Advanced Functional Analysis 3. Exercise Sheet– 10th November, 2021

Basic information: Lipschitz boundary and trace

A bounded domain (i.e., non-empty, open, connected and bounded) $\Omega \subset \mathbb{R}^d$ is said to possess Lipschitz boundary (or be a bounded Lipschitz domain), if there is $N \in \mathbb{N}$, open sets $(U_i)_{i \in \{1,\ldots,N\}}$ such that $\partial \Omega \subset \bigcup_{i=1}^N U_i$, associated orthonormal systems $(e_i^1, \ldots, e_i^d) = E_i \in \mathbb{R}^{d \times d}$ and Lipschitz continuous functions $g_i : \mathbb{R}^{d-1} \to \mathbb{R}$ such that for $x \in U_i$ with $(x_i^1, \ldots, x_i^d) := E_i^* x$ (the parameter representation):

$$\begin{cases} x \in \partial \Omega & \text{if and only if} \qquad x_i^d = g_i(\overline{x}_i), \\ x \in \Omega & \text{if and only if} \qquad x_i^d < g_i(\overline{x}_i), \\ x \notin \Omega & \text{if and only if} \qquad x_i^d > g_i(\overline{x}_i), \end{cases}$$
(1)

where $\overline{x}_i = (x_i^1, \ldots, x_i^{d-1})$. Without loss of generality, it can always be assumed that the U_i are hypercubes, i.e., $U_i = \{x \in \mathbb{R}^d \mid x_i^j \in]\alpha_i^j, \beta_i^j[$ for $j \in \{1, \ldots, d\}\}$ for some constants $\alpha_i^j, \beta_i^j \in \mathbb{R}$ and restrict g_i to $U'_i = \{z \in \mathbb{R}^{d-1} \mid z^j \in]\alpha_i^j, \beta_i^j[$ for $j \in \{1, \ldots, d-1\}\}$. Recall, that (by the Rademacher theorem) a Lipschitz continuous function is almost everywhere (totally) differentiable.

Setting $\tilde{g}_i(x) = x_i^d - g(\overline{x}_i)$ and $\tilde{\nu}_i := E_i \nabla \tilde{g}_i = E_i \left(-\frac{\partial g_i}{\partial x^1}, \dots, -\frac{\partial g_i}{\partial x^{d-1}}, 1 \right)^T$, the outer normal is (almost everywhere) given via $\nu = \tilde{\nu}_i / \|\tilde{\nu}_i\|$. In particular, ν does depend only on x, and not on U_i , g_i and E_i (altough this construction does).

Given $(x^1, \ldots, x^{d-1}) \in U'_i$ we set $\underline{x}_i = \sum x^j e_i^j + g_i(x^1, \ldots, x^{d-1}) e_i^d = E_i(x^1, \ldots, x^{d-1}, g_i)^T \in \partial\Omega \cap U_i$ (the associated boundary point). For a function $f: U_i \cap \partial\Omega \to \mathbb{R}$ such that $(x^1, \ldots, x^{d-1}) \mapsto f(\underline{x}_i)$ is measurable on U'_i , one can define the integral

$$\int_{\partial\Omega\cap U_i} f \,\mathrm{d}s := \int_{U_i'} f(\underline{x}_i) \|\tilde{\nu}_i(\underline{x}_i)\| \,\mathrm{d}(x^1, \dots, x^{d-1}).$$
(2)

Note that for a smooth boundary, this formula coincides with the classical formula for surface integrals. For measurable functions $f: \partial \Omega \to \mathbb{R}$ (such that each $f_{|\partial\Omega_i}$ is measurable as above), the integral $\int_{\partial\Omega} f \, ds := \sum_{i=1}^N \int_{\partial\Omega \cap U_i} \xi_i f \, ds$, where $(\xi_i)_{i=1}^N$ is a suitable partition of unity of $\partial\Omega$ with respect to U_i . So we can now define spaces $L^p(\partial\Omega)$ in the classical way with respect to aforementioned integral formulation (with measure $S(A) = \int_{\partial\Omega} \chi_A \, ds$). Note that alternatively, one could construct these spaces via Hausdorff measures, whose construction is however quite technical.

On a Lipschitz domain Ω , the subspace $\mathcal{C}^{\infty}(\overline{\Omega})$ is dense in $W^{1,p}(\Omega)$ for $p < \infty$, and there is a (unique) linear continuous operator (called the trace operator) $\gamma \colon W^{1,p}(\Omega) \to L^p(\partial\Omega)$ such that $\gamma u = u_{|\partial\Omega|}$ almost everywhere when $u \in \mathcal{C}^{\infty}(\overline{\Omega})$.

Example 3.1) [No trace for L^p]

Let Ω be a domain with Lipschitz boundary, and $p \in [1, \infty[$. Show that there is no linear continuous operator $T: L^p(\Omega) \to L^p(\partial\Omega)$ such that $Tu = u_{|\partial\Omega}$ for $\mathcal{C}^{\infty}(\overline{\Omega})$.

Hint. Show that the boundary measure S is finite and not trivial (not the zero measure), concluding that $L^p(\partial\Omega)$ is not trivial $(L^p(\partial\Omega) \neq \{0\})$.

Remark. This result illustrates that it is not possible to define a trace operator from $L^p(\Omega)$, meaning there is no reasonable way to define boundary values for all L^p functions.

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Example 3.2) [Integration by parts]

Let $\Omega \subset \mathbb{R}^d$ be a bounded Lipschitz domain, $p, p^* \in]1, \infty[$ with $\frac{1}{p} + \frac{1}{p^*} = 1$.

a) Show for $f \in W^{1,p}(\Omega)$, $g \in W^{1,p^*}(\Omega)$ and $i \in \{1, \ldots, d\}$ that

$$\int_{\Omega} f \partial^{e_i} g \, \mathrm{d}x = \int_{\partial\Omega} \gamma(g) \nu_i \gamma(f) \, \mathrm{d}s - \int_{\Omega} g \partial^{e_i} f \, \mathrm{d}x, \tag{3}$$

where ν_i is the *i* th component of ν .

b) Conclude for $f \in W^{2,p}(\Omega)$ and $g \in W^{1,p^*}(\Omega)$, that

$$\int_{\Omega} g\Delta f + \nabla g \cdot \nabla f \, \mathrm{d}x = \int_{\partial \Omega} g\gamma(\nabla f) \cdot \nu \, \mathrm{d}s.$$
(4)

Here $\gamma(\nabla f)$ is understood to be applied componentwise.

Hint. You may assume that (3) holds if $f, g \in C^{\infty}(\overline{\Omega})$.

Remark. These results are can be understood as generalizations of integration by parts, (4) is known as the Green identity. They find much application in the study of second order linear PDEs.

Example 3.3) [Decomposition of Lipschitz domains]

Let $\Omega \subset \mathbb{R}^d$ be a bounded Lipschitz domain and $\{\Omega_i\}_{i=1}^n$ a tuple of bounded Lipschitz domains such that $\overline{\Omega} = \bigcup_{i=1}^n \overline{\Omega}_i$, with $\Omega_i \cap \Omega_j = \emptyset$ if $i \neq j$.

- a) Show that for S almost every $x \in \bigcup_{i=1}^{n} \partial \Omega_i$, if $x \in \partial \Omega_{i_1} \cap \partial \Omega_{i_2}$ for $i_1 \neq i_2$, then $\nu_{\Omega_{i_1}}(x) = -\nu_{\Omega_{i_2}}(x)$ (the respective outer normal vectors). Conclude that S almost everywhere $x \notin \bigcup_{i \in \{1,...n\} \setminus \{i_1,i_2\}} \partial \Omega_i$, i.e., almost every point is in at most two boundaries.
- **b)** Conclude that a function $f \in \mathcal{C}(\overline{\Omega})$ with $f_{|\Omega_i|} \in \mathcal{C}^1(\overline{\Omega_i})$, is weakly differentiable and compute the derivative.

Hint. A sketch is certainly helpful, but also prove the result rigorously.

Remark. Such results are for example of relevance for numerical schemes regarding PDEs which consider smooth ansatz functions on suitable subsets (triangulation) and need to understand the corresponding Sobolev properties.

Example 3.4) [Functions with zero derivative are constant]

Let $\Omega \subset \mathbb{R}^d$ be a bounded domain (open and connected) with Lipschitz boundary. It is well known, that 'the function is constant' and ' $\nabla f = 0$ on Ω ' are equivalent when f is smooth. Show that this still holds when $f \in L^1(\Omega)$ and ∇ is the weak gradient.