

Solution of the Time-dependent Schrödinger Equation using the Crank-Nicolson algorithm with MPI on a 2-D regular Cartesian grid

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Time-dependent Schrödinger Equation

Schrödinger Equation in 2-D for an electron in a given potential

$$i\hbar \frac{\partial}{\partial t} |\psi(t, \mathbf{x})\rangle = \hat{H}(\hat{\mathbf{p}}, \hat{\mathbf{x}}) |\psi(t, \mathbf{x})\rangle, \quad \hat{H} = \frac{\hat{p}_x^2}{2m} + \frac{\hat{p}_y^2}{2m} + \hat{V}(x, y) \quad (1)$$

Attempt to simply discretize the differential operators,

$$\partial_t \psi(t, \mathbf{x}) \approx \frac{\psi_{j,l}^{n+1} - \psi_{j,l}^n}{\Delta t},$$

$$\frac{\hat{p}^2}{2m} \psi(t, \mathbf{x}) = -\frac{\hbar^2}{2m} \nabla^2 \psi(t, \mathbf{x}) \approx -\frac{\hbar^2}{2m} \frac{\psi_{j+1,l}^{n+1} - 2\psi_{j,l}^{n+1} + \psi_{j-1,l}^{n+1}}{(\Delta x)^2} + \dots$$

is – as the von Neumann stability analysis shows – unconditionally stable. However, each solution of Schrödinger's equation has to fulfill a continuity equation for the probability $w(t, \mathbf{x}) d^3x = \psi^* \psi d^3x$ to find the electron within a volume d^3x around \mathbf{x} ,

$$\partial_t w(t, \mathbf{x}) + \nabla \cdot \mathbf{j} = 0, \quad \mathbf{j} = \frac{\hbar}{2im} [\psi^* (\nabla \psi) - (\nabla \psi^*) \psi] \quad (2)$$

From the continuity equation follows the conservation of the norm of the wave function:

$$\begin{aligned} \frac{d}{dt} \int d^3x w(t, \mathbf{x}) &= \int d^3x \partial_t w(t, \mathbf{x}) = - \int d^3x \nabla \cdot \mathbf{j}(t, \mathbf{x}) = - \int d\mathbf{S} \cdot \mathbf{j}(t, \mathbf{x}) \\ \int_{\mathbb{R}^3} d^3x \|w(0, \mathbf{x})\|^2 &\stackrel{\text{SE}}{\rightarrow} \int_{\mathbb{R}^3} d^3x \|w(t, \mathbf{x})\|^2 = 1 \end{aligned} \quad (3)$$

The normalization of the wave function $\psi(t, \mathbf{x})$ is however not conserved by the fully implicit discretization as this method is not unitary \Rightarrow a discretization preserving the hermiticity of the Hamiltonian is needed that maintains the normalization of the wavefunction.

The temporal evolution of the wave function can be expressed using the unitary time-evolution operator $\hat{U}(t)$:

$$|\psi(t + \Delta t, \mathbf{x})\rangle \simeq \hat{U}(t) |\psi(t, \mathbf{x})\rangle, \quad \hat{U}(t) = \exp(-i\hat{H}t/\hbar) \quad (4)$$

With the time-evolution operator one can find the explicit Forward-Time Centered-Space (FTCS) scheme $\psi_{j,l}^{n+1} = (1 - i\hat{H}\Delta t)\psi_{j,l}^n$ and the implicit Backward-Time scheme $(1 + i\hat{H}\Delta t)\psi_{j,l}^{n+1} = \psi_{j,l}^n$. Neither scheme is unitary and thus violates probability conservation.

A finite-difference approximation of $\exp(-i\hat{H}\Delta t/\hbar)$ that is unitary was found by Cayley:

$$\exp(-i\hat{H}\Delta t/\hbar) = \frac{1 - \frac{i\hat{H}\Delta t}{2\hbar}}{1 + \frac{i\hat{H}\Delta t}{2\hbar}} + \mathcal{O}((\Delta t)^2)$$

$$(4) \Rightarrow \left(1 + \frac{i}{2\hbar}\hat{H}\Delta t\right) |\psi(t + \Delta t, \mathbf{x})\rangle = \left(1 - \frac{i}{2\hbar}\hat{H}\Delta t\right) |\psi(t, \mathbf{x})\rangle \quad (5)$$

This is exactly the Crank-Nicolson scheme for the Schrödinger equation.

Discretization

By substituting the 2-D discrete wave function $\psi(t; x, y) \rightarrow \psi_{j,l}^n$ into Eq. (5) and considering the Hamiltonian in the form

$$\hat{H} = |\hat{\mathbf{p}} = -i\hbar\nabla| = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} - \frac{\hbar^2}{2m} \frac{\partial^2}{\partial y^2} + \hat{V}(x, y)$$

one obtains the discretized 2-D Schrödinger Equation

$$\begin{aligned} \psi_{j,l}^{n+1} - \frac{i\Delta t}{2\hbar} \left(\frac{\hbar^2}{2m} \frac{\psi_{j+1,l}^{n+1} - 2\psi_{j,l}^{n+1} + \psi_{j-1,l}^{n+1}}{(\Delta x)^2} + \frac{\psi_{j,l+1}^{n+1} - 2\psi_{j,l}^{n+1} + \psi_{j,l-1}^{n+1}}{(\Delta y)^2} - V_{j,l} \psi_{j,l}^{n+1} \right) \\ = \psi_{j,l}^n + \frac{i\Delta t}{2\hbar} \left(\frac{\hbar^2}{2m} \frac{\psi_{j+1,l}^n - 2\psi_{j,l}^n + \psi_{j-1,l}^n}{(\Delta x)^2} + \frac{\hbar^2}{2m} \frac{\psi_{j,l+1}^n - 2\psi_{j,l}^n + \psi_{j,l-1}^n}{(\Delta y)^2} - V_{j,l} \psi_{j,l}^n \right) \quad (6) \end{aligned}$$

Rewrite Eq. (6) in matrix-form. Assign a short-hand notation for the prefactors of the wave function at the next time step at various spatial grid points:

$$\psi_{j,l}^{n+1} : \quad b_{j,l} = 1 + \frac{i\Delta t}{\hbar} \frac{\hbar^2}{2m} \left(\frac{1}{(\Delta x)^2} + \frac{1}{(\Delta y)^2} \right) + \frac{i\Delta t}{2\hbar} V_{j,l}$$

$$\psi_{j-1,l}^{n+1} : \quad c = -\frac{i\Delta t}{2\hbar} \frac{\hbar^2}{2m} \frac{1}{(\Delta x)^2}$$

$$\psi_{j+1,l}^{n+1} : \quad a = c$$

$$\psi_{j,l+1}^{n+1} : \quad d = -\frac{i\Delta t}{2\hbar} \frac{\hbar^2}{2m} \frac{1}{(\Delta x)^2}$$

$$\psi_{j,l-1}^{n+1} : \quad e = d$$

and for the RHS:

$$\psi_{j,l}^n : \quad f_{j,l} = 1 - \frac{i\Delta t}{\hbar} \frac{\hbar^2}{2m} \left(\frac{1}{(\Delta x)^2} + \frac{1}{(\Delta y)^2} \right) - \frac{i\Delta t}{2\hbar} V_{j,l}$$

$$\psi_{j+1,l}^n : \quad g = \frac{i\Delta t}{2\hbar} \frac{\hbar^2}{2m} \frac{1}{(\Delta x)^2}$$

$$\psi_{j-1,l}^n : \quad h = g$$

$$\psi_{j,l+1}^n : \quad k = \frac{i\Delta t}{2\hbar} \frac{\hbar^2}{2m} \frac{1}{(\Delta y)^2}$$

$$\psi_{j,l-1}^n : \quad p = k$$

LHS of the discretized Schrödinger Equation

Map the two indices j and l of the wave function $\psi_{j,l}^n$ on a single one $(j, l) \mapsto i$:

$$i = 1 + (j - 1)(L - 1) + l - 1 \quad \text{for } j = 0, 1, \dots, J; l = 0, 1, \dots, L$$

Thereby $\psi_{1,1}^n \rightarrow \psi_1^n, \psi_{1,2}^n \rightarrow \psi_2^n, \dots, \psi_{1,J}^n \rightarrow \psi_J^n, \psi_{2,1}^n \rightarrow \psi_{J+1}^n, \dots$. For simplicity (and lack of space) shown here only for $J = L = 4$, though later $J, L \sim 10^3$ will be used. It exhibits sub-blocks of shape $J \times L$:

$$\begin{pmatrix} b_{1,1} & d & 0 & a & 0 & 0 & 0 & 0 & 0 \\ e & b_{1,2} & d & 0 & a & 0 & 0 & 0 & 0 \\ 0 & e & b_{1,3} & 0 & 0 & a & 0 & 0 & 0 \\ c & 0 & 0 & b_{2,1} & d & 0 & a & 0 & 0 \\ 0 & c & 0 & e & b_{2,2} & d & 0 & a & 0 \\ 0 & 0 & c & 0 & e & b_{2,3} & 0 & 0 & a \\ 0 & 0 & 0 & c & 0 & 0 & b_{3,1} & d & 0 \\ 0 & 0 & 0 & 0 & c & 0 & e & b_{3,2} & d \\ 0 & 0 & 0 & 0 & 0 & c & 0 & e & b_{3,3} \end{pmatrix} \begin{pmatrix} \psi_1^{n+1} \\ \psi_2^{n+1} \\ \psi_3^{n+1} \\ \psi_4^{n+1} \\ \psi_5^{n+1} \\ \psi_6^{n+1} \\ \psi_7^{n+1} \\ \psi_8^{n+1} \\ \psi_9^{n+1} \end{pmatrix} = \mathbf{r}$$

RHS of the discretized Schrödinger Equation

Vectorization of the RHS is not necessary when working with Fortran exclusively but essential when using the `numpy` module with Python:

$$\mathbf{r} = \begin{pmatrix} f_{1,1} & k & 0 & g & 0 & 0 & 0 & 0 & 0 \\ p & f_{1,2} & k & 0 & g & 0 & 0 & 0 & 0 \\ 0 & p & f_{1,3} & 0 & 0 & g & 0 & 0 & 0 \\ h & 0 & 0 & f_{2,1} & k & 0 & g & 0 & 0 \\ 0 & h & 0 & p & f_{2,2} & k & 0 & g & 0 \\ 0 & 0 & h & 0 & p & f_{2,3} & 0 & 0 & g \\ 0 & 0 & 0 & h & 0 & 0 & f_{3,1} & k & 0 \\ 0 & 0 & 0 & 0 & h & 0 & p & f_{3,2} & k \\ 0 & 0 & 0 & 0 & 0 & h & 0 & p & f_{3,3} \end{pmatrix} \begin{pmatrix} \psi_1^n \\ \psi_2^n \\ \psi_3^n \\ \psi_4^n \\ \psi_5^n \\ \psi_6^n \\ \psi_7^n \\ \psi_8^n \\ \psi_9^n \end{pmatrix}$$

After vectorization, the discretized Schrödinger Equation simplifies to

$$\hat{A}\psi^{n+1} = \mathbf{r} = \hat{B}\psi^n$$

Pseudo-code:

for n in range(N):

- Compute $\hat{B}\psi^n = \mathbf{r}$ as a matrix-vector product
- Solve $\hat{A}\psi^{n+1} = \mathbf{r}$ with LU decomposition
- This yields ψ^{n+1}
- Map the rolling index i back to indices j, l : $\psi_i^{n+1} \rightarrow \psi_{j,l}^{n+1}$
- Check that the wave packet remains normalized:

$$\int_{\Delta^2} d^2x \|\psi(t, \mathbf{x})\|^2 \approx \sum_{j,l=1}^{J,L} \Delta x \Delta y \|\psi_{j,l}^n\|^2 \stackrel{!}{=} 1$$

Setting up the matrices in Python

```
# Build the main diagonal
b_main_diag = [] # coefficient matrix of LHS
f_main_diag = [] # coefficient matrix of RHS
for j in range(J-1):
    for l in range(J-1):
        b_main_diag.append(b[j,l]); f_main_diag.append(f[j,l])

e_minor_diag = np.ones((len(b_main_diag)-1), dtype=complex)*e
d_minor_diag = np.ones((len(b_main_diag)-1), dtype=complex)*d
a_minor_diag = np.ones((len(b_main_diag)-3), dtype=complex)*a
c_minor_diag = np.ones((len(b_main_diag)-3), dtype=complex)*c
k_minor_diag = np.ones((len(f_main_diag)-1), dtype=complex)*k
p_minor_diag = np.ones((len(f_main_diag)-1), dtype=complex)*p
g_minor_diag = np.ones((len(f_main_diag)-3), dtype=complex)*g
h_minor_diag = np.ones((len(f_main_diag)-3), dtype=complex)*h

# Build the coefficient matrices for  $A\psi^{(n+1)} = B\psi^{(n)}$ 
A = np.diag(b_main_diag) + np.diag(e_minor_diag,-1) + np.diag(d_minor_diag,1) \
    + np.diag(c_minor_diag,-3) + np.diag(a_minor_diag,3)
B = np.diag(f_main_diag) + np.diag(p_minor_diag,-1) + np.diag(k_minor_diag,1) \
    + np.diag(h_minor_diag,-3) + np.diag(g_minor_diag,3)
```

Setting-up the RHS in Python

```
for n in range(Nt):
    if n == 0:
        psi_n_mat = psi_0
        # Rewrite matrix psi_jl as a vector psi_i
        psi_n_vec = np.empty(((J-1)**2,), dtype=complex)
        for j in range(J-1):
            for l in range(J-1):
                i = ind(j,l)
                psi_n_vec[i] = psi_n_mat[j,l]
    else:
        psi_n_vec = psi_np1_vec

RHS = np.dot(B,psi_n_vec)
r = RHS
```

LU decomposition; finally to be parallelized as Fortran code

```
# LU decomposition:
P, L, U = scipy.linalg.lu(A)
LU = L + U
nA = np.size(A, 0)
y = np.zeros((nA,), dtype=complex)
x = np.zeros((nA,), dtype=complex)

r = np.dot(np.linalg.inv(P),r)

for i in range(1, nA+1):
    s = r[i-1]
    for j in range(1, i):
        s = s - LU[i-1,j-1]*y[j-1]
    y[i-1] = s

for i in range(nA, 0, -1):
    s = y[i-1]
    for j in range(i+1, nA+1):
        s = s - LU[i-1,j-1]*x[j-1]
    x[i-1] = s/LU[i-1,i-1]

psi_np1_vec = x
```

Parallelizing the code

The following strategies for code parallelization systems are envisaged:

- Application of Distributed SuperLU (SuperLU_DIST) of the SuperLU library
- Crank-Nicolson predictor-corrector (CNPC) method
 - Decomposition of spatial domain Ω in subdomains Ω_i which can be assigned to their own processor
 - Forward Euler to predict unknown values on the interface Γ between subdomains $\Omega_i \subset \Omega$
 - Solving the problem independently on the subdomains Ω_i with Backward Euler using the predicted values ψ_Γ^* at t_{n+1}
 - Correction of interface values ψ_Γ^{n+1} with Backward Euler using interior values