

• Min - Max principle (for elliptic PDEs)

$$Lu = -\sum_{i,j} a_{ij} u_{x_i} u_{x_j} + \sum_i b_i u_{x_i} + c u$$

L is coercive

a, b, c functions of x

$\Rightarrow$ weak maximum principle

A) $c(x) = 0 \quad \forall x \in \Omega$

$$Lu \leq 0 \Rightarrow \max_{\bar{\Omega}} u = \max_{\partial\Omega} u$$

$$Lu \geq 0 \Rightarrow \min_{\bar{\Omega}} u = \min_{\partial\Omega} u$$

$$\Rightarrow Lu = 0 \Rightarrow \text{Min/Max of } u \text{ is on } \partial\Omega$$

B) $c(x) \geq 0 \quad \forall x \in \Omega$

$$Lu \leq 0 \Rightarrow \max_{\bar{\Omega}} u \leq \max_{\partial\Omega} u^+$$

$$Lu \geq 0 \Rightarrow \min_{\bar{\Omega}} u \geq -\max_{\partial\Omega} u^-$$

$$-u'' + pu' = 0$$

$\Rightarrow$ Minimum and Maximum of $u(x)$ are located on $\Gamma = \partial\Omega$

Matrices

[Meurant, p. 22ff, § 1.4]

- Matrix A is ^{generalized} strictly diagonally dominant if there exists a vector $d, d_i > 0$:

$$|a_{ii}| d_i \geq \sum_{\substack{j=1 \\ j \neq i}}^n |a_{ij}| d_j$$

strictly $\Leftrightarrow \exists i$ such that $>$ holds

- A is strictly diagonally dominant $\Rightarrow A$ is non-singular and $a_{ii} \neq 0 \forall i$.

- If $a_{ij} \geq 0$ then A is a strictly positive matrix denoted by $A \geq 0$

- A is monotone $\Leftrightarrow A$ is non-singular and $A^{-1} \geq 0$

$\uparrow$ discrete
Finite dimensional version of Maximum principle
($b \geq 0 \Rightarrow x \geq 0$ as solution of $Ax = b$)

- If we can write $A = cI - B$ with $c > 0$ and $B \geq 0$ such that $c(B) \leq c$

is named an M-matrix.

If A is non-singular then $c(B) < c$ holds.

Remark: $a_{ii} > 0 \forall i$ in an M-matrix

- A is a non-singular M-matrix

$\Leftrightarrow a_{ij} \leq 0 \forall i \neq j$ and A is strictly diagonally dominant

Remark: $a_{ii} \geq -\sum_{\substack{j=1 \\ j \neq i}}^n a_{ij} \forall i$ and $\exists i: a_{ii} > -\sum_{\substack{j=1 \\ j \neq i}}^n a_{ij}$

Min-Max principle in context of FEM

- $a(u, v)$ coercive $\Rightarrow$ Min/Max principle holds in weak formulation

- Galerkin approach

$$a(u_h, v_h) = \langle F, v_h \rangle$$

discretization



FEM isomorphism

$$\underline{K} \underline{u} = \underline{f}$$

$$V_h \subset H^1$$



$$\mathbb{R}^{N_h}$$

- ▶ discrete version of Min-Max principle has to be preserved by the FEM in matrix K
- ▶ Violation of the discrete maximum principle manifests itself in an unphysical discrete solution

► Condition of stiffness matrix

$$\kappa(K) \leq \frac{\lambda_{\max}(K)}{\lambda_{\min}(K)} \leq \frac{\mu_2}{\mu_1}$$

► finite support of basis functions and test functions
→ sparse matrix K (sparsity pattern)

Storage schemes for K :

e.g.: CRS compressed row storage