

A primal-dual extragradient method for nonlinear inverse problems for PDEs

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Motivation

Primal-dual extragradient method:

- first-order algorithm for nonsmooth convex problems with linear operators [Chambolle/Pock 2011]
- very popular in imaging (TV denoising, deblurring, ...)
- acceleration (Nesterov, $\mathcal{O}(1/k^2)$ convergence)
- version for nonlinear operators [Valkonen 2014]

Here:

- application to parameter identification for PDEs
- \rightsquigarrow function space algorithm

Difficulty:

- convergence proof requires set-valued analysis in infinite-dimensional spaces

Model problems

L¹-fitting

$$\min_u \|S(u) - y^\delta\|_{L^1} + \frac{\alpha}{2} \|u\|_{L^2}^2$$

L[∞]-fitting

$$\min_u \frac{1}{2} \|u\|_{L^2}^2 \quad \text{s. t.} \quad |S(u)(x) - y^\delta(x)| \leq \delta \quad \text{a. e. in } \Omega$$

$S : U \subset L^2(\Omega) \rightarrow L^2(\Omega)$, $S(u) =: y$ satisfies

$$\begin{cases} -\Delta y + uy = f \\ \partial_\nu y = 0 \end{cases}$$

1 Overview

2 Algorithm

3 Set-valued analysis

- Metric regularity
- Pointwise subderivatives
- Stability of saddle points

4 Application to parameter identification

- L^1 fitting
- L^∞ fitting

5 Numerical examples

Problem statement

$$\min_{u \in X} F(K(u)) + G(u)$$

- $F : Y \rightarrow \overline{\mathbb{R}}$, $G : X \rightarrow \overline{\mathbb{R}}$ convex, lower semicontinuous
- X, Y Hilbert spaces
- $K \in C^2(X, Y)$ (here: $K(u) = S(u) - y^\delta$ or $K(u) = S(u)$)
- saddle point formulation:

$$\min_{u \in X} \sup_{v \in Y^*} G(u) + \langle K(u), v \rangle - F^*(v)$$

- $F^* : Y^* \rightarrow \overline{\mathbb{R}}$ Fenchel conjugate

Algorithm

K linear:

$$\begin{cases} u^{k+1} = \text{prox}_{\tau G}(u^k - \tau K^* v^k) \\ \bar{u}^{k+1} = 2u^{k+1} - u^k \\ v^{k+1} = \text{prox}_{\sigma F^*}(v^k + \sigma K \bar{u}^{k+1}) \end{cases}$$

- σ, τ step sizes, $\sigma\tau < \|K\|^{-2}$
- $\text{prox}_{\sigma F}(v) = \arg \min_u \frac{1}{2\sigma} \|u - v\|^2 + F(u)$ proximal mapping

Algorithm

K nonlinear:

$$\begin{cases} u^{k+1} = \text{prox}_{\tau G}(u^k - \tau K'(u^k)^* v^k) \\ \bar{u}^{k+1} = 2u^{k+1} - u^k \\ v^{k+1} = \text{prox}_{\sigma F^*}(v^k + \sigma K(\bar{u}^{k+1})) \end{cases}$$

- σ, τ step sizes, $\sigma\tau < \sup_{u \in B_R} \|K'(u)\|^{-2}$
- $\text{prox}_{\sigma F}(v) = \arg \min_u \frac{1}{2\sigma} \|u - v\|^2 + F(u)$ proximal mapping
- $K'(u)$ Fréchet derivative, $K'(u)^*$ adjoint

Algorithm

K nonlinear, accelerated:

$$\begin{cases} u^{k+1} = \text{prox}_{\tau_k G}(u^k - \tau^k K'(u^k)^* v^k) \\ \omega_k = 1/\sqrt{1 + 2c\tau^k} \quad \tau^{k+1} = \omega_k \tau^k \quad \sigma_{k+1} = \sigma_k / \omega_k \\ \bar{u}^{k+1} = u^{k+1} + \omega_k(u^{k+1} - u^k) \\ v^{k+1} = \text{prox}_{\sigma_{k+1} F^*}(v^k + \sigma_{k+1} K(\bar{u}^{k+1})) \end{cases}$$

- σ, τ step sizes, $\sigma_0 \tau_0 < \sup_{u \in B_R} \|K'(u)\|^{-2}$
- $\text{prox}_{\sigma F}(v) = \arg \min_u \frac{1}{2\sigma} \|u - v\|^2 + F(u)$ proximal mapping
- $K'(u)$ Fréchet derivative, $K'(u)^*$ adjoint
- $c \geq 0$ acceleration parameter

Convergence

Theorem

Iterates converge locally to saddle point (\bar{u}, \bar{v}) if

- 1 G is c_G -strongly convex (here: $c_G = 1$)
- 2 $c = c_n \in [0, c_G]$, $c_n = 0$ for $n > N \in \mathbb{N}$ (finite acceleration)
- 3 metric regularity around saddle point

(cf. [Valkonen 2014])

Difficulty:

- metric regularity in function spaces
- \leadsto requires infinite-dimensional set-valued analysis
- here: only rough outline, no details

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Metric regularity

Saddle-point problem

$$\min_{u \in X} \sup_{v \in Y^*} G(u) + \langle K(u), v \rangle - F^*(v)$$

Primal-dual optimality conditions

$$\begin{cases} K(\bar{u}) \in \partial F^*(\bar{v}) \\ -K'(\bar{u})^* \bar{v} \in \partial G(\bar{u}) \end{cases}$$

Metric regularity

Primal-dual optimality conditions

$$\begin{cases} K(\bar{u}) \in \partial F^*(\bar{v}) \\ -K'(\bar{u})^* \bar{v} \in \partial G(\bar{u}) \end{cases}$$

Set inclusion for $H : L^2(\Omega)^2 \rightrightarrows L^2(\Omega)^2$

$$0 \in H_{\bar{u}}(\bar{u}, \bar{v}) := \begin{pmatrix} \partial G(\bar{u}) + K'(\bar{u})^* \bar{v} \\ \partial F^*(\bar{v}) - K(\bar{u}) \end{pmatrix}$$

Metric regularity

Set inclusion for $H : L^2(\Omega)^2 \rightrightarrows L^2(\Omega)^2$

$$0 \in H_{\bar{u}}(\bar{u}, \bar{v}) := \begin{pmatrix} \partial G(\bar{u}) + K'(\bar{u})^* \bar{v} \\ \partial F^*(\bar{v}) - K(\bar{u}) \end{pmatrix}$$

Metric regularity at (\bar{u}, \bar{v})

$$\inf_{q: w \in H_{\bar{u}}(q)} \|q - (\bar{u}, \bar{v})\| \leq L\|w\| \quad \text{for all } \|w\| \leq \rho$$

- interpretation: small perturbation w of 0
 \Rightarrow small perturbation q of saddle point (\bar{u}, \bar{v})
- Lipschitz property for set-valued $H_{\bar{u}}^{-1}$ at $((\bar{u}, \bar{v}), 0)$

Metric regularity

Metric regularity at (\bar{u}, \bar{v})

$$\inf_{q: w \in H_{\bar{u}}(q)} \|q - (\bar{u}, \bar{v})\| \leq L\|w\| \quad \text{for all } \|w\| \leq \rho$$

Mordukhovich criterion

$$L_R = \inf_{t>0} \sup \left\{ \|\widehat{D}^* R(q' | w')\| \mid q' \in B((\bar{u}, \bar{v}), t), w' \in R(q') \cap B(w, t) \right\}$$

- Aubin constant $L_{H^{-1}}$ is minimal choice of L
- $\widehat{D}^* R$ regular coderivative of $R (= H^{-1})$ (cf. $L = \|\nabla f\|$ for $f \in C^1$)
- \rightsquigarrow set-valued analysis in function spaces

Difficulties:

- multiple non-equivalent concepts (regular, limiting)
- calculus not tight

Here:

- set-valued mappings from subdifferentials of pointwise functionals
- \rightsquigarrow infinite-dimensional (regular) derivatives pointwise via nice finite-dimensional (regular, graphical) derivatives
- cf. pointwise Fenchel conjugates, subdifferentials [Ekeland]

Q, W Hilbert space, $R : Q \rightrightarrows W$

Regular coderivative

$$\widehat{D}^*R(q|w)(\Delta w) = \left\{ \Delta q \in Q \mid (\Delta q, -\Delta w) \in \widehat{N}((q, w); \text{Graph } R) \right\}$$

Graphical derivative

$$DR(q|w)(\Delta q) = \left\{ \Delta w \in W \mid (\Delta q, \Delta w) \in T((q, w); \text{Graph } R) \right\}$$

- $\widehat{N}(u; U)$ regular normal cone to $U \subset X$
- $T(u; U)$ tangent cone to $U \subset X$

Derivatives of set-valued mappings

For Q, W finite-dimensional:

$$\widehat{D}^* R(q|w)(\Delta w) = [DR(q|w)]^{*+} = [\widetilde{DR}(q|w)]^{*+}$$

- upper adjoint

$$J^{*+}(\Delta w) = \left\{ \Delta q \in Q \mid \langle \Delta q, \Delta q' \rangle \leqslant \langle \Delta w, \Delta w' \rangle \text{ for } \Delta w' \in J(\Delta q') \right\}$$

- convexification

$$\text{Graph } \widetilde{DR}(q|w) = \text{conv Graph}[DR(q|w)]$$

- (A linear operator: $DA = \widetilde{D}A = A, \quad \widehat{D}^*A = A^*$)

Pointwise characterization

Assume $g : \Omega \times \mathbb{R}^m \rightarrow \overline{\mathbb{R}}$ normal, proper, convex,
proto-differentiable a.e.,

$$G : L^2(\Omega) \rightarrow \overline{\mathbb{R}} \quad G(u) = \int_{\Omega} g(x, u(x)) dx$$

Then:

$$\widehat{D}^*[\partial G](u|\xi)(\Delta\xi) = \left\{ \Delta u \in L^2(\Omega; \mathbb{R}^m) \mid \Delta u(x) \in \widehat{D}^*[\partial g(x, \cdot)](u(x)|\xi(x))(\Delta\xi(x)) \right\}$$

$$D[\partial G](u|\xi)(\Delta u) = \left\{ \Delta \xi \in L^2(\Omega; \mathbb{R}^m) \mid \Delta \xi(x) \in D[\partial g(x, \cdot)](u(x)|\xi(x))(\Delta u(x)) \right\}$$

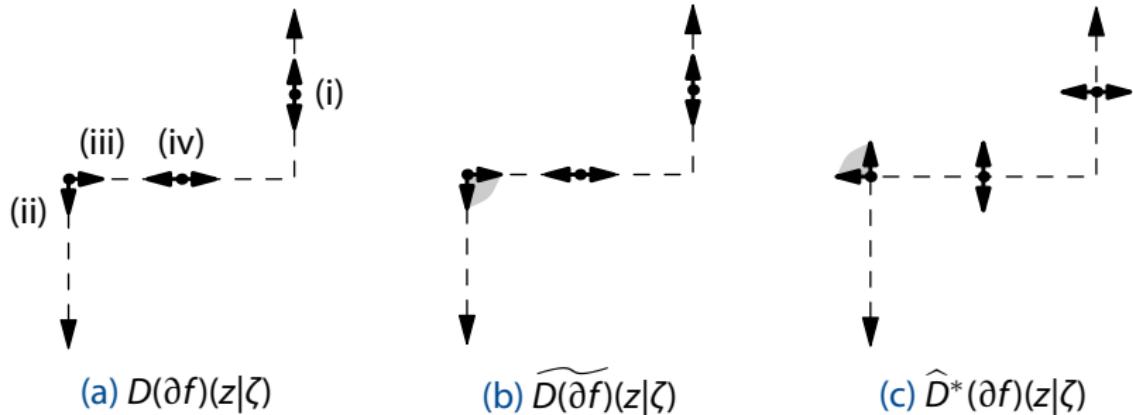
$$\widehat{D}^*[\partial G](u|\xi) = [D[\partial G](u|\xi)]^{*+} = \widetilde{[D[\partial G](u|\xi)]^{*+}}$$

Examples: L¹ fitting

$$\min_u \|S(u) - y^\delta\|_{L^1} + \frac{\alpha}{2} \|u\|_{L^2}^2$$

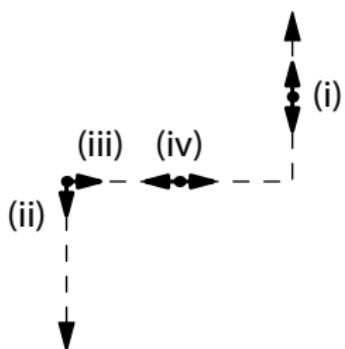
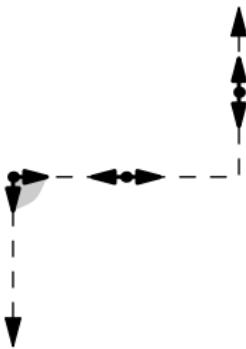
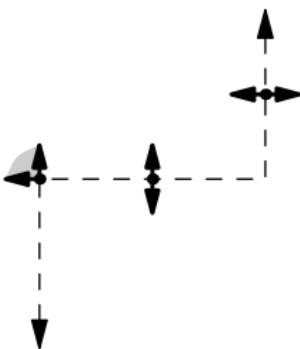
- $K(u) = S(u) - y^\delta$
- $F(y) = \int_{\Omega} |y(x)| dx \rightsquigarrow f(z) = |z|$
- $f^*(z) = \iota_{[-1,1]}(z) = \begin{cases} 0 & |z| \leq 1 \\ \infty & |z| > 1 \end{cases}$
- $\partial f^*(z) = \begin{cases} [0, \infty)z & |z| = 1 \\ \{0\} & |z| < 1 \\ \emptyset & \text{otherwise} \end{cases}$

Examples: L¹ fitting (conjugate)



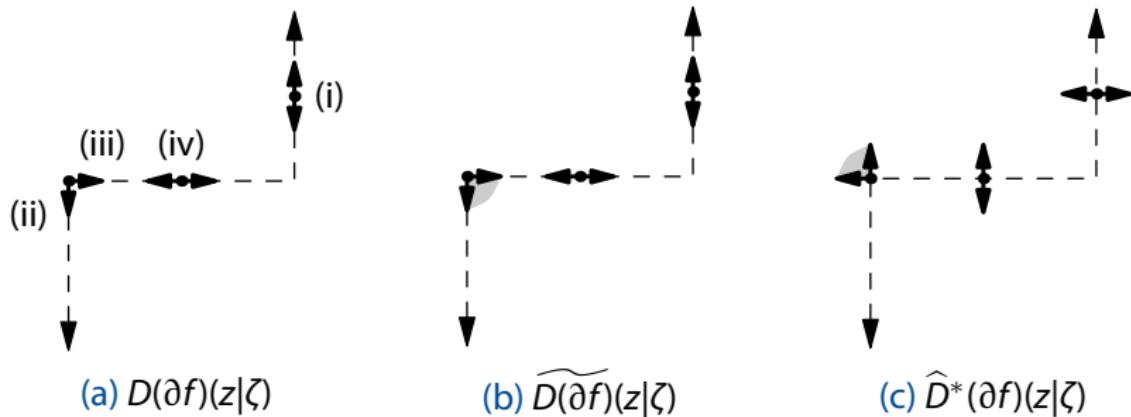
$$D(\partial f)(z|\zeta)(\Delta z) = \begin{cases} \mathbb{R} & |z| = 1, \zeta \in (0, \infty)z, \Delta z = 0 \\ [0, \infty)z & |z| = 1, \zeta = 0, \Delta z = 0 \\ \{0\} & |z| = 1, \zeta = 0, z\Delta z < 0 \\ \{0\} & |z| < 1, \zeta = 0 \\ \emptyset & \text{otherwise} \end{cases}$$

Examples: L¹ fitting (conjugate)

(a) $D(\partial f)(z|\zeta)$ (b) $\widetilde{D(\partial f)}(z|\zeta)$ (c) $\widehat{D}^*(\partial f)(z|\zeta)$

$$\widetilde{D(\partial f)}(z|\zeta)(\Delta z) = \begin{cases} \text{I}\mathbb{R} & |z| = 1, \zeta \in (0, \infty)z, \Delta z = 0 \\ [0, \infty)z & |z| = 1, \zeta = 0, z\Delta z \leq 0 \\ \{0\} & |z| < 1, \zeta = 0 \\ \emptyset & \text{otherwise} \end{cases}$$

Examples: L¹ fitting (conjugate)



$$\widehat{D}^*(\partial f)(z|\zeta)(\Delta\zeta) = \begin{cases} \mathbb{R} & |z| = 1, \zeta \in (0, \infty), z, \Delta\zeta \neq 0 \\ [0, \infty)z & |z| = 1, \zeta = 0, z\Delta\zeta \geq 0 \\ \{0\} & |z| < 1, \zeta = 0 \\ \emptyset & \text{otherwise} \end{cases}$$

Examples: L¹ fitting (conjugate)

$$F : L^2(\Omega) \rightarrow \overline{\mathbb{R}} \quad F(z) = \int_{\Omega} l_{[-1,1]}(z(x)) dx$$

$$\widetilde{D[\partial F]}(z|\zeta)(\Delta z) = \begin{cases} V_{\partial F}(z|\zeta)^{\circ} & \Delta z \in V_{\partial F}(z|\zeta) \text{ and } \zeta \in \partial F(z) \\ \emptyset & \text{otherwise} \end{cases}$$

$$\widehat{D}^*[\partial F](z|\zeta)(\Delta \zeta) = \begin{cases} V_{\partial F}(z|\zeta)^{\circ} & -\Delta \zeta \in V_{\partial F}(z|\zeta) \text{ and } \zeta \in \partial F(z) \\ \emptyset & \text{otherwise} \end{cases}$$

$$V_{\partial F}(z|\zeta) = \{v \in L^2(\Omega) \mid v(x) = 0 \text{ if } |z(x)| = 1\}$$

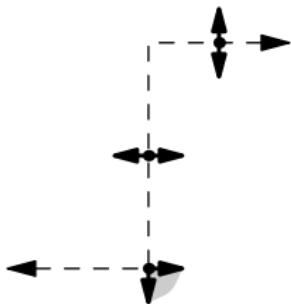
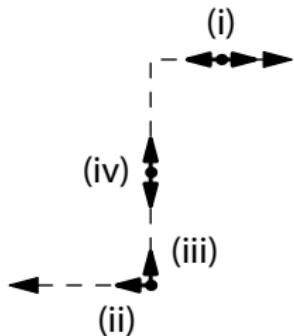
$$V_{\partial F}(z|\zeta)^{\circ} = \{v \in L^2(\Omega) \mid v(x)z(x) \geq 0 \text{ if } \zeta(x) = 0 \text{ and } v(x) = 0 \text{ if } |z(x)| < 1\}$$

$$\min_u \frac{1}{2} \|u\|_{L^2}^2 \quad \text{s. t.} \quad |S(u)(x) - y^\delta(x)| \leq \delta \quad \text{a. e. in } \Omega$$

- $K(u) = S(u) - y^\delta$
- $F(y) = \iota_{\{v \in L^2 : |v(x)| \leq \delta \text{ a.e.}\}}(y) \quad \leadsto \quad f(z) = \iota_{[-\delta, \delta]}(z)$
- $f^*(z) = \delta|z|$

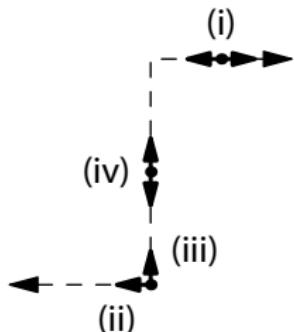
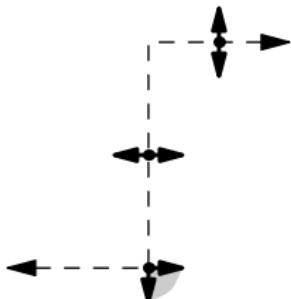
- $\partial f^*(z) = \delta \operatorname{sign}(z) = \begin{cases} \{\delta\} & z > 0 \\ \{-\delta\} & z < 0 \\ [-\delta, \delta] & z = 0 \end{cases}$

Examples: L^∞ fitting (conjugate, $\delta = 1$)



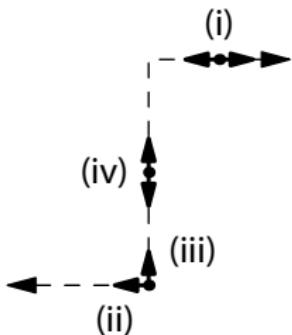
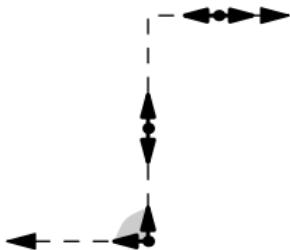
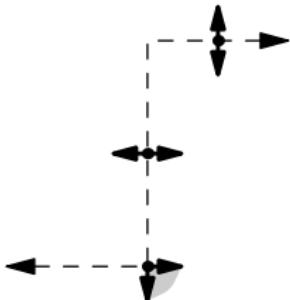
$$D(\partial f)(z|\zeta)(\Delta z) = \begin{cases} \{0\} & z \neq 0, \zeta = \text{sign } z, \\ \{0\}, & z = 0, \Delta z \in (0, \infty)\zeta, \\ (-\infty, 0]\zeta, & z = 0, \Delta z = 0, |\zeta| = 1, \\ \mathbb{R}, & z = 0, \Delta z = 0, |\zeta| < 1, \\ \emptyset, & \text{otherwise,} \end{cases}$$

Examples: L^∞ fitting (conjugate, $\delta = 1$)

(a) $D(\partial f)(z|\zeta)$ (b) $\widetilde{D}(\partial f)(z|\zeta)$ (c) $\widehat{D}^*(\partial f)(z|\zeta)$

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Examples: L^∞ fitting (conjugate)

$$F : L^2(\Omega) \rightarrow \overline{\mathbb{R}} \quad F(v) = \int_{\Omega} \delta |v(x)| dx$$

$$\widetilde{D[\partial F]}(z|\zeta)(\Delta z) = \begin{cases} V_{\partial F}(z|\zeta)^\circ & \Delta z \in V_{\partial F}(z|\zeta), \zeta \in \partial F(z) \\ \emptyset & \text{otherwise} \end{cases}$$

$$\widehat{D}^*[\partial F](z|\zeta)(\Delta \zeta) = \begin{cases} V_{\partial F}(z|\zeta)^\circ & -\Delta \zeta \in V_{\partial F}(z|\zeta), \zeta \in \partial F(z) \\ \emptyset & \text{otherwise} \end{cases}$$

$$V_{\partial F}(z|\zeta) = \{v \in L^2(\Omega) \mid v(x)\zeta(x) \geq 0 \text{ if } z(x) = 0 \text{ and } (\delta - |\zeta(x)|)v(x) = 0\}$$

$$V_{\partial F}(z|\zeta)^\circ = \{v \in L^2(\Omega) \mid v(x)\zeta(x) \leq 0 \text{ if } |\zeta(x)| = \delta \text{ and } z(x)v(x) = 0\}$$

Application to saddle point inclusion

$$0 \in H_{\bar{u}}(\bar{u}, \bar{v}) = \begin{pmatrix} \partial G(\bar{u}) + K'(\bar{u})^* \bar{v} \\ \partial F^*(\bar{v}) - K(\bar{u}) \end{pmatrix}$$

$$DH_{\bar{u}}(q|w)(\Delta q) = \begin{pmatrix} D[\partial G](u|\xi - K'(\bar{u})^* v)(\Delta u) + K'(\bar{u})^* \Delta v \\ D[\partial F^*](v|\eta + K'(\bar{u})u + c_{\bar{u}})(\Delta v) - K'(\bar{u})\Delta u \end{pmatrix}$$

$$\widetilde{DH}_{\bar{u}}(q|w)(\Delta q) = \begin{cases} T_q \Delta q + V(q|w)^\circ & \Delta q \in V(q|w) \\ \emptyset & \text{otherwise} \end{cases}$$

- $q = (u, v), \quad w = (\xi, \eta), \quad c_{\bar{u}} = K(\bar{u}) - K'(\bar{u})\bar{u}$
- T_q linear Operator (independent of w), $V(q|w)$ cone
- $\widehat{D}^* H_{\bar{u}}(q|w) = [\widetilde{DH}_{\bar{u}}(q|w)]^{*+}$

Mordukhovich criterion

$$\widetilde{DH}_{\bar{u}}(q|w)(\Delta q) = \begin{cases} T_q \Delta q + V(q|w)^{\circ} & \Delta q \in V(q|w) \\ \emptyset & \text{otherwise} \end{cases}$$

Then: **Aubin constant** $L_H \leq c < \infty$ **iff**

$$\sup_{t>0} \inf_{\substack{(\Delta w, z) \in W^t(q|w), \\ \|\Delta w\| > 0}} \frac{\|T_q^* \Delta w - z\|}{\|\Delta w\|} \geq c^{-1} > 0$$

$$W^t(q|w) = \bigcup \left\{ V(q'|w') \times V(q'|w')^{\circ} \mid \begin{array}{l} w' \in H_{\bar{u}}(q'), \\ \|q' - q\| < t, \|w' - w\| < t \end{array} \right\}$$

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Application to PDEs

Primal-dual optimality conditions

$$\begin{cases} S(\bar{u}) - y^\delta \in \partial F^*(\bar{v}) \\ -S'(\bar{u})^* \bar{v} = \bar{u} \end{cases}$$

Metric regularity **around** (\bar{u}, \bar{v}) if either

- 1 $\sup_{t>0} \inf \left\{ \frac{\|S'(\bar{u})S'(\bar{u})^* z - v\|}{\|z\|} \mid (z, v) \in V_{\partial F^*}^t(\bar{v}|y^\delta - S(\bar{u})), z \neq 0 \right\} > 0$
- 2 Moreau–Yosida regularization: $F^* \mapsto F_\gamma^* := F^* + \frac{\gamma}{2} \|\cdot\|^2$
- 3 finite-dimensional data: $Y \rightsquigarrow Y_h$

In case 1: $\|S'(\bar{u})^* z\| \geq c \|z\|$ for $z \in V_{\partial F^*}^t(\bar{v}|y^\delta - S(\bar{u}))$ necessary!

$$\min_u \frac{1}{a} \|S(u) - y^\delta\|_{L^1} + \frac{1}{2} \|u\|_{L^2}^2$$

- $F(y) = \int_{\Omega} a^{-1} |y(x)| dx \quad \rightsquigarrow \quad f^*(z) = \delta_{[-a^{-1}, a^{-1}]}(z)$
- $S : U \subset L^2(\Omega) \rightarrow L^2(\Omega), \quad S(u) =: y$ satisfies

$$\begin{cases} -\Delta y + uy = f \\ \partial_\nu y = 0 \end{cases}$$

Here: $z \in V_{\partial F^*}^t(v|\eta)$ if

$$z(x) \in \begin{cases} \{0\} & |v'(x)| = a^{-1} \text{ and } \eta'(x) \neq 0 \\ -\operatorname{sign} v'(x)[0, \infty) & |v'(x)| = a^{-1} \text{ and } \eta'(x) = 0 \\ \mathbb{R} & |v'(x)| < a^{-1} \text{ and } \eta'(x) = 0 \end{cases}$$

for some $\|v' - \bar{v}\| \leq t$, $\|\eta' - \bar{\eta}\| \leq t$

- S compact operator: $\|S'(\bar{u})^*z\| \geq c\|z\|$ only holds for $z = 0$
- $\bar{\eta} = S(\bar{u}) - y^\delta$, $a\bar{v} \in \operatorname{sign} \bar{\eta}$
- \rightsquigarrow in general **not satisfied!**

L¹ fitting: algorithm

$$\left\{ \begin{array}{l} z^{k+1} = S'(u^k)^* v^k \\ u^{k+1} = \frac{1}{1 + \tau_k} (u^k - \tau_k z^{k+1}) \\ \omega_k = 1 / \sqrt{1 + 2c\tau_k} \quad \tau_{k+1} = \omega_k \tau_k \quad \sigma_{k+1} = \sigma_k / \omega_k \\ \bar{u}^{k+1} = u^{k+1} + \omega_k (u^{k+1} - u^k) \\ v^{k+1} = \text{proj}_{[-a^{-1}, a^{-1}]} \left(\frac{1}{1 + \sigma_{k+1}\gamma} (v^k + \sigma_{k+1} (S(\bar{u}^{k+1}) - y^\delta)) \right) \end{array} \right.$$

- $S'(u^k)^* v^k$ solution of adjoint equation
- proj_C pointwise projection on convex set $C \subset \mathbb{R}$
- Moreau–Yosida parameter $\gamma \geq 0$
- local convergence if $\gamma > 0$ or finite-dimensional

$$\min_u \frac{1}{2} \|u\|_{L^2}^2 \quad \text{s. t.} \quad |S(u)(x) - y^\delta(x)| \leq \delta \quad \text{a. e. in } \Omega$$

- $F(y) = \delta_{\{|y(x)| \leq \delta\}}(y) \quad \rightsquigarrow \quad f^*(z) = \delta|z|$
- $S : U \subset L^2(\Omega) \rightarrow L^2(\Omega)$, $S(u) =: y$ satisfies
 - $\begin{cases} -\Delta y + uy = f \\ \partial_\nu y = 0 \end{cases}$
 - for $t = 0$: $z(x) = 0$ if $|S(\bar{u})(x) - y^\delta(x)| < \delta \rightsquigarrow$ estimate unlikely

L^∞ fitting: algorithm

$$\left\{ \begin{array}{l} z^{k+1} = S'(u^k)^* v^k \\ u^{k+1} = \frac{1}{1 + \tau_k} (u^k - \tau_k z^{k+1}) \\ \omega_k = 1 / \sqrt{1 + 2c\tau_k} \quad \tau_{k+1} = \omega_k \tau_k \quad \sigma_{k+1} = \sigma_k / \omega_k \\ \bar{u}^{k+1} = u^{k+1} + \omega_k (u^{k+1} - u^k) \\ \bar{v}^{k+1} = v^k + \sigma_{k+1} (S(\bar{u}^{k+1}) - y^\delta) \\ v^{k+1} = \frac{1}{1 + \sigma_{k+1}\gamma} (|\bar{v}^{k+1}| - \delta\sigma)^+ \operatorname{sign}(\bar{v}^{k+1}) \end{array} \right.$$

- local convergence if $\gamma > 0$ or finite-dimensional

1 Overview

2 Algorithm

3 Set-valued analysis

- Metric regularity
- Pointwise subderivatives
- Stability of saddle points

4 Application to parameter identification

- L^1 fitting
- L^∞ fitting

5 Numerical examples

- $\Omega = [-1, 1]$, FE ($P_1 - P_0$) discretization of (y, u)

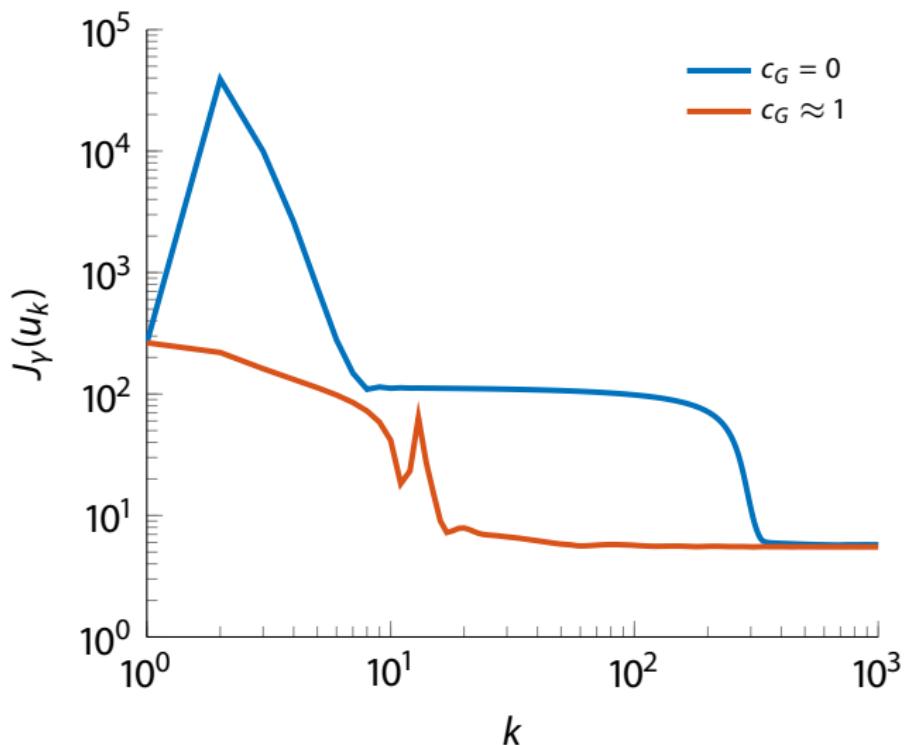
- random impulsive noise:

$$y^\delta(x) = \begin{cases} y^\dagger(x) + \|y^\dagger\|_\infty \xi(x) & \text{with probability 0.3} \\ y^\dagger(x) & \text{else} \end{cases}$$

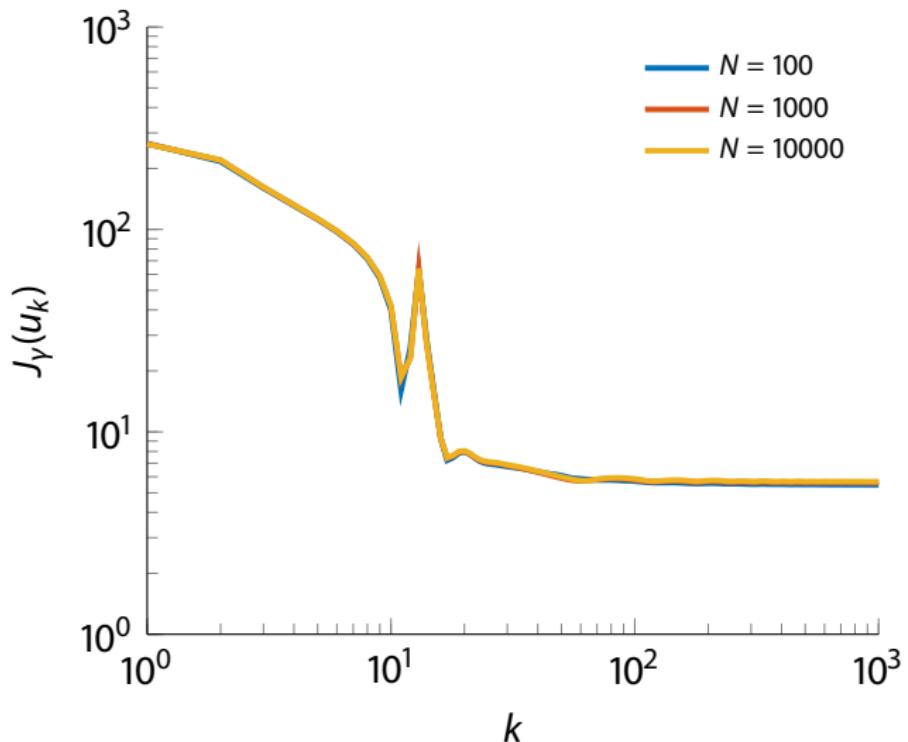
$$y^\dagger = S(u^\dagger), \quad \xi(x) \in \mathcal{N}(0, 0.1), \quad \rightsquigarrow \alpha = 10^{-2}$$

- $\sigma_0 = \tilde{L}^{-1}, \tau_0 = 0.99\tilde{L}^{-1}, \quad \tilde{L} = \|S(u^0)\|/\|u^0\|$
- $\gamma = 10^{-12}, \quad u^0 \equiv 1, v^0 = 0 \quad (\text{no warmstart!})$
- compare $c \in \{0, 1 - 10^{-16}\}, \quad N \in \{100, 1000, 10000\}$

L^1 fitting: acceleration (same data)

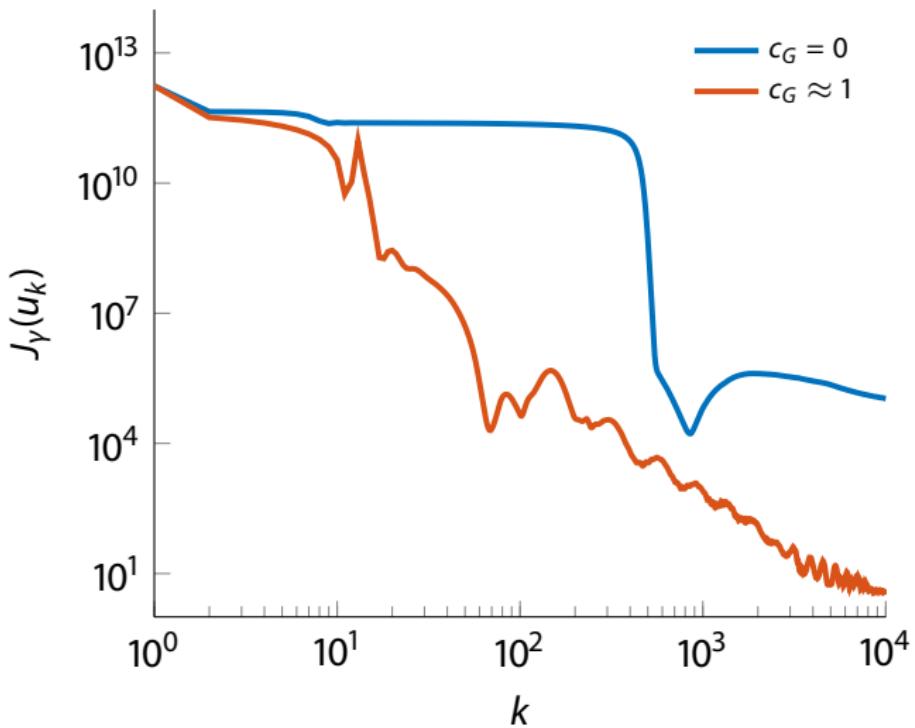


L^1 fitting: discretization (avg. of 10)

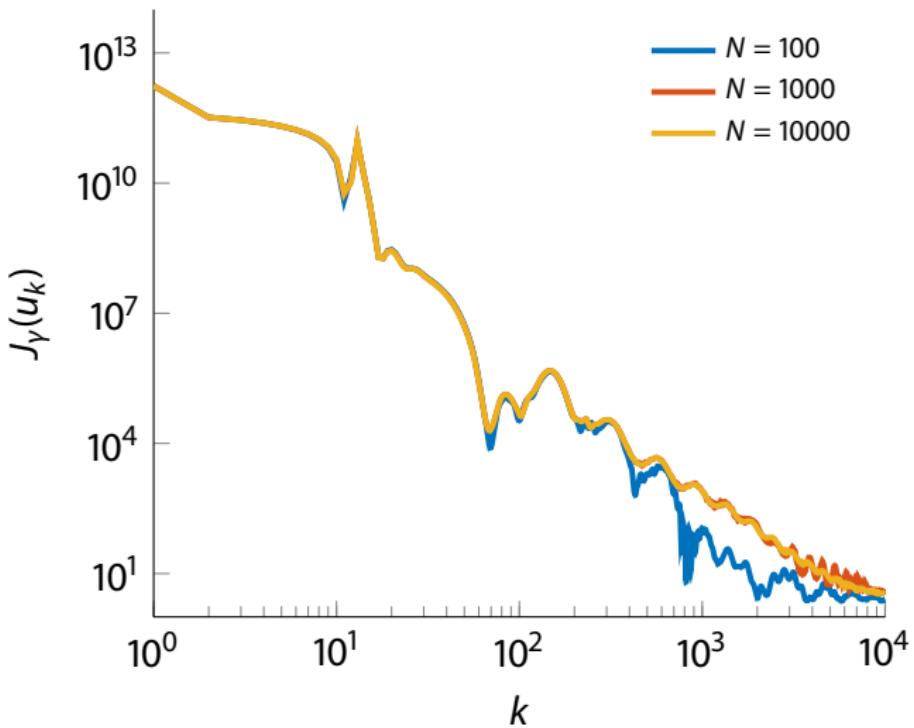


- $\Omega = [-1, 1]$, FE ($P_1 - P_0$) discretization of (y, u)
- quantization noise:
round y^\dagger to $n_b = 11$ equidistant values
- $\gamma = 10^{-12}$, $\sigma_0 = \tilde{L}^{-1}$, $\tau_0 = 0.99\tilde{L}^{-1}$, $\tilde{L} = \|S(u^0)\|/\|u^0\|$
- $u^0 \equiv 1, v^0 = 0$ (no warmstart!)
- compare $c \in \{0, 1 - 10^{-16}\}$, $N \in \{100, 1000, 10000\}$

L^∞ fitting: acceleration (same data)



L^∞ fitting: discretization (same data)



Conclusion

Primal-dual extragradient methods in function space:

- can be accelerated
- analyzed using set-valued analysis in function space
- requires Moreau–Yosida regularization
- \rightsquigarrow no norm gap, continuation needed; mesh-independence

Outlook:

- full acceleration
- partial stability (w.r.t. primal variable only)
- other PDE-constrained optimization problems

Preprints/Code:

http://www.uni-due.de/mathematik/agclason/clason_pub.php