

# Approximate Polynomial Greatest Common Divisor

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- in practical problems inexact polynomials are considered, and their inexact feature implies they are, with high probability, coprime. Hence, they must be perturbed slightly in order to induce a non-constant GCD, and this GCD is called **an approximate greatest common divisor (AGCD)**.
- numerically, an AGCD can be computed from Sylvester matrices:

Let

$$\hat{f}(x) = \sum_{i=0}^m \hat{a}_i x^{m-i} \quad (\hat{a}_0 \hat{a}_m \neq 0) \quad \text{and} \quad \hat{g}(x) = \sum_{j=0}^n \hat{b}_j x^{n-j} \quad (\hat{b}_0 \hat{b}_n \neq 0)$$

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Then there exist polynomials  $u$  and  $v$  of degrees  $m - k$  and  $n - k$ , respectively, so that

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This equations can be written in the matrix-vector notation as

$$S_k(\hat{f}, \hat{g}) \begin{bmatrix} \mathbf{v} \\ -\mathbf{u} \end{bmatrix} = \mathbf{0}$$

where  $\mathbf{u}$  denotes the vector of coefficients of  $u$ .

The matrix  $S_k = S_k(\hat{f}, \hat{g})$  is the  $k$ th Sylvester subresultant matrix,

$$S_k = \begin{bmatrix} \hat{a}_0 & & & & \hat{b}_0 & & & & \\ \hat{a}_1 & \hat{a}_0 & & & \hat{b}_1 & \hat{b}_0 & & & \\ \vdots & \hat{a}_1 & \ddots & & \vdots & \hat{b}_1 & \ddots & & \\ \hat{a}_m & \vdots & \ddots & \hat{a}_0 & \hat{b}_n & \vdots & \ddots & \hat{b}_0 & \\ & \hat{a}_m & & \hat{a}_1 & & \hat{b}_n & & \hat{b}_1 & \\ & & \ddots & \vdots & & & \ddots & \vdots & \\ & & & \hat{a}_m & & & & \hat{b}_n & \end{bmatrix} \in \mathbb{R}^{(m+n-k+1) \times (m+n-2k+2)}.$$

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The Sylvester matrix is the matrix  $S = S_1 = \left[ C_n(\hat{f}), C_m(\hat{g}) \right] \in \mathbb{R}^{(m+n) \times (m+n)}$ .

The following statements hold:

- i)  $\text{rank}(S(\hat{f}, \hat{g})) = m + n - k \iff \text{deg } \hat{h} = k,$
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- SVD strategies by Bini and Boito, Corless, Tragger, Watt, Emiris, Zeng, ... (methods do not work well for inexact polynomials),
- TLS strategies by Winkler, Kaltofen, Zítko.

## Inexact polynomials:

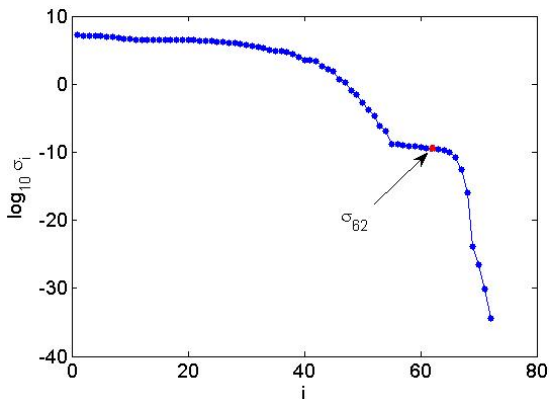
Assume that

$$\hat{f}(x) = \sum_{i=0}^m \hat{a}_i x^{m-i} \quad \text{and} \quad \hat{g}(x) = \sum_{j=0}^n \hat{b}_j x^{n-j}$$

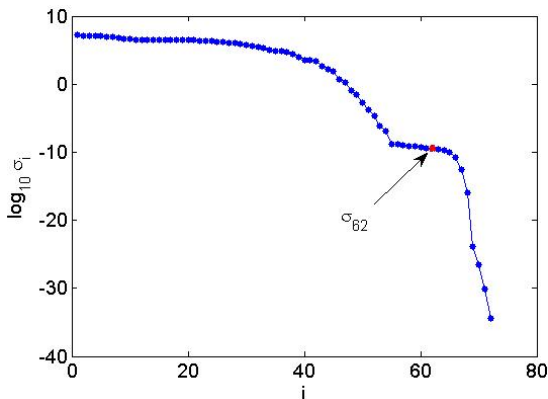
are exact polynomial. **Componentwise** perturbation, in particular

$$\begin{aligned} a_i &= \hat{a}_i + \epsilon \hat{a}_i c_i, \quad i = 0, \dots, m \\ b_i &= \hat{b}_i + \epsilon \hat{b}_i d_i, \quad i = 0, \dots, n, \end{aligned} \tag{1}$$

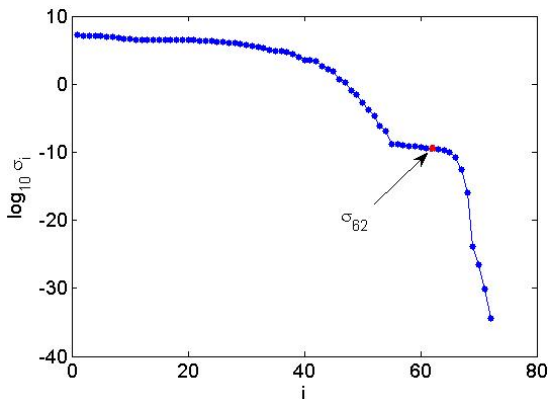
yields the inexact polynomials  $f$  and  $g$ , where  $c_i$  and  $d_i$  are random numbers in  $[-1, 1]$  and  $\text{SNR} = \frac{1}{\epsilon}$  is the signal-to-noise ratio.



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Golub and Van Loan recommend to use  $\theta = \varepsilon_{\text{mach}} \|S\| \approx 1.1 \times 10^{-9}$  that returns  $r = 57$  and the numerical-rank gap criterion gives  $r = 68$  that are incorrect results.

The system

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# TLS formulation

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$$S_k(\hat{f}, \hat{g}) \begin{bmatrix} \mathbf{v} \\ -\mathbf{u} \end{bmatrix} = \mathbf{0} \implies A_k \mathbf{x} = \mathbf{c}_k$$

where  $\mathbf{c}_k$  is the first column of  $S_k$  and  $A_k$  is formed from the remaining  $m + n - 2k + 1$  columns of  $S_k$ ,  $S_k = [\mathbf{c}_k, A_k]$ .

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However, if the polynomials  $f$  and  $g$  are coprime, we can demand to compute the minimal corrections  $\delta f$  and  $\delta g$  of  $f$  and  $g$  so that  $f + \delta f$  and  $g + \delta g$  have a non-trivial GCD with the highest possible degree. Then, we set

$$\text{AGCD}(f, g) = \text{GCD}(f + \delta f, g + \delta g).$$

Let  $\delta S_k = \delta S_k(\delta f, \delta g)$  be the Sylvester matrix of  $\delta f$  and  $\delta g$ ,  $\delta S_k = [\mathbf{h}_k, E_k]$ , and let  $\mathbf{z} = [\delta \mathbf{f}^T, \delta \mathbf{g}^T]^T$  be the vector of the coefficients of  $\delta f$  and  $\delta g$ .

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Methods:

- Structured Total Least Norm (STLN) of Park and Glick – for AGCD customized by Kaltofen; non-linear extension (SNTLN) is given by Winkler,
- Lagrange-Newton Structured TLS (LN-STLS) of Huffel.

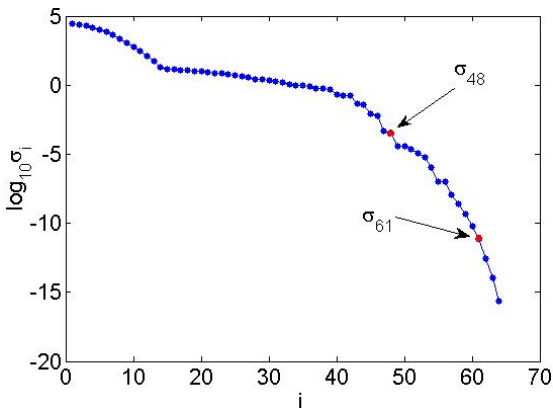


**Exmple.** Consider the polynomials  $\hat{f}$  and  $\hat{g}$  of degree 32,

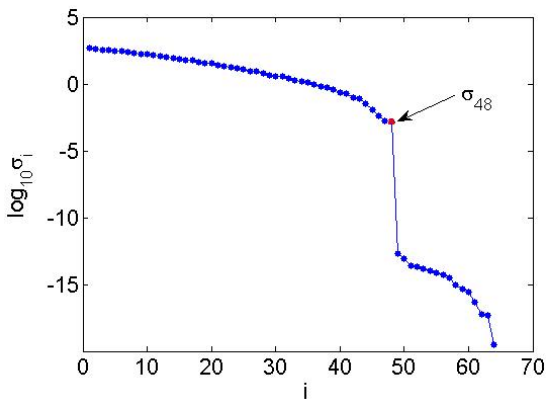
$$\hat{f}(x) = \prod_{i=1}^8 [(x - r_1 \alpha_i)^2 + r_1^2 \beta_i^2] \prod_{i=9}^{16} [(x - r_2 \alpha_i)^2 + r_2^2 \beta_i^2],$$
$$\hat{g}(x) = \prod_{i=1}^{16} [(x - r_1 \alpha_i)^2 + r_1^2 \beta_i^2],$$

where  $\alpha_i = \cos\left(\frac{\pi i}{m}\right)$ ,  $\beta_i = \sin\left(\frac{\pi i}{m}\right)$ ,  $i = 1, \dots, n$ ,  $r_1 = 0.5$  and  $r_2 = 1.5$ . These polynomials have the exact GCD of degree 16. So the rank of the Sylvester matrix  $S(f, g)$  is 48.

Suppose that a noise of the signal-to-noise ratio  $\text{SNR} = 10^8$  is componentwisely imposed to the coefficients of  $\hat{f}$  and  $\hat{g}$ , thereby yielding the inexact polynomials  $f$  and  $g$ .



Singular values of the Sylvester matrix  $S(f, g)$ . For the threshold  $\theta = \varepsilon_{mach} \|S\| \approx 10^{-12}$  the numerical rank is 61 that is incorrect. The correct numerical rank 48 can be revealed with  $\theta \approx 10^{-4}$ .









Singular values of  $S(f, g) + \delta S(\delta f, \delta g)$  where  $\delta f$  and  $\delta g$  are obtained from the TLS problem solved by the LN-SLTS method.

## Thesis review:

- sensitivity of the AGCD problem on noise,
- formulation of the AGCD problem as the structured TLS problem,
- overview of the methods for solving STLS (STLN and LN-STLS),
- modification of the Winkler's SNTLN method that is in a column pivoting in choosing a “better” TLS problem (a new contribution of the thesis),
- application of LN-STLS method on the AGCD problem (a new contribution of the thesis),
- developing a non-linear extension of the LN-STLS method (a new contribution of the thesis).

**Thank you for you attention!**

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