketches $k_0(s)$, $k_1(s)$, which will be derived from the image data I_0 , I_1 by an optimal control method as well. Within (P), $K \subset \mathbb{R}^{2 \times 2}$ is a convex body with $0 \in \text{int}(K)$. We consider the linear-elastic or hyperelastic regularization terms

$$r(Jx(s)) = \sum_{i,j=1}^2 \left(\frac{\partial x_i(s)}{\partial s_j} + \frac{\partial x_j(s)}{\partial s_i} \right)^2 ds, \\ r(Jx(s)) = \left(c_1 \|E_2 - Jx(s)\|^p + c_2 (\text{Det}(E_2 - Jx(s)))^2 \right) ds,$$

respectively. The introduction of constraints for the Jacobi matrix Jx reflects the necessity to ensure the validity of the underlying elasticity models (the resulting shear stress must remain bounded).

Numerical solution. For the numerical solution of (P), an efficient direct method will be provided. We evaluate the necessary optimality conditions for the discretized problem and solve the resulting large-scale system of nonlinear equations by interior-point methods, cf. [1] and [5]. Selected numerical results will be presented and discussed.

References.

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