INSTITUT FÜR MATHEMATIK UND



Optimierung I

Problem Sheet 10 Due date: 24. June 2014

Problem 10.1: [Finding a descent direction with Newton's method]

We consider a twice-differentiable function $f : \mathbb{R}^n \to \mathbb{R}$, with a continuous second-order derivative. At a given point $x \in \mathbb{R}^n$, if $\nabla^2 f(x)$ is invertible, Newton's method provides a direction $d \in \mathbb{R}^n$ which is such that:

$$\nabla f(x) + \nabla^2 f(x)d = 0. \tag{1}$$

We assume that $\nabla f(x) \neq 0$.

- i) Give an example where (1) has a solution which is not a descent direction.
- ii) Let us assume that $\nabla^2 f(x)$ is positive definite. Prove that d is a descent direction.
- iii) Now, we do not make any assumption on the positivity of $\nabla^2 f(x)$. For all C, we denote by d_C , if it exists, the solution to:

$$\nabla f(x) + (\nabla^2 f(x) + C \operatorname{Id}_n)d = 0.$$
⁽²⁾

Let ρ_{-} be the smallest eigenvalue of $\nabla^{2} f(x)$, prove that for all C with $C > -\rho_{-}$, (2) has a solution which is a descent direction.

iv) Prove that

$$d_C \xrightarrow[C \to \infty]{} 0 \quad \text{and} \quad \frac{d_C}{\|d_C\|} \xrightarrow[C \to \infty]{} -\frac{\nabla f(x)}{\|\nabla f(x)\|}.$$
 (3)

v) Consider the function $f(x_1, x_2) = x_1^2 - \frac{1}{2}x_2^2 + x_1 + x_2$ and the point $x = (0, 0)^{\top}$. Compute the solution to (1), prove that it is not a descent direction, compute the solution to (2) for any $C > -\rho_{-}$.

Problem 10.2: [Analysis of the order of convergence]

In this exercise, we analyse the convergence of Newton's method for a particular case (in dimension 1). Let f be defined by:

$$f(x) = -e^{-x^2},$$
 (4)

let us define:

$$d(x) = \frac{-f'(x)}{f''(x)}.$$
(5)

For a given $x_0 \in \mathbb{R}$, we define the sequence $(x_k)_k$ as follows: for all k,

$$x_{k+1} = x_k + d(x_k). (6)$$

Note that d(x) is not defined neither at $x = -\frac{1}{\sqrt{2}}$ nor at $x = -\frac{1}{\sqrt{2}}$. We say that the sequence $(x_k)_k$ is well-defined if for all $k, x_k \neq -\frac{1}{\sqrt{2}}$ and $x_k \neq \frac{1}{\sqrt{2}}$.

i) Draw a graph of f, draw the tangents at $x = \frac{1}{\sqrt{2}}$ and $x = -\frac{1}{\sqrt{2}}$.

- ii) Compute d(x), and motivate the definition of the sequence $(x_k)_k$.
- iii) Let us define $g(x) = \left|\frac{x+d(x)}{x}\right|$, for $|x| \neq \frac{1}{\sqrt{2}}$. Study the variation of g, and prove that for all x, if $|x| \leq \frac{1}{2}$, then g(x) < 1, and if $|x| \geq \frac{1}{\sqrt{2}}$, g(x) > 1.
- iv) Prove that if $x_0 > \frac{1}{\sqrt{2}}$, then $(x_k)_k$ is well-defined and $x_k \to +\infty$, and similarly, if $x_0 < -\frac{1}{\sqrt{2}}$, then $(x_k)_k$ is well-defined and $x_k \to -\infty$.
- v) Prove that if $|x_0| < \frac{1}{2}$, the sequence converges to 0. Compute the order of convergence (german: *Q-Konvergenzordnung*) and the associated factor.
- vi) Is the order of convergence the one that was expected from results of the lecture ?

Problem 10.3: [Cholesky decomposition]

For any positive definite symmetric matrix S in $\mathbb{R}^{n \times n}$, we call Cholesky decomposition the following decomposition:

$$S = LL^{\top},\tag{7}$$

where L is a lower triangular matrix of $\mathbb{R}^{n \times n}$ with strictly positive diagonal coefficients. The goal of this exercise is to prove the existence and the uniqueness of such a matrix L. The proof is a proof by induction of the dimension n.

- i) Consider the case n = 1.
- ii) Let $n \in \mathbb{N}$, let us assume to have proved the result for this dimension. Let S be a positive definite symmetric matrix of size n + 1, that we write as follows:

$$S = \begin{pmatrix} a & b^{\top} \\ b & \tilde{S} \end{pmatrix},\tag{8}$$

where $a \in \mathbb{R}, b \in \mathbb{R}^n, \tilde{S} \in \mathbb{R}^{n \times n}$. Let L be a lower triangular matrix of size n + 1, with

$$L = \begin{pmatrix} c & 0\\ d & \tilde{L} \end{pmatrix},\tag{9}$$

with $c \in \mathbb{R}$, $d \in \mathbb{R}^n$, $\tilde{L} \in \mathbb{R}^{n \times n}$ lower triangular. Prove that if $S = LL^{\top}$, then there is a unique possible choice for c and d, with c > 0.

iii) Let $\ell = \begin{pmatrix} c \\ d \end{pmatrix} \in \mathbb{R}^{n+1}$, compute the symmetric matrix $Q \in \mathbb{R}^{n \times n}$ which is such that:

$$S - \ell \ell^{\top} = \begin{pmatrix} 0 & 0 \\ 0 & Q \end{pmatrix}.$$
 (10)

- iv) Prove that Q is positive definite. To do so, you can prove that for all $x \in \mathbb{R}^n$, there exists $x_0 \in \mathbb{R}$ such that for $y = \begin{pmatrix} x_0 \\ x \end{pmatrix}$, $y^{\top}Sy = x^{\top}Qx$. Conclude.
- v) Using a Cholesky decomposition, solve the equation:

$$\begin{pmatrix} 10 & 5 & 4 \\ 5 & 25 & 20 \\ 4 & 20 & 26 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 8 \\ 30 \\ 64 \end{pmatrix}.$$
 (11)

Problem 10.4: [An optimal triangle]

In this problem, we compute the maximal area of a triangle ABC having its three vertices A, B, and C on the same circle. Without loss of generality, we can assume that the three vertices belong to the circle of radius 1 and center (0,0), and we can assume that A = (0,1), $B = (\cos(\theta_1), \sin(\theta_1))$, $C = (\cos(\theta_2), \sin(\theta_2))$, with θ_1 and θ_2 in $[0, 2\pi]$.

Denoting by \mathcal{A} the area of the triangle and by M the matrix of size 2 formed with the vectors ABand \overrightarrow{AC} , we recall the formula: $\mathcal{A} = \frac{1}{2} |\det(M)|$. Find the optimal triangles

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Problem 10.5: [Regularization]

Suppose we want to recover a signal $\hat{u} \in \mathbb{R}^n$ from a given a noise signal $u_0 = \hat{u} + \delta$, where $\delta \in \mathbb{R}^n$ is some (Gaussian) noise (see Figure 1). If we know that our original signal was approximately piecewise constant, a one approach to recover \hat{u} is to solve

$$\min_{u \in \mathbb{R}^n} F(u) \quad \text{with} \quad F(u) = \frac{1}{2} \|u - u_0\|_2^2 + \mu \|\nabla u\|_1 = \frac{1}{2} \sum_{i=1}^n (u_i - (u_0)_i)^2 + \mu \sum_{i=1}^n |(\nabla u)_i|$$

where

$$(\nabla u)_i = \begin{cases} u_{i+1} - u_i & \text{if } 1 \le i < n \\ 0 & \text{else} \end{cases}$$

denotes a discret gradient. Now the difficulty is that $|\cdot|$ is not differentiable at 0. One approach is to solve an approximate, regularized problem:

- i) Given a parameter $\epsilon > 0$, find an approximation $|\cdot|_{\epsilon} : \mathbb{R} \to \mathbb{R}_+$ of the absolute value $|\cdot|$ such that
 - $|\cdot|_{\epsilon}$ is convex and continuously differentiable
 - $\sup_{x \in \mathbb{R}} ||x|_{\epsilon} |x|| \to 0$ as $\epsilon \to 0$
 - There exists $R(\epsilon) > 0$ with $R(\epsilon) \to 0$ as $\epsilon \to 0$ and $|x|_{\epsilon} = |x|$ for all $|x| > R(\epsilon)$.
- ii) Use $|\cdot|_{\epsilon}$ to define an approximation $F_{\epsilon} \in C^1(\mathbb{R}^n, \mathbb{R})$ of F such that $||F_{\epsilon} F||_{\infty} \to 0$ as $\epsilon \to 0$ and calculate ∇F_{ϵ}
- iii) Ensure existence of a unique solution to $\min_u F(u)$ and $\min_u F_{\epsilon}(u)$.
- iv) Show that for any approximation as in 2), denoting u_{ϵ} the minimizer of F_{ϵ} , $u_{\epsilon} \to u^*$, u^* being the unique minimizer of F, in particular $F(u_{\epsilon}) \to F(u)$ as $\epsilon \to 0$.
- v)* Use your program of exercise 8.5 to solve the approximate problem. An example of noisy and true data is provided on the webpage. Try different values of μ and ϵ and bring pictures of your results to class (on USB). You can also generate your own data.

NOTE: v)* is an additional point, it is not necessary to cross the exercise. After completing i)-iv), we will as if one students wants to show v)* and give 2 extra points for the presentation.

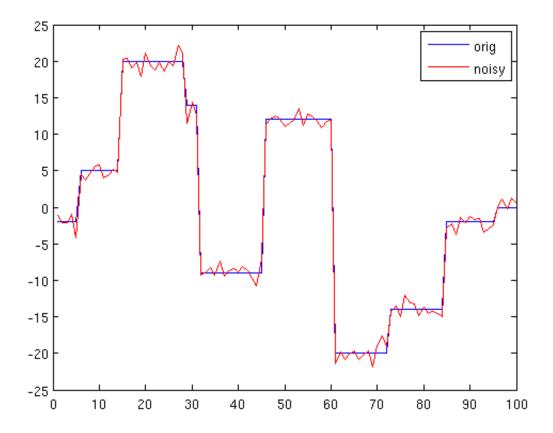


Abbildung 1: Example of original (blue) and noisy (red) data